





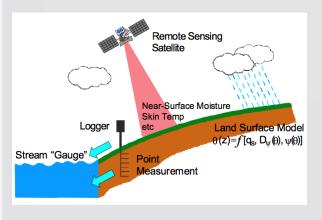
ECMWF/ H-SAF and HEPEX Workshops on coupled hydrology Reading, 3-6 November 2014

Assimilation of satellite soil moisture data in a distributed hydrological model: impact on the hydrological cycle in some Italian basins

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International Centre on Environmental Monitoring



Data Assimilation

Data assimilation is used operationally in oceanography and meteorology, but in hydrology it is only recently that international research activities have been

deployed.



(some) Open questions in DA

- 1. Which is the best DA techniques?
- 2. How can satellite data be used in a framework for DA in hydrological models?
- 3. Which is the proper model configuration?
- 4. Which is the impact of DA on the hydrological cycle?

1. Data Assimilation Technique

Direct insertion (Houser et al. 1998; Walker et al. 2001a)

Statistical correction (Houser et al. 1998)

Successive correction Bergthorsson and Döös (1955)

Analysis correction Lorenc et al. (1991)

Nudging (Stauffer and Seaman 1990)

Optimal interpolation (Lorenc et al. 1991)

Kalman Filters, simple, extended, ensemble (Evensen)

) 2 - ---| --- --- --| 4000)

Particle filter (Kalman, 1960; Evensen 1994, Gordon et al. 1993)

3D & 4D var -> Var. filter

$$J = \frac{1}{2} \left(\mathbf{X}_{0} - \mathbf{X}_{0}^{b} \right)^{T} \Sigma_{0}^{b^{-1}} \left(\mathbf{X}_{0} - \mathbf{X}_{0}^{b} \right) + \frac{1}{2} \sum_{k=1}^{N-1} \left(\mathbf{Z}_{k} - \hat{\mathbf{Z}}_{k} \right)^{T} \mathbf{R}_{k}^{-1} \left(\mathbf{Z}_{k} - \hat{\mathbf{Z}}_{k} \right),$$

SEQUENTIAL

FILTERS

 $x_{\nu}^{i+} = x_{\nu}^{i-} + G_{\nu}(y_{\nu}^{i} - x_{\nu}^{i-})$

Houser, De Lannoy and Walker (2012). Hydrologic Data Assimilation, Approaches to Managing Disaster - Assessing Hazards, Emergencies and Disaster Impacts, http://www.intechopen.com/books/approaches-to-managing-disaster-assessing-hazards-emergencies-and- disaster-impacts/land-surface-data-assimilation

1. Data Assimilation Technique

The assimilation technique is particularly important in some cases

Samuel, J. et al. 2014 (JoH)

"[...] In the streamflow assimilation, soil moisture states were markedly Distorted [...]"

"General filtering approaches in hydrologic data assimilation, such as the ensemble Kalman filter (EnKF), are based on the assumption that uncertainty of the current background prediction can be reduced by correcting errors in the state variables at the same time step. However, this assumption may not be valid when assimilating stream discharge into hydrological models to correct soil moisture storage due to the time lag between the soil moisture and the discharge ..."

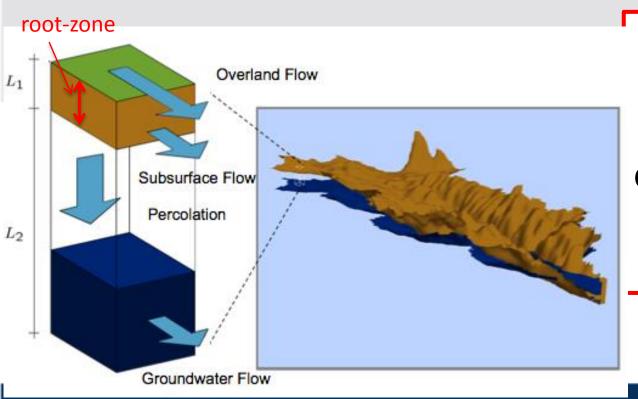
Li et al. 2013 (WRR)

The EnKF is designed to update model-forecasted state predictions at the same time an observation is acquired. No attempt is made to reanalyze previous model predictions in response to a particular observation. In contrast, the **Ensemble Kalman Smoother (EnKS)** can be used to update all model states predictions within a fixed lag of past time (Dunne and Entekhabi, 2005).

Crow and Ryu, 2009 (HESS)

Osservare per prevedere, prevedere per prevenire

Satellite data give information of soil moisture for the first centimetres of the soil. This may not match the layer depth simulated by the model (different climatology and considerable bias)



Usually satellite soil moisture data CANNOT be directly used within hydrological models

- A. "Transform" the sat. SSM in the "same" modelled variable
 - → Filtering
- B. Adjusting the observation to match the climatology of the model
 - → Bias handling

Filtering: A filtering technique is applied to obtain information of a deeper soil layer

$$SWI(t) = \frac{\sum_{i} SSM_{t_i} \exp\left(-\frac{t - t_i}{T}\right)}{\sum_{i} \exp\left(-\frac{t - t_i}{T}\right)}$$

Wagner et al., 1999, Stroud, 1999 Albergel et al., 2008

Dec 99

Mar 00

Jun 99

Sep 99

SWI: Soil Water Index

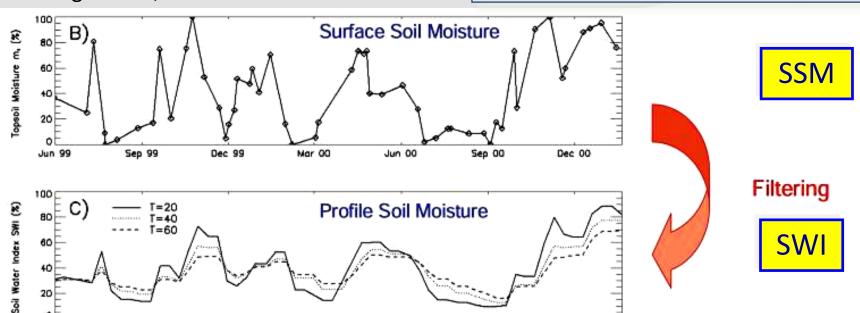
t: time

SSM_{ti}: relative Surface Soil

Moisture [0,1]

ti: acquisition time of SSM_{ti}

T: characteristic time length



Jun 00

Sep 00

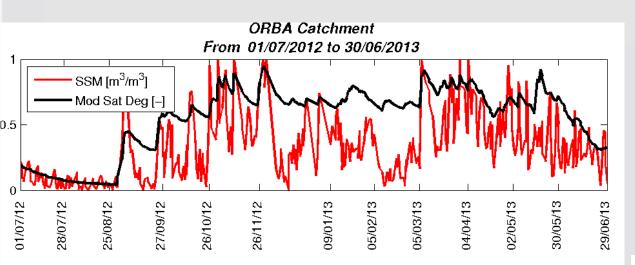
Dec 00

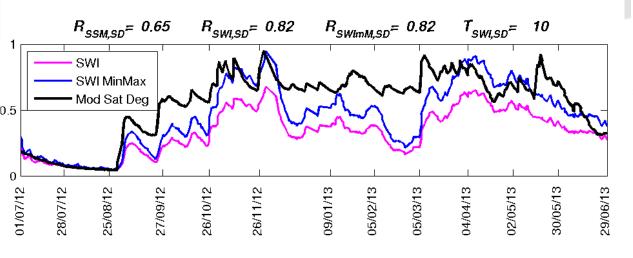
prevenire

Bias Handling: Several potential strategies exist and have been applied in hydrologic data assimilation

Variance matching (VM) (Brocca et al. 2010, 2012, Matgen et al. 2011, Chen et al. 2011)
Linear regression techniques (LR)
Cumulative distribution function matching (CDF) (Reichle and Koster 2004)
Anomaly based cumulative distribution (aCDF)
Triple collocation analysis-based approach (TCA) (Stoffelen 1998, Yilamz and Crow 2013)

There many methods their optimality (for real cases) in terms of error analysis in an assimilation framework has not been yet analysed

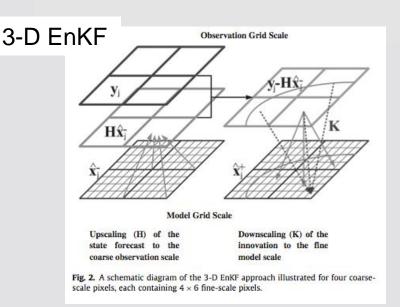




- 1. Filtering -> SWI
- 2. Bias handling

$$SAT^* = \frac{SAT - m(SAT)}{S(SAT)} \times S(SD_{\text{mod}}) + m(SD_{\text{mod}})$$

$$SAT^* = \frac{SAT - \min(SAT)}{\frac{6}{2}\max(SAT) - \min(SAT)} \frac{1}{\frac{6}{2}\max(SAT) - \min(SAT)} \frac{1}{\frac{6}{2}\max(SD_{\text{mod}}) - \min(SD_{\text{mod}})} \frac{1}{\frac{6}{2}\min(SD_{\text{mod}})} \frac{1}{\frac$$



The 1-D EnKF application assimilates a priori partitioned observations at the fine scale model grid cells.

The 3-D EnKF algorithm downscales the coarse observations within the assimilation scheme and uses multiple coarse observation grid cells, as shown in Fig. 2.

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Assimilation and downscaling of satellite observed soil moisture over the Little River Experimental Watershed in Georgia, USA

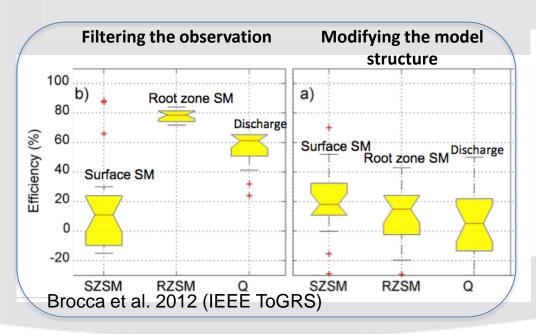
Alok Kumar Sahoo a,*, Gabriëlle J.M. De Lannoy b,c, Rolf H. Reichle c, Paul R. Houser d

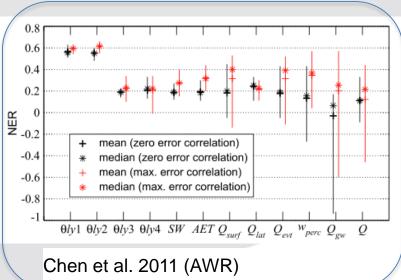
Sahoo et al., 2013

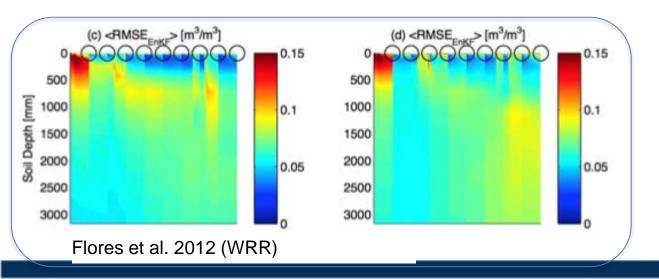
After the assimilation the analysis is bias-corrected to bring the output to the true climatology

Both the EnKF algorithms produce finescale results that are closer to the in situ data than either the model open loop or the satellite observations alone. The 3-D EnKF slightly outperforms the 1-D EnKF and better preserves realistic spatial patterns because of the colored spatial error correlations and the corresponding impact of multiple coarse observation grid cells

3. Proper model configuration







4. Which is the impact of DA on the hydrological cycle?

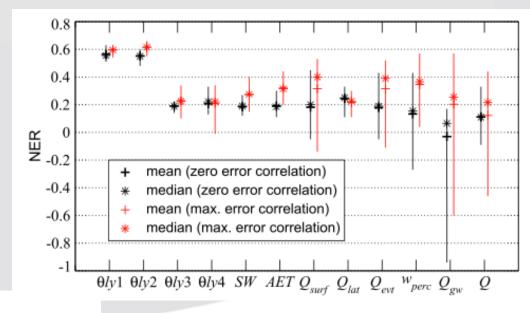
Many of the hydrologic DA studies reported in the literature focused on advancing the theoretical development of DA techniques using **synthetic experiments** (e.g., Andreadis et al., 2007; Kumar et al., 2009; Crow and Ryu, 2009).

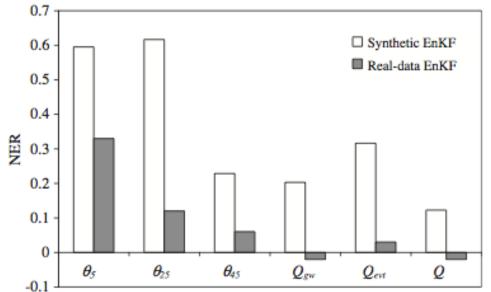
- diagnostic and design purposes such as assessing the impact of improper characterization of model and observation errors (e.g., Crow and Van Loon, 2006; Reichle et al., 2008
- evaluating the potential benefits of future satellite missions (e.g., Matgen et al., 2010)

Only a few formulated DA in an operational setting and attempted to evaluate the performance gain from DA in **real cases** (e.g., as a result of better characterized initial conditions) studies (e.g., Seo et al., 2003, 2009; Thirel et al., 2010; Weerts et al., 2010; DeChant and Moradkhani, 2011, Brocca et al. 2012)

"There is a strong need to estimate soil moisture content through assimilating remotely sensed soil moisture <u>into a long-term, physically based distributed catchment scale hydrologic model</u>. Most of the previous studies that explored DA for runoff simulation used **conceptual rainfall-runoff models** (Aubert et al. 2003; Weerts and El Serafy, 2006; Crow and Ryu, 2009; van Delft et al. 2009) or **lumped models** (Jacobs et al 2003) or for short-term period with real measurements (Pauwels et al. 2001)". **Han et al. 2012**

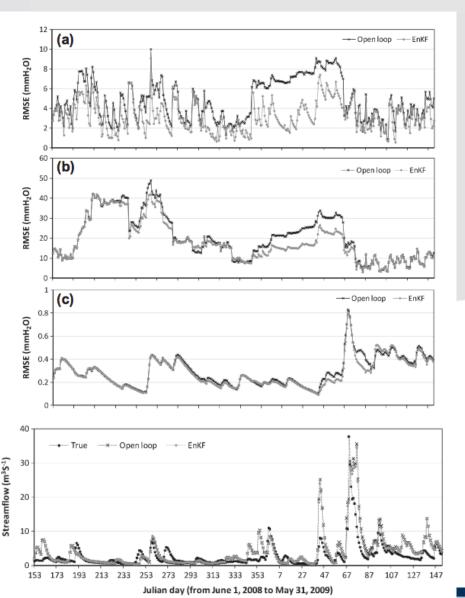
4. Which is the impact of DA on the hydrological cycle?

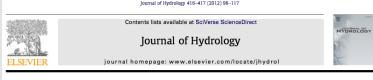




Chen et al. 2011 (AWR)

4. Which is the impact of DA on the hydrological cycle?





Implementation of surface soil moisture data assimilation with watershed scale distributed hydrological model

Eunjin Han a, Venkatesh Merwade a.*, Gary C. Heathman b Han et al., 2012

Synthetic experiments using SWAT model Results of assimilation:

- great impact on soil moisture
- small impact on discharge
- impact on discharge is a function of soil type
- the capability of the SSM assim. for improving streamflow is constrained by the accuracy of precipitation
- Model predicted antecedent soil moisture is less than the true soil moisture (θ_{predicted} < θ_{true} ≈ θ_{EnKF}) and current precipitation is overestimated.
- Model predicted antecedent soil moisture is greater than the true soil moisture (θ_{predicted} > θ_{true} ≈ θ_{EnKF}) and current precipitation is overestimated.
- Model predicted antecedent soil moisture is less than the true soil moisture (θ_{predicted} < θ_{true} ≈ θ_{EnKF}) and current precipitation is underestimated.
- Model predicted antecedent soil moisture is greater than the true soil moisture (θ_{predicted} > θ_{true} ≈ θ_{EnKF}) and current precipitation is underestimated.

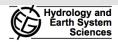
Assimilation of sat. SM in distributed hydrological model

Continuum model

MAIN CHARACTERISTICS:

- Simple but complete description of Hydrological Cycle
 - Schematization of vegetation interception and water table
 - Tank schematization of overland and channel flows
- Mass Balance and Energy Balance completely solved
- Fully Distributed
- River network derived from a DEM
- Spatial-temporal evolution of:
 - Streamflow
 - Evapotranspiration
 - Vegetation retention
 - Land Surface Temperature
 - Soil Moisture
 - Water table
- It can be calibrated using only satellite data (e.g. surface temperature or soil moisture). Model suitable for application in data scarce environments

Hydrol. Earth Syst. Sci., 17, 39–62, 2013 www.hydrol-earth-syst-sci.net/17/39/2013/ doi:10.5194/hess-17-39-2013 © Author(s) 2013. CC Attribution 3.0 License.



Exploiting remote sensing land surface temperature in distributed hydrological modelling: the example of the Continuum model

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Received: 24 May 2012 – Published in Hydrol. Earth Syst. Sci. Discuss.: 14 June 2012 Revised: 12 December 2012 – Accepted: 20 December 2012 – Published: 11 January 2013

Silvestro et al., 2013

The model Fortran code is open and can be requested to: http://www.cimafoundation.org/cima-foundation/continuum/

Hydrol. Earth Syst. Sci. Discuss., 11, 6215–6271, 2014 www.hydrol-earth-syst-sci-discuss.net/11/6215/2014/ doi:10.5194/nessd-11-6215-2014 @ Authorfs) 2014. CC Attribution 3.0 License.



This discussion paper is/has been under review for the journal Hydrology and Earth System Sciences (HESS). Please refer to the corresponding final paper in HESS if available.

Uncertainty reduction and parameters estimation of a distributed hydrological model with ground and remote sensing data

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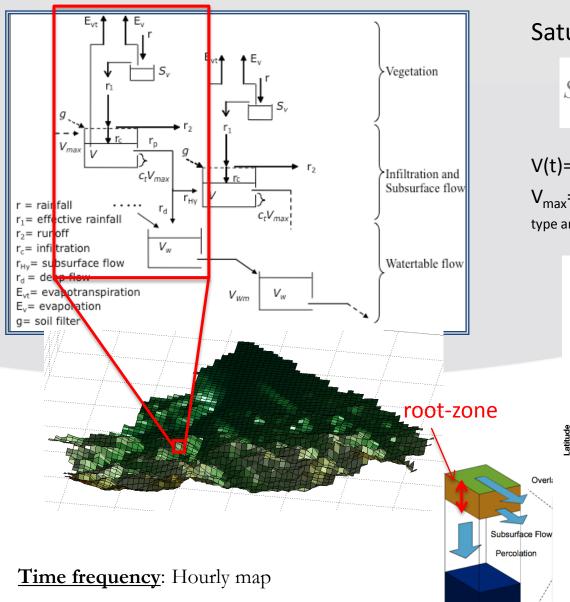
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Silvestro et al., 2014

Osservare per prevedere, prevedere per prevenire

Continuum



Resolution: 100 m

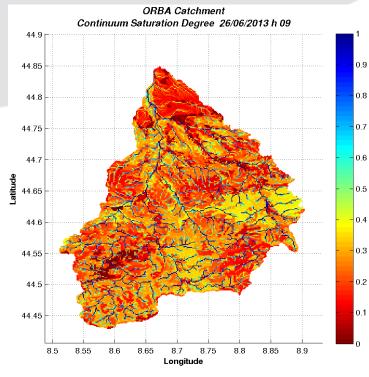
Saturation Degree of root zone

$$SD = \frac{V(t)}{V_{\text{max}}}$$

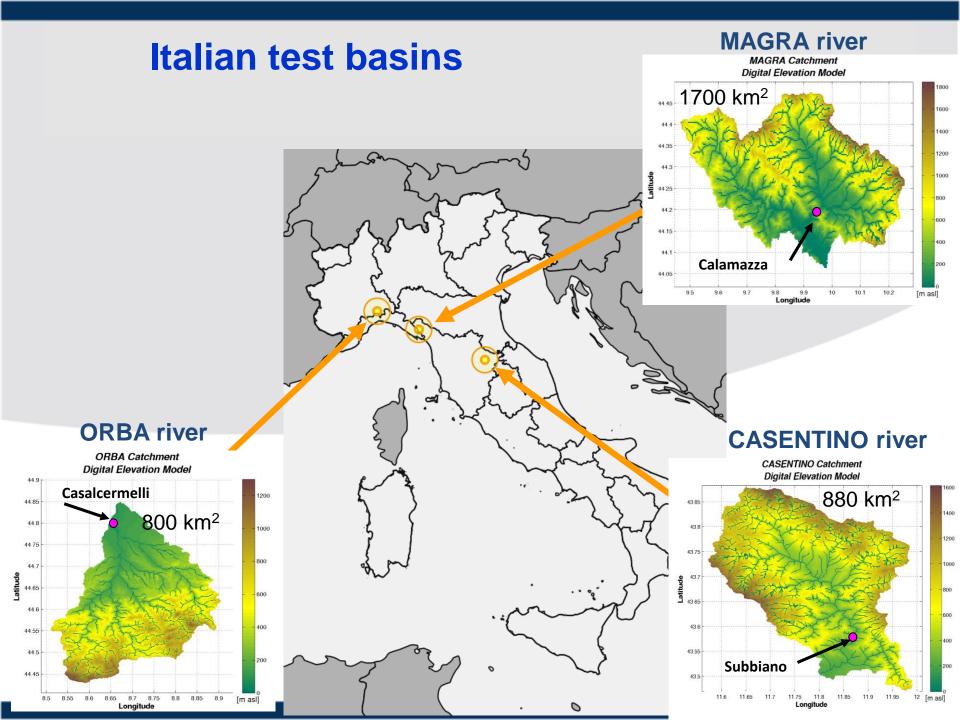
0 £ *SD* £ 1

V(t)= <u>Actual water volume</u>

V_{max} = <u>Max soil retention capacity</u> (related to soil type and land use through the CN)



Osservare per prevedere, prevedere per prevenire



H-SAF Soil Moisture products

• SM-OBS-1 (H07)

Large-scale surface soil moisture (SSM) [-]

Time frequency: 2 maps per day, 1-2 days revisit time

Spatial coverage: Strips of 1000 km swath covering the whole globe

Resolution: 25 km

• SM-OBS-2 (H08)

Small-scale surface soil moisture (SSM) [-]

Time frequency: 2 maps per day, 1-2 days revisit time

Spatial coverage: Strips of 1000 km swath crossing the H-SAF area

Resolution: 1 km

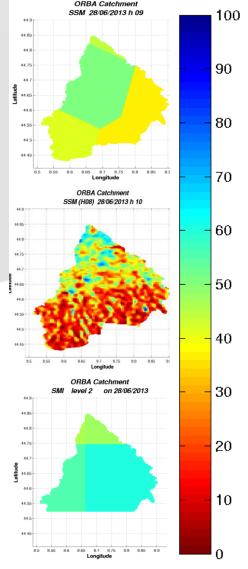
• SM-DAS-2 (H14)

Profile Soil Moisture Index (SMI) in the roots region [-]

Time frequency: Daily map (at 00.00)

<u>Spatial coverage</u>: Globe <u>Horizontal resolution</u>: 25 km

Vertical resolution: 4 layers (0-7 cm, **7-28 cm**, 28-100 cm, 100-289 cm)



SMOS soil moisture product

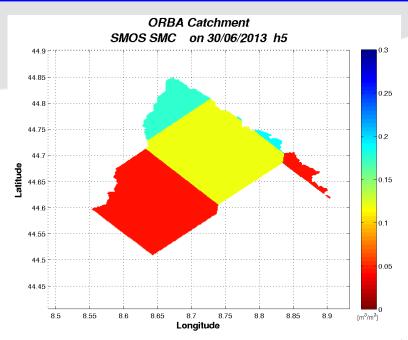
• Level 2 Soil Moisture

volumetric soil moisture content (SMC) [m³/m³]

<u>Time frequency</u>: 2 maps per day, max 3 days revisit time

Spatial coverage: 600 km swath covering the whole globe

Resolution: 43 km in average, 35 km (centre of field of view)



Data Preparation

- Satellite soil moisture data **regridded** to Continuum grid using **nearest neighbour method**
- Assimilation of the mornig passes only
- Discarded H07 data with high quality flag
- Discarded SMOS data with DQX>=0.045 and RFI/200>1

Normalization:

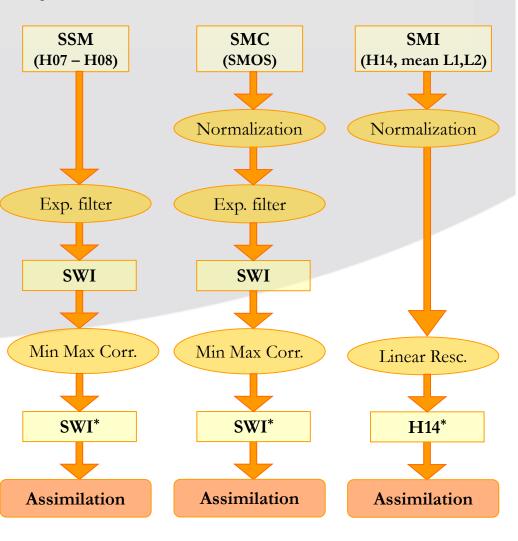
$$SAT_{norm} = \frac{SAT - \min(SAT)}{\max(SAT) - \min(SAT)}$$

Linear Rescaling (H14)

$$SAT^* = \frac{SAT - \mu(SAT)}{\sigma(SAT)} \cdot \sigma(SD_{\text{mod}}) + \mu(SD_{\text{mod}})$$

Min Max correction (H07, H08 and SMOS)

$$SAT^* = \frac{SAT - \min(SAT)}{\left[\max(SAT) - \min(SAT)\right]} \cdot \left[\max(SD_{\text{mod}}) - \min(SD_{\text{mod}})\right] + \min(SD_{\text{mod}})$$



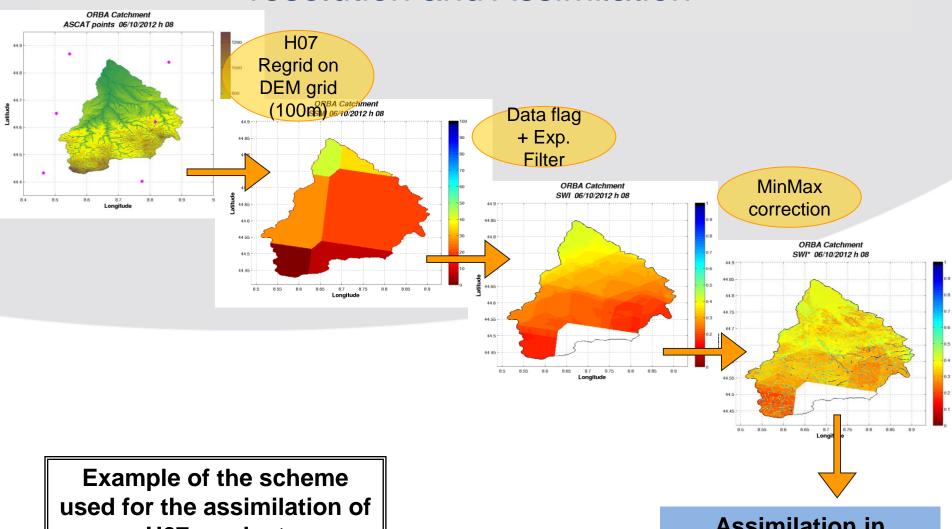
Assimilation in Continuum model

- Assimilation of the four SSM products
- Model scale → Re-grid of Sat. data at model's resolution, filtering and bias handling and Assimilation
- 2. Sat. scale → Re-grid of Model's state at Sat. resolution, filtering and bias handling, Assimilation and then downscaling of assimilated state to model's resolution
- **3. Model scale** → Re-grid of Sat. data at model's resolution and Assimilation

Nudging

} Ensemble

1. Model Scale → Re-grid of Sat. data at model's resolution and Assimilation

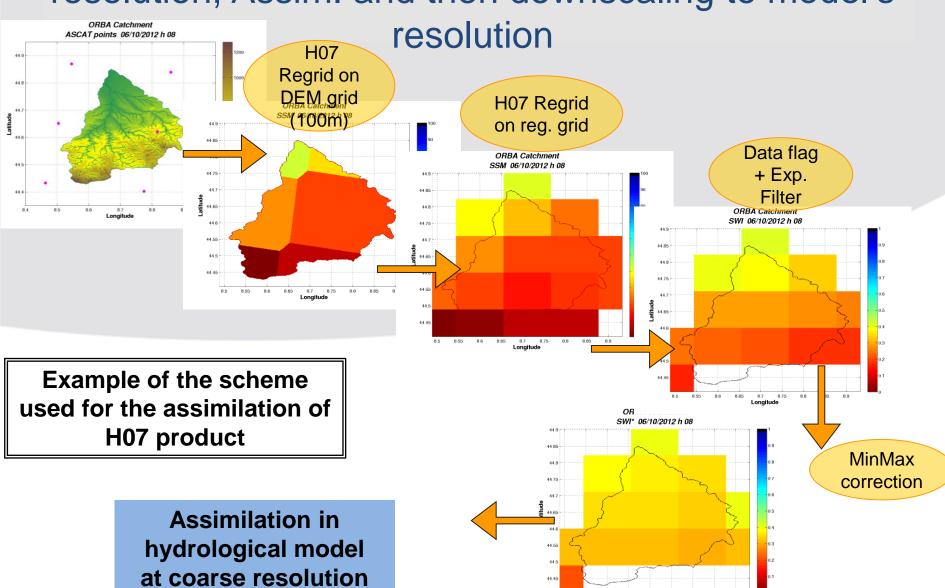


H07 product

Assimilation in hydrological model

Osservare per prevedere, prevedere per prevenire

2. Sat. Scale > Re-grid of Model's state at Sat. resolution, Assim. and then downscaling to model's



re, prevedere per prevenire

Model Scale → Re-grid of Sat. data at model's resolution and Assimilation

$$X_{\text{mod}}^{+}(t) = X_{\text{mod}}^{-}(t) + G \cdot \left[X_{obs}(t) - X_{\text{mod}}^{-}(t) \right]$$

Nudging assimilation scheme

X⁻_{mod} = **Background modeled** Saturation Degree

$$G = Gain$$

$$G = \frac{RMSD_{mod}}{RMSD_{mod} + RMSD_{obs}}$$

No assimilation over urban areas and rivers

RMSD_{mod} = **Root Mean Square Difference** of $X_{mod}^- = 0.092$ (Estimated from a study over modeled soil moisture outputs)

RMSD_{obs}= Root Mean Square Difference of X_{ob}

RMSD_{H14}: 0.22 [-]

(SOURCE: Albergel validation work presented during H-SAF meeting in Budapest 2013)

RMSD_{SWI.HSAF}: 0.12 [-] for H07 and H08

(SOURCE: Brocca et al. 2011)

RMSD_{SWI.SMOS}: 0.24 [-]

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(SOURCE: Albergel et al. 2012)

Nudging assimilation scheme Satellite scale

$$X_{\text{mod}}^{+}(t) = X_{\text{mod}}^{-}(t) + S \times R \times G \cdot \left[X_{obs}(t) - H \times X_{\text{mod}}^{-}(t) \right]$$

X⁺_{mod} = **New** Saturation Degree

X⁻_{mod} = **Background modeled** Saturation Degree

$$G = Gain value$$

$$G = \frac{RMSD_{mod}}{RMSD_{mod} + RMSD_{obs}}$$

$$G = 0.3 \text{ (H14)}$$

$$G = 0.43 \text{ (H07 and H08)}$$

$$G = 0.28 \text{ (SMOS)}$$

H = **Observation operator** (allow to obtain the map at 12.5 km resolution from that at 100 m resolution)

R = **Regrid operator** (allow to obtain the map at 100 m resolution from that at 12.5 km resolution)

S = Spatialization operator (allow to redistribute the correction on the 100 m grid. The correction depends on the ratio between the value of X_{mod}^{-} at each 100 m pixel and the mean soil moisture value at the corresponding 12.5 km pixel)

Bayesian assimilation scheme Model scale

$$SD_{ass}(t) = \langle SD|SD_{obs} \rangle = (P^{-1} \cdot m + R^{-1} \cdot SD_{obs}) \cdot (P^{-1} + R^{-1})^{-1}$$

SD_{ass}= **Posterior mean** of Saturation Degree

$$SD_{mod}(t) = Modeled$$
 Saturation Degree

$$SD_{obs}(t) = Observed Saturation Degree$$
 SMI (H-14)

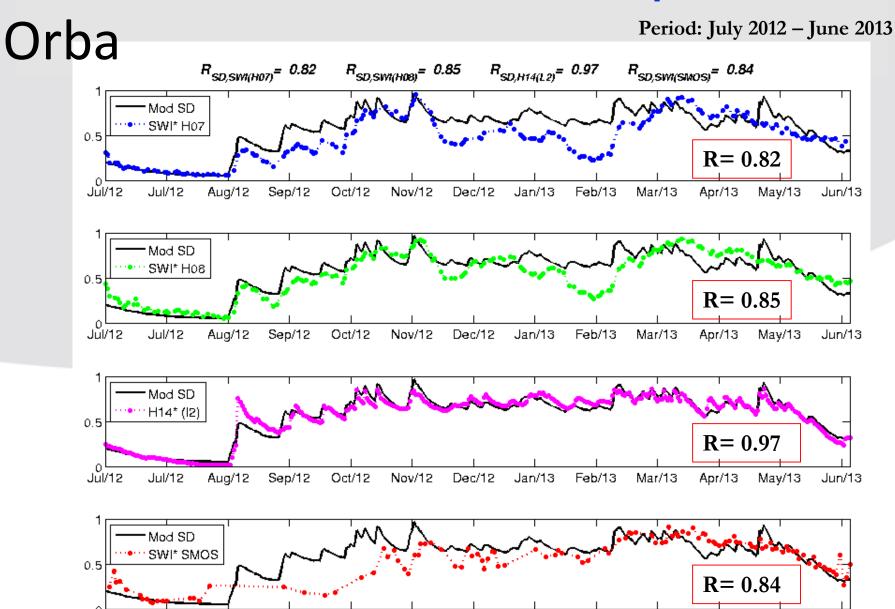
$$\mathbf{R} = \mathbf{Variance of SD_{oss}} = 0.04$$
 (assumption)

$$\mathbf{m} = \mathbf{Expected \ value \ of \ SD_{mod}} \qquad m(t) = \frac{1}{N} \sum_{i=1}^{N} SD_{mod,i}(t)$$

$$N = 20$$
 parameters sets

$$\mathbf{P} = \mathbf{variance of SD}_{mod} \longrightarrow P(t) = \sigma^2 \left[SD_{mod} \right] = \frac{1}{N-1} \sum_{i=1}^{N} \left[\left(SD_{mod,i}(t) - m(t) \right)^2 \right]$$

Soil moisture basin scale comparison



Feb/13

Mar/13

Apr/13

May/13

Jun/13

Jŭl/12

Jul/12

Aug/12

Sep/12

Oct/12

Nov/12

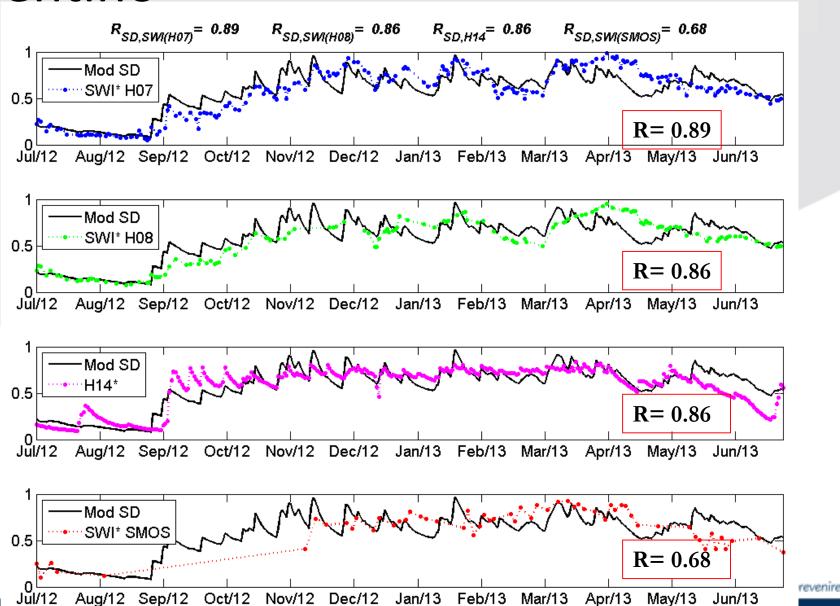
Dec/12

Jan/13

Soil moisture basin scale comparison

Casentino

Period: July 2012 – June 2013

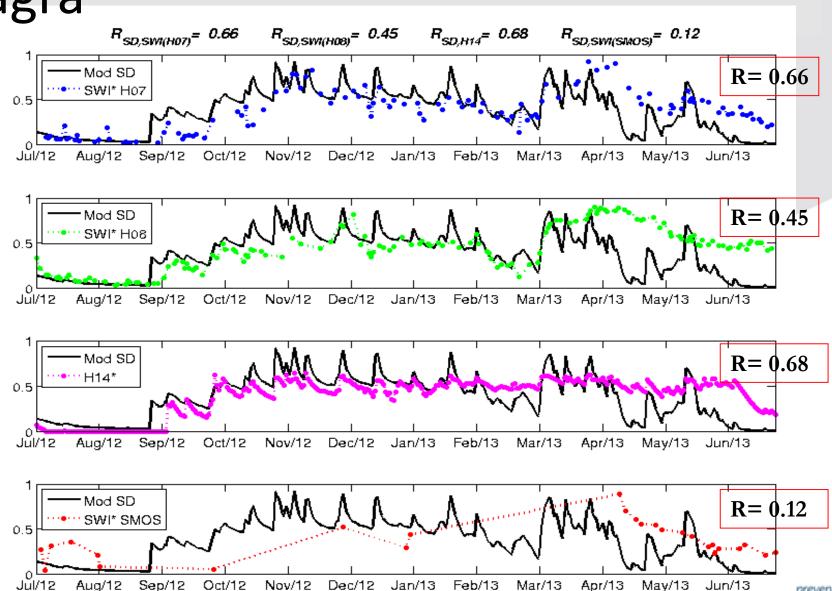


Soil moisture basin scale comparison

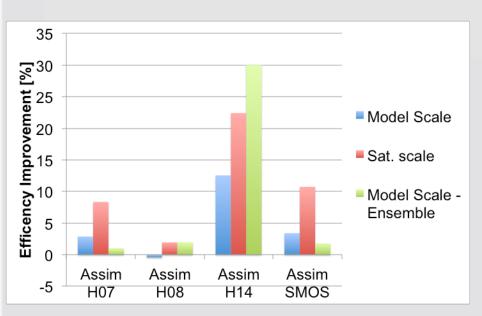


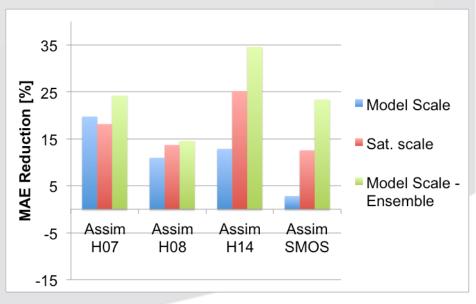
Period: July 2012 – June 2013

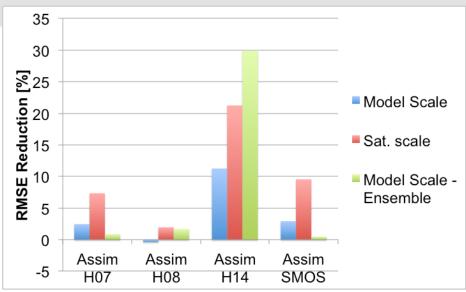
prevenire



Annual results - Orba







$$E_{OL} = 0.63$$

MAE = 17.4 [m³/s]
RMSE = 25.3 [m³/s]

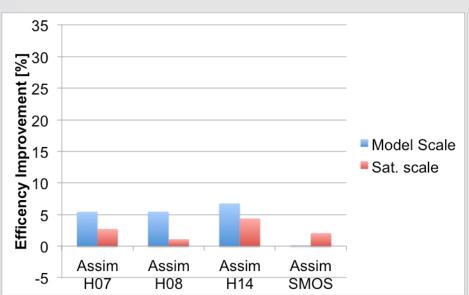
$$MAE = \frac{1}{n} \sum_{i=1}^{n} |Qs_i - Qo_i| \quad RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (Qs_i - Qo_i)^2}$$

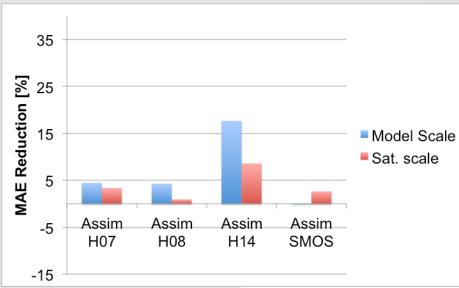
$$E = 1 - \frac{\sum_{i=1}^{n} (Qo_i - Qs_i)^2}{\sum_{i=1}^{n} (Qo_i - \overline{Qo})^2} \quad Q_{si} - \text{simulated values}$$

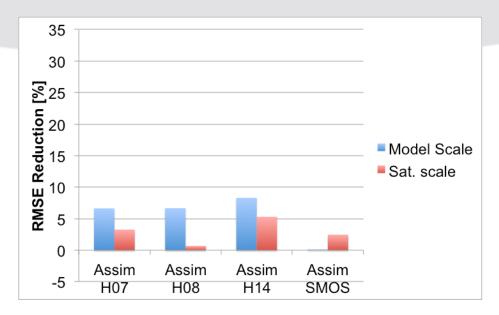
$$Q_{oi} - \text{observed value}$$

$$Q_{oi} - \text{observed per prevedere, prevedere per prevenire}$$

Annual results - Casentino



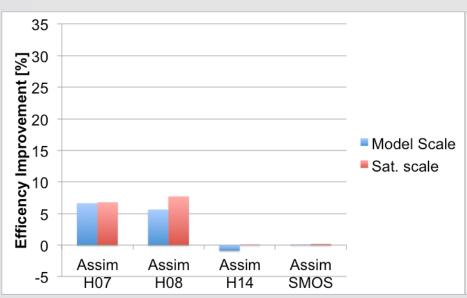


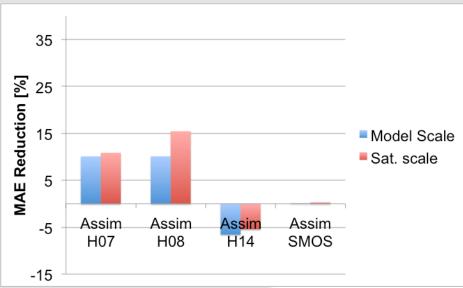


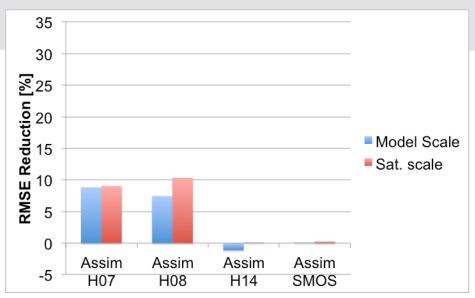
$$E_{OL} = 0.70$$

MAE = 14.3 [m³/s]
RMSE = 21.6 [m³/s]

Annual results - Magra

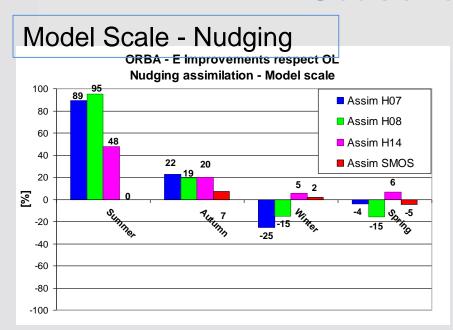


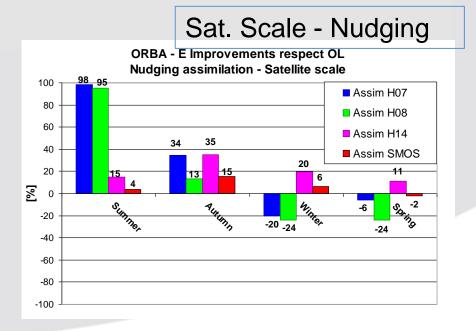


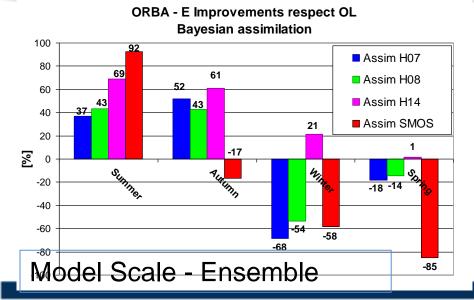


 $E_{OL} = 0.72$ MAE = 28.4 [m³/s] RMSE = 46.7 [m³/s]\

Seasonal results - Orba

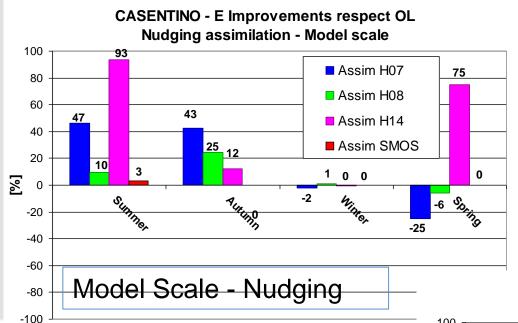






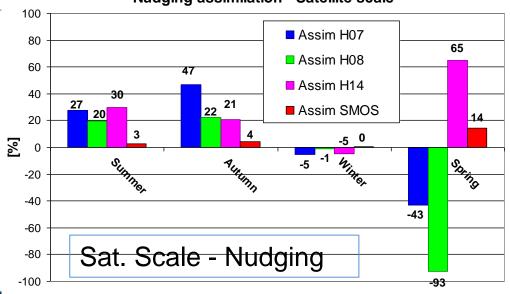
Summer	Autumn	Winter	Spring
-2.64	0.57	0.52	0.78

Seasonal results - Casentino

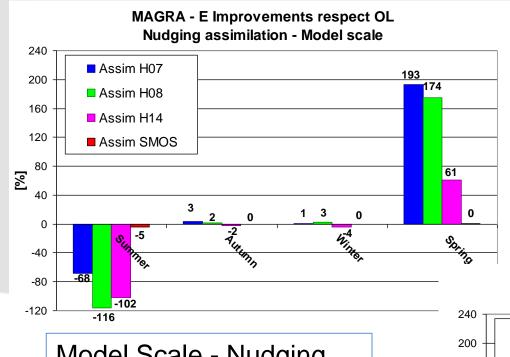


Summer	Autumn	Winter	Spring
-1.50	0.50	0.86	-0.64

CASENTINO - E Improvements respect OL Nudging assimilation - Satellite scale

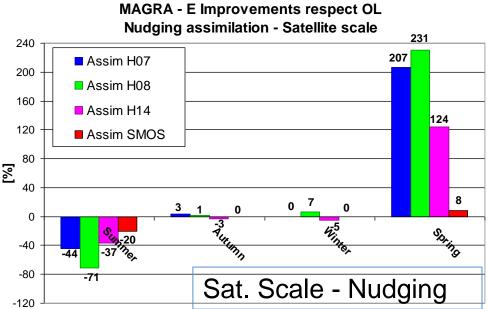


Seasonal results - Magra



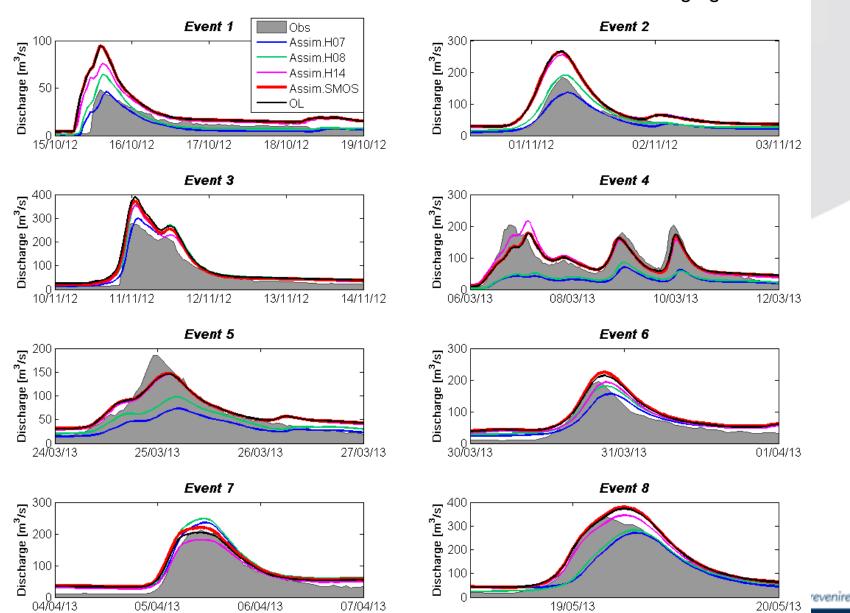
Summer	Autumn	Winter	Spring
-0.18	0.84	0.60	0.24



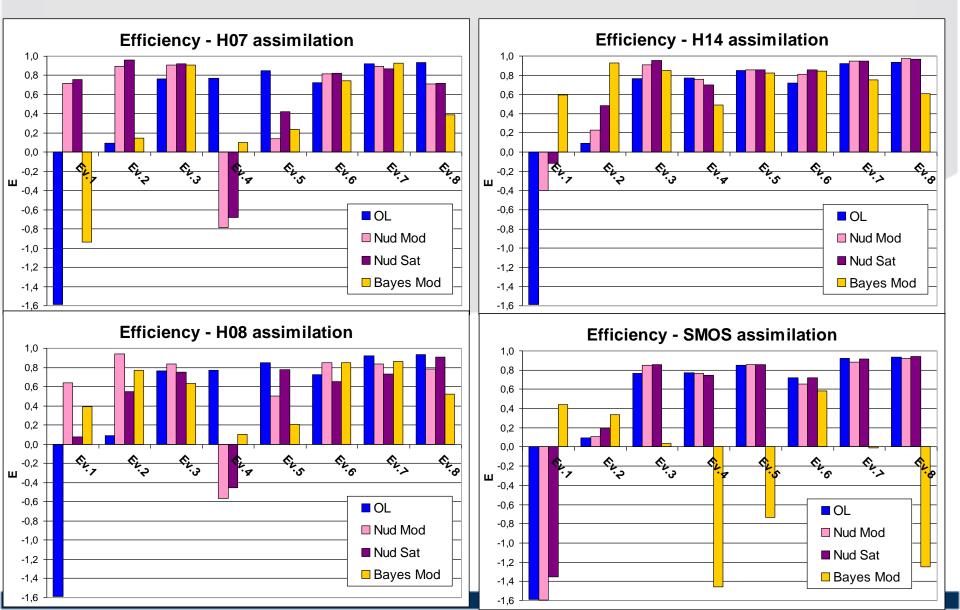


Discharge events results - Orba



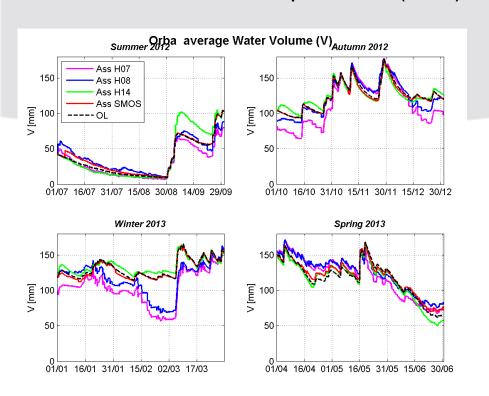


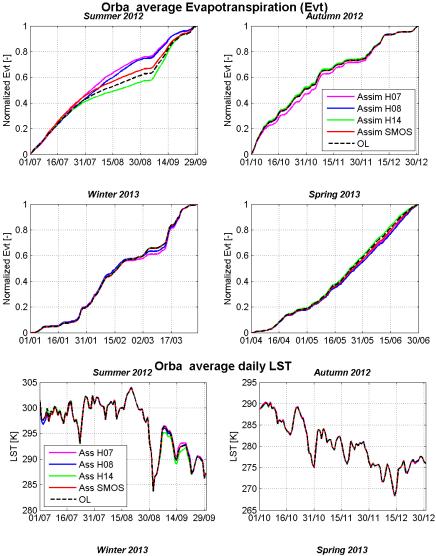
Discharge events results - Orba

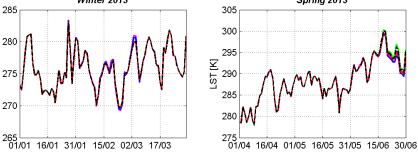


Impact of assimilation on other state variables

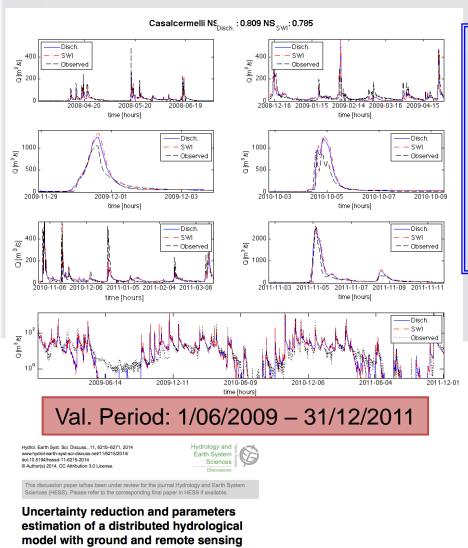
- Water Volume (V)
- Evapotranspiration (Evt)
- Land Surface Temperature (LST)



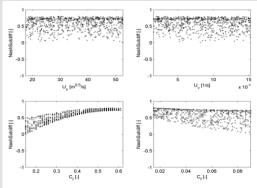




Model calibration with satellite data

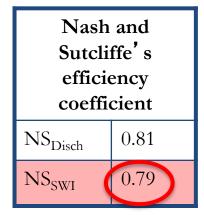


Parameter calibration using SWI(H07)



Satellite data reduced hydrological uncertainty and could be used to calibrate models

Calibration results using only geomorphology (DEM) and **SWI** from H07



data

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Conclusions

Annual evaluation

- Assimilations of Soil moisture products improved the performances
- "Sat. Scale" is better than "Model Scale" for Magra and Orba
- The Ensemble method is promising on Orba

Seasonal evaluation

- Summer and Autumn benefit most from assimilation
- "Sat. Scale" is better than "Model Scale" for Magra and Orba

Events evaluation

- H14 leads to improvement in 90% of cases
- H07 and H08 lead improvement in 50% of cases
- SMOS lead improvement in 35% of cases

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Thank you!

Osservare per prevedere, prevedere per prevenire



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