

# **All-sky observations: errors, biases, representativeness and gaussianity**

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**Thanks to: Bill Bell, Niels Bormann, Anne Foullioux, Jan Haseler, Tony McNally**

# Assimilation of cloud and precipitation affected microwave radiances at ECMWF

- Microwave imagers, e.g. SSM/I, SSMIS, TMI, AMSR-E
  - Radiances are sensitive to humidity, cloud, precipitation, and the ocean surface
- 1D+4D-Var of cloud and precipitation-affected microwave imagers from June 2005
- All-sky assimilation of radiances directly into 4D-Var from March 2009
  - All-sky = clear, cloudy and precipitating conditions together (no cloud-clearing)
  - Cloud and precipitation are part of the 4D-Var minimisation
  - Increased weight of observations for summer 2010 (revised observation errors and quality control)
- All-sky 4D-Var microwave sounder (AMSU-A) radiances in testing

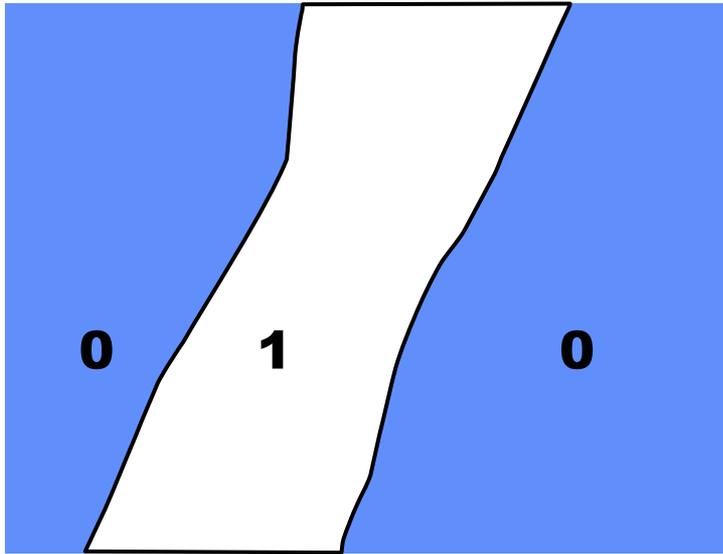
# Introduction

- Adding cloud / precip observations to an operational system needs:
  - Neutral or improved medium-range forecast scores
  - Improved fits to other observations in analysis and first guess
  - (Fast computational speed)
- To achieve this:
  - Appropriate background and observation errors
  - Gaussian error statistics
  - Linearity of models (Philippe Lopez's talk)
  - Quality control
  - Representativeness of observations and model
  - Bias correction

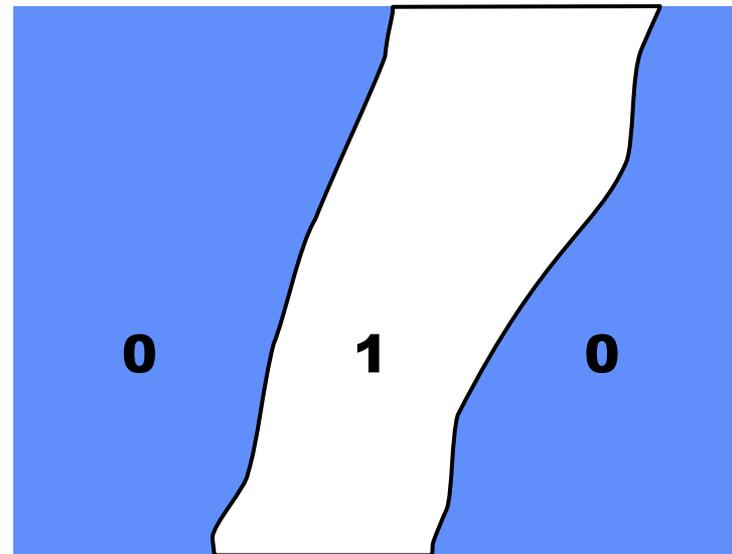
# Observation errors and cloud sampling

# Sampling

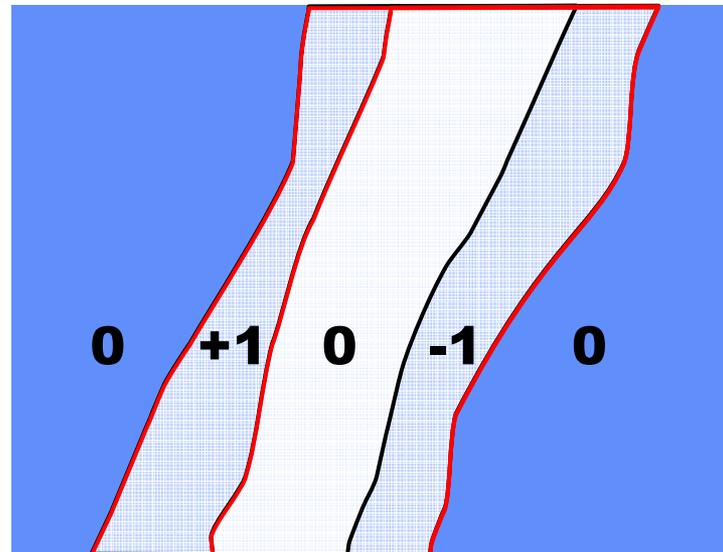
Observation (Obs)



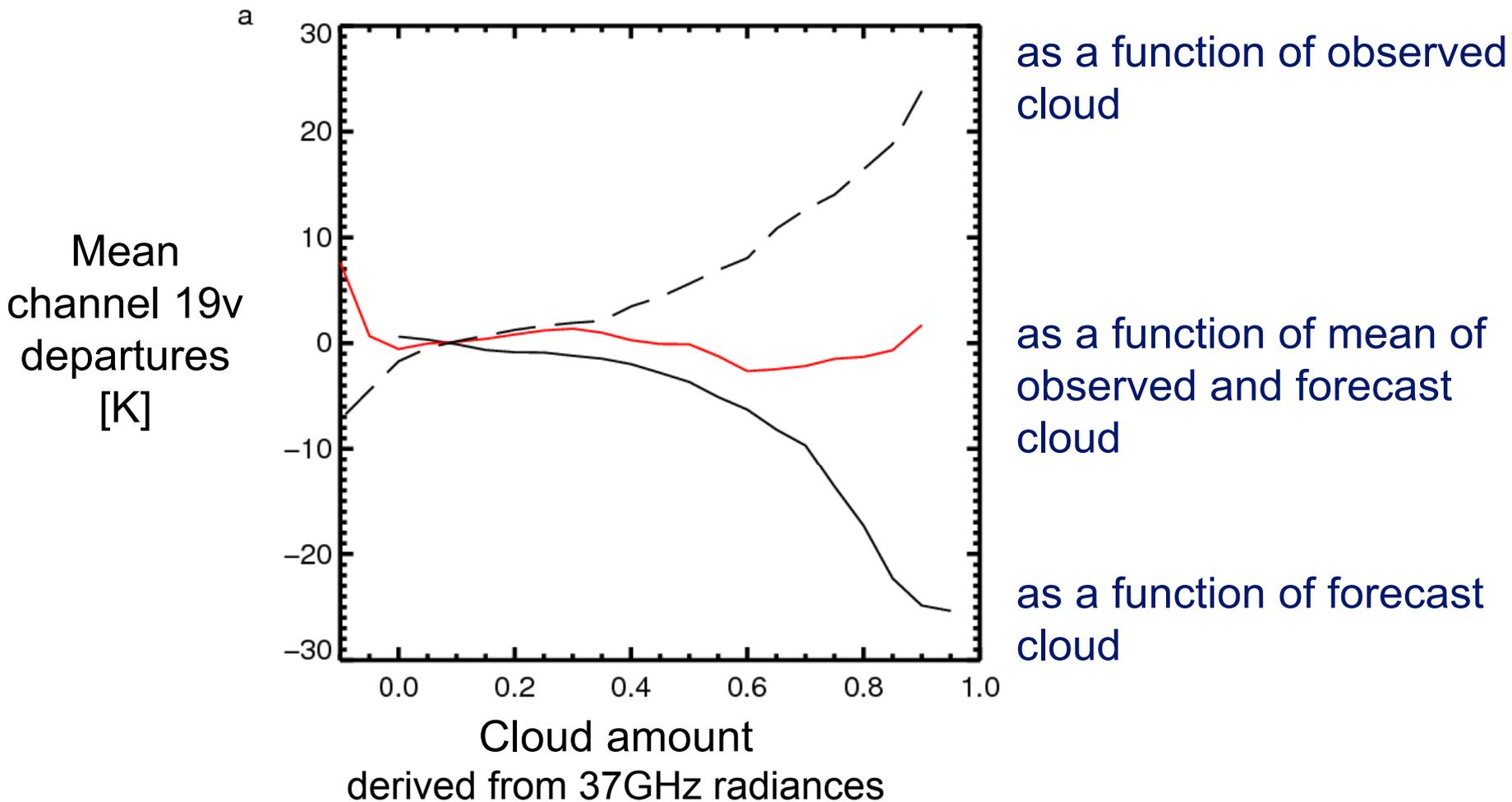
First guess (FG)



Obs - FG



# All-sky SSM/I first guess departures

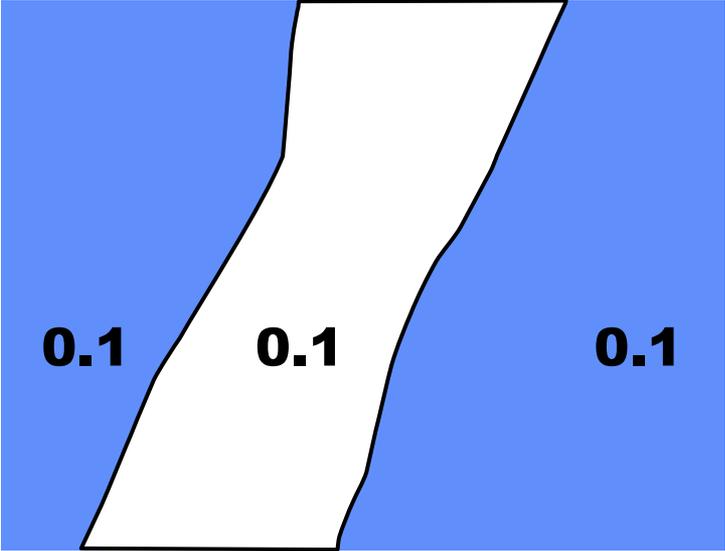


# Symmetry in all-sky assimilation

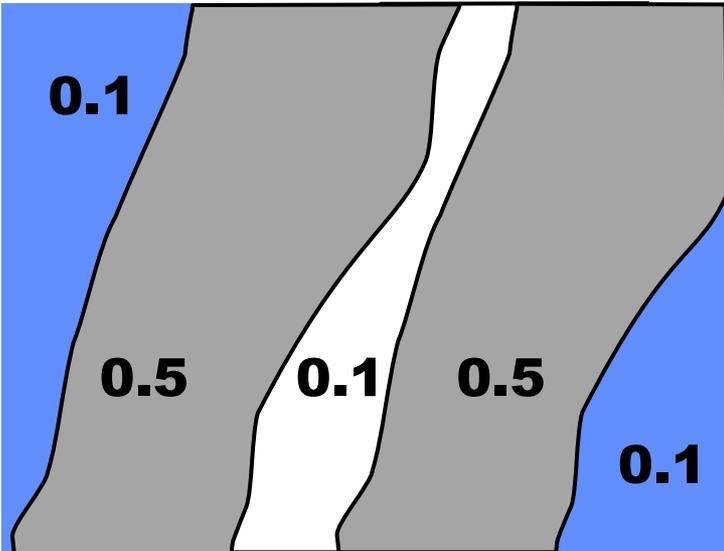
- Any property in a data assimilation system that varies as a function of cloud or rain may lead to “asymmetric” sampling errors
- Bias correction as a function of observed cloud
  - Never enough model cloud when cloud is observed
- Observation error as a function of observed cloud amount
  - Will “lock in” the sampling bias
- ‘Symmetric’ cloud / rain predictors:
  - Mean of observed and first guess cloud
  - Max of observed and first guess cloud
  - Constant error more appropriate for AMSU-A and rain radar

# Error standard deviations – in an ideal world

Observation

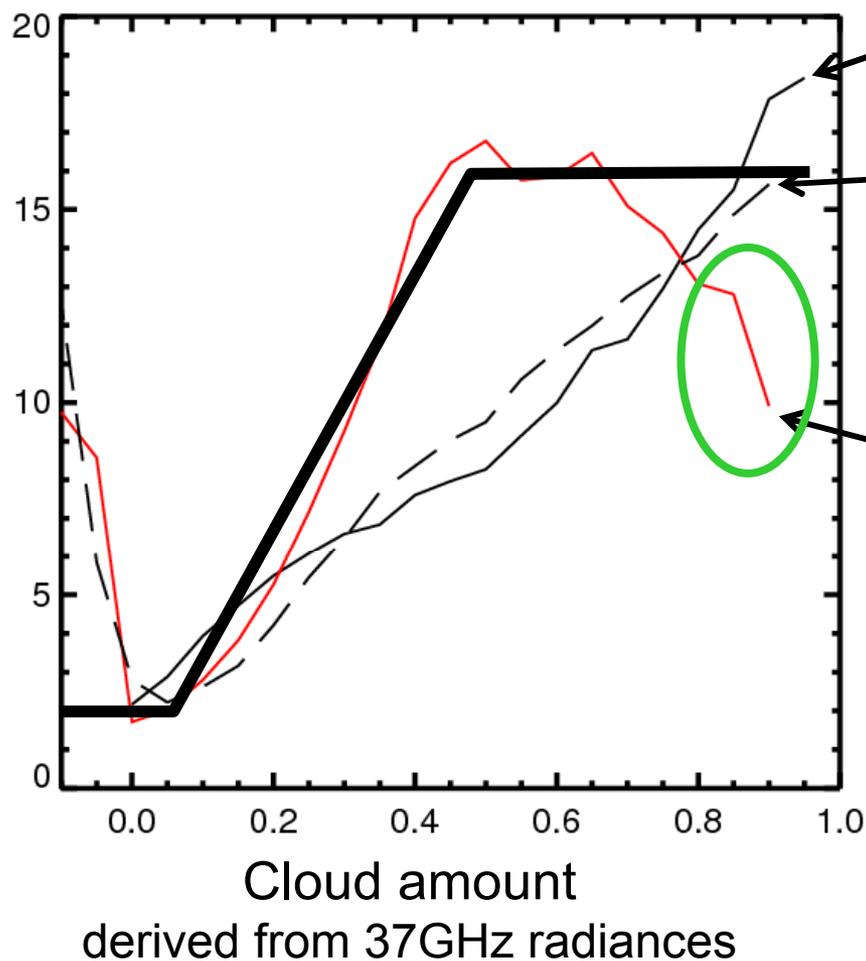


Background



# All-sky SSM/I first guess departures

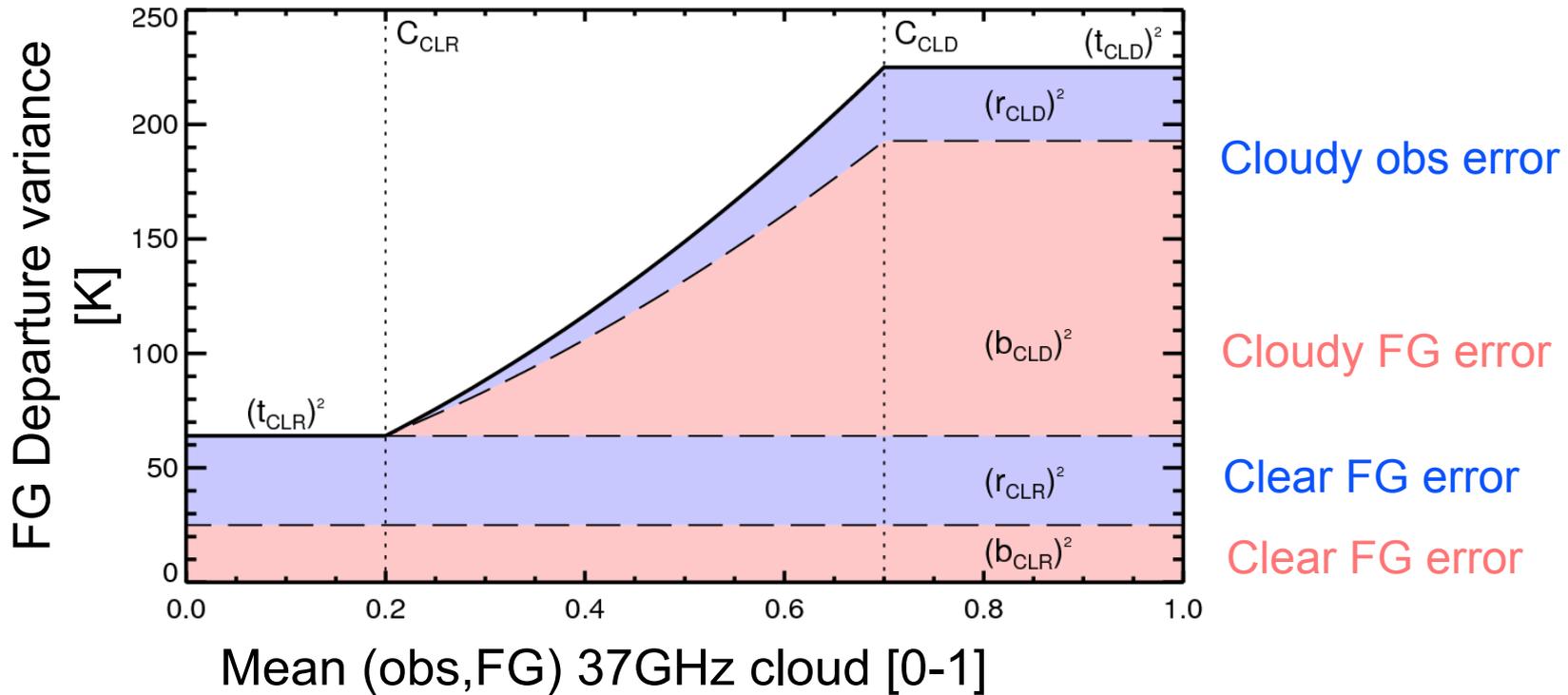
Std. dev.  
channel 19v  
departures  
[K]



as a function of forecast  
cloud  
as a function of observed  
cloud  
as a function of mean of  
observed and forecast  
cloud

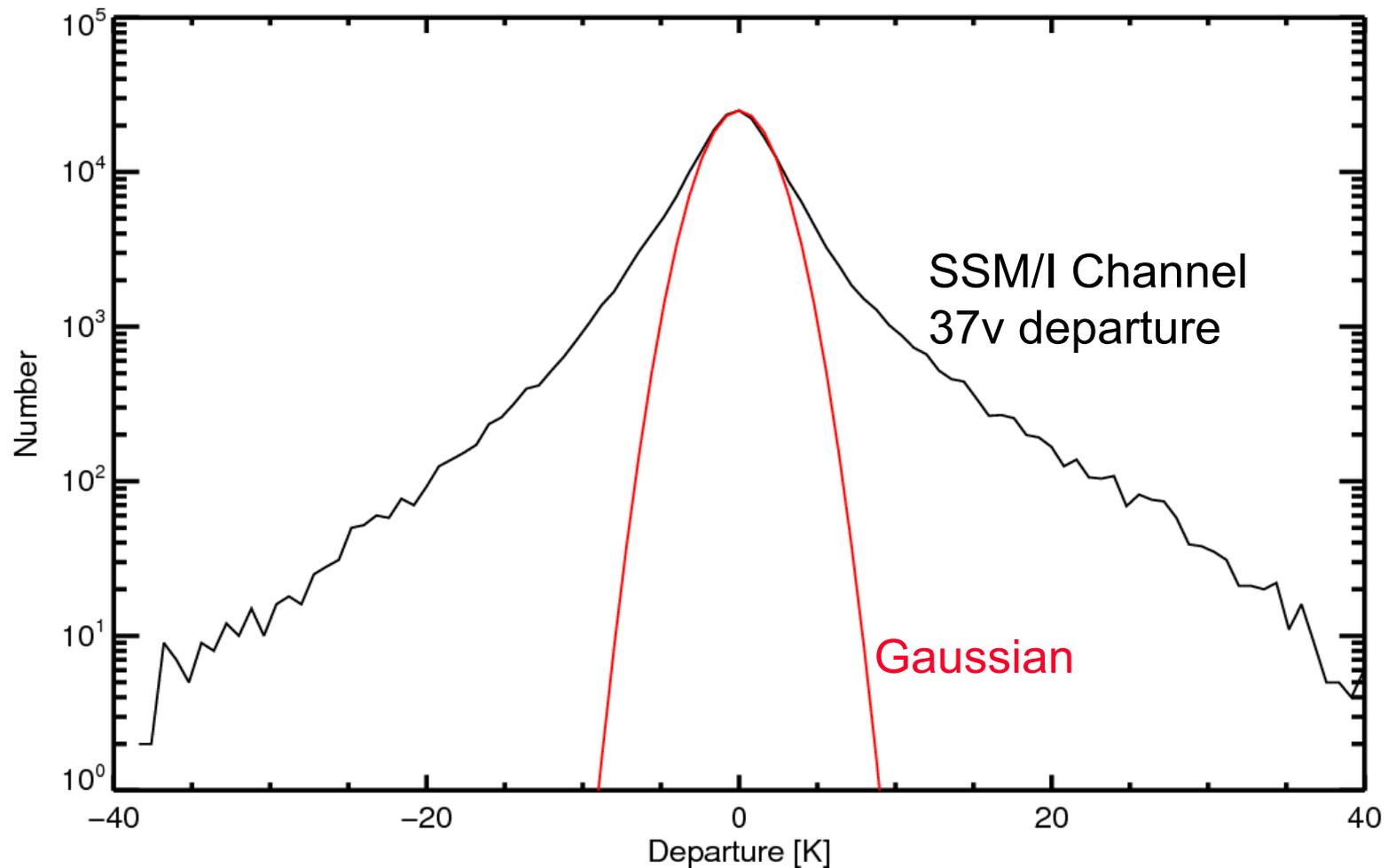


# Symmetric model for all-sky observation error

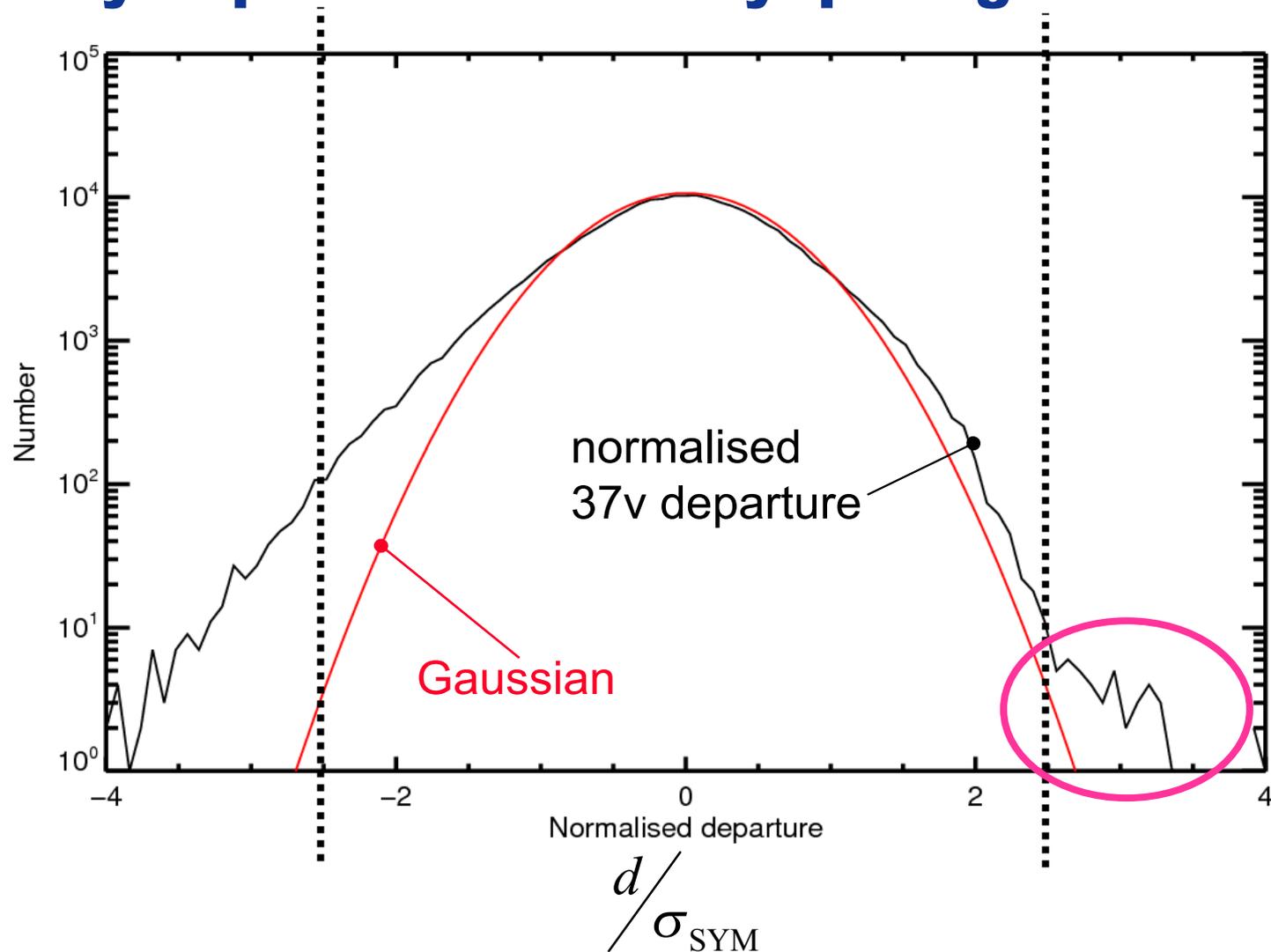


# Useful properties of “symmetric” errors

# All-sky departures: not gaussian?

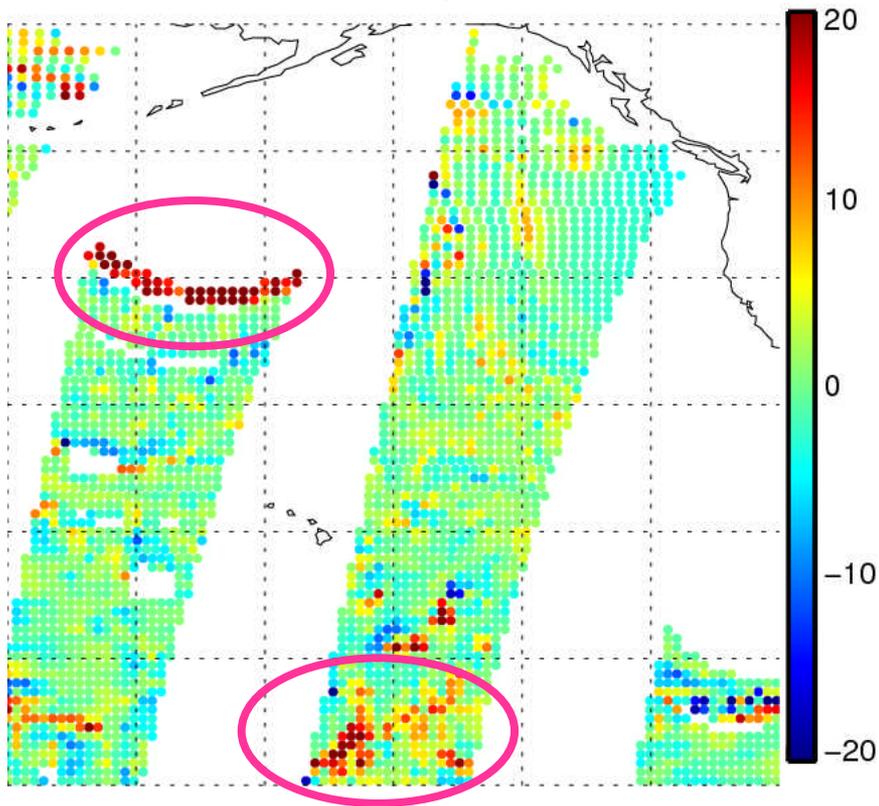


# All-sky departures: actually quite gaussian



# All-sky 4D-Var departures: QC

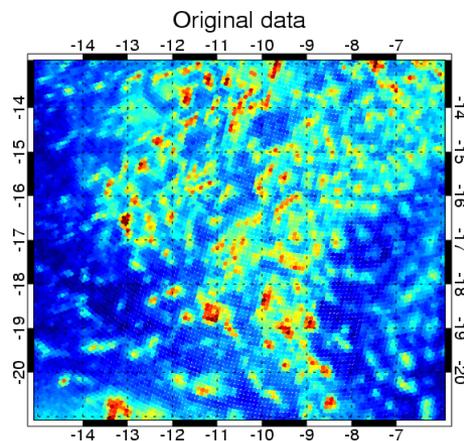
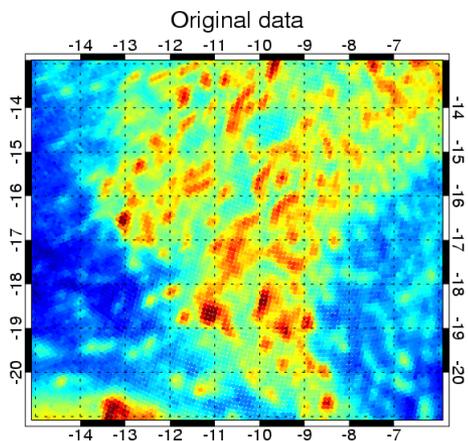
SSM/I 37v departure



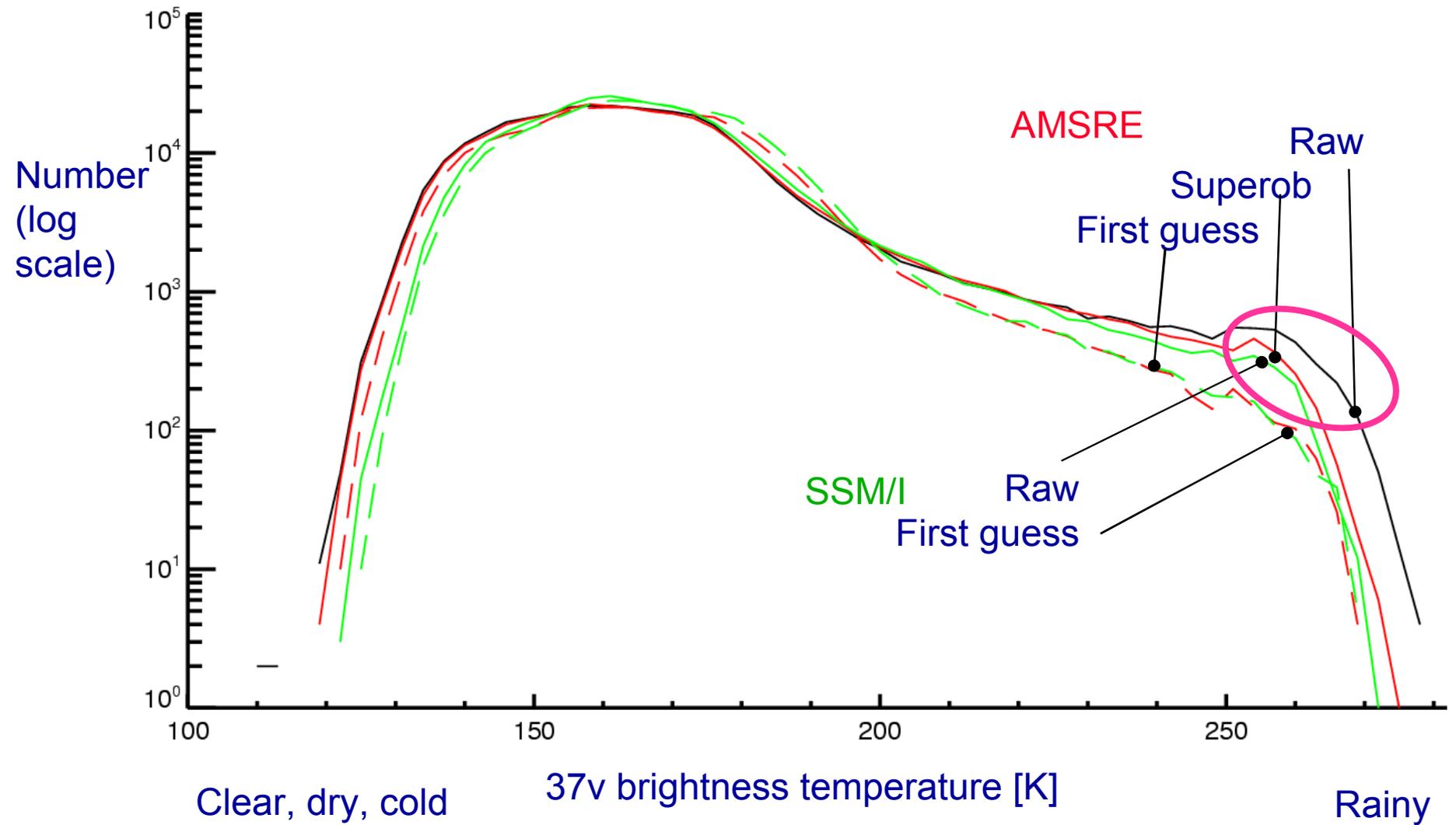
# Representativity

# 19 GHz

# 37 GHz



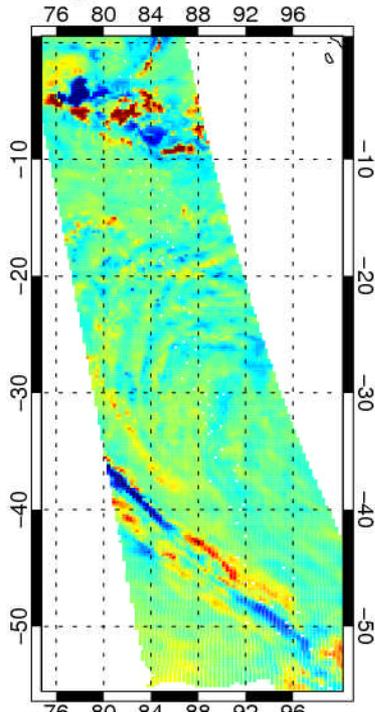
Raw AMSR-E data:  
10km by 9km sampling



# Model representativity: saved by ‘effective resolution’ of cloud

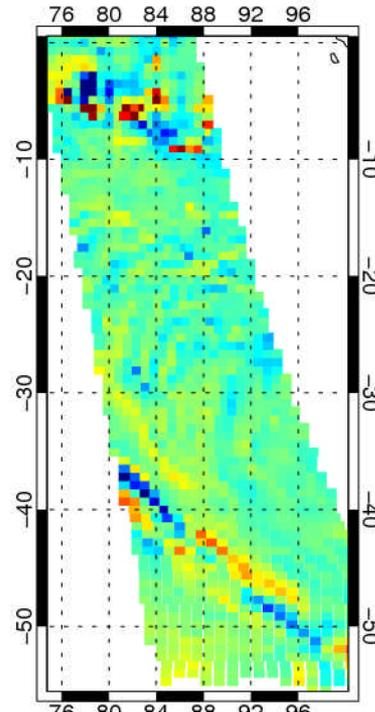
Hires obs –  
Hires model

g) Obs-FG T799



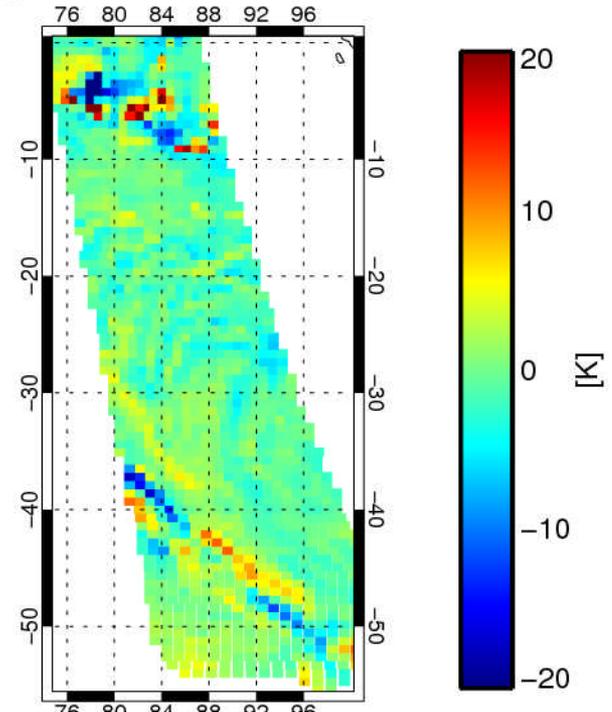
Lores obs –  
subsampled model

h) T255 Obs – subsampled FG

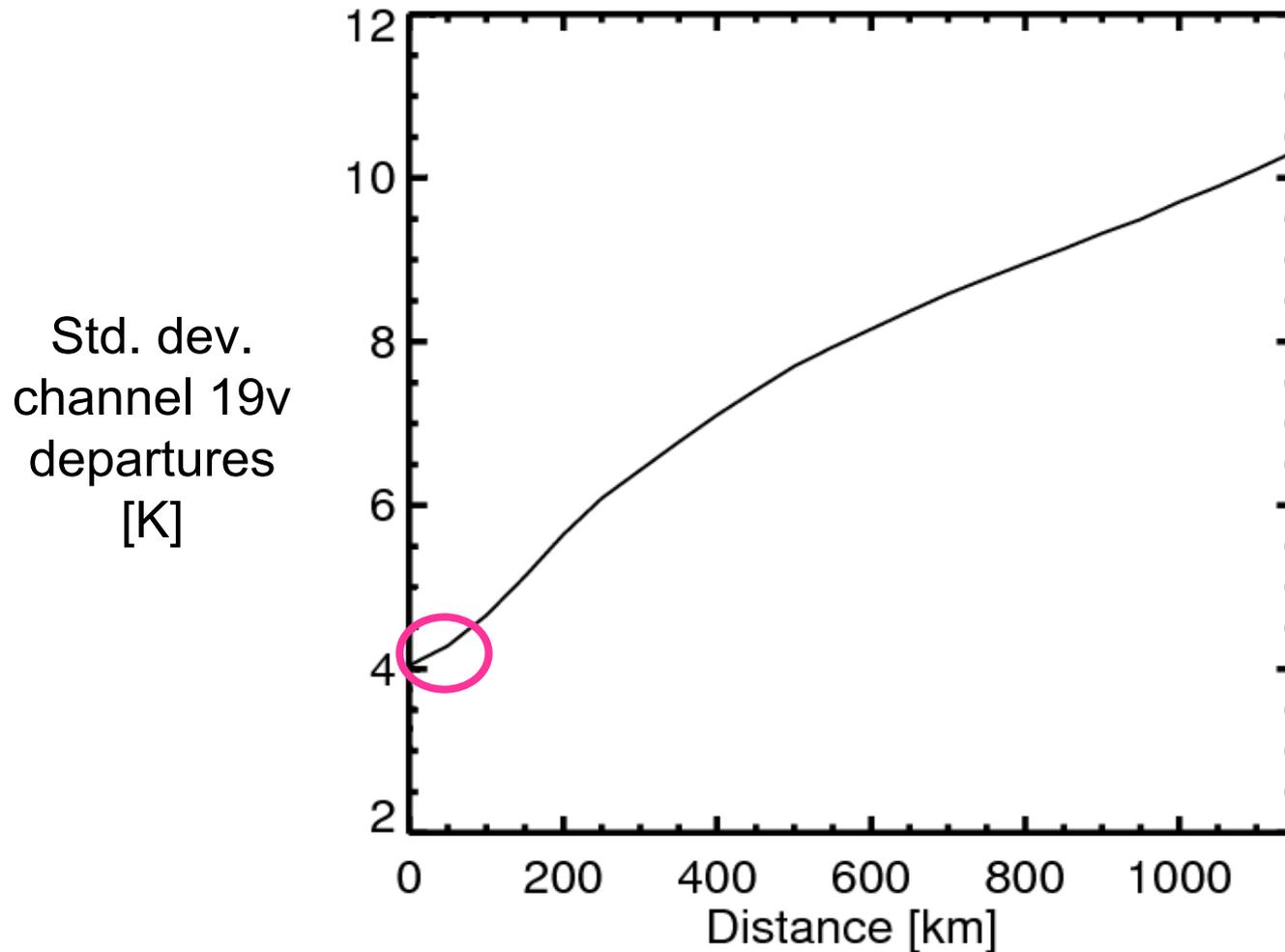


Lores obs –  
“superrobbed” model

i) T255 Obs – averaged FG



# Error inflation with collocation distance model vs. observation

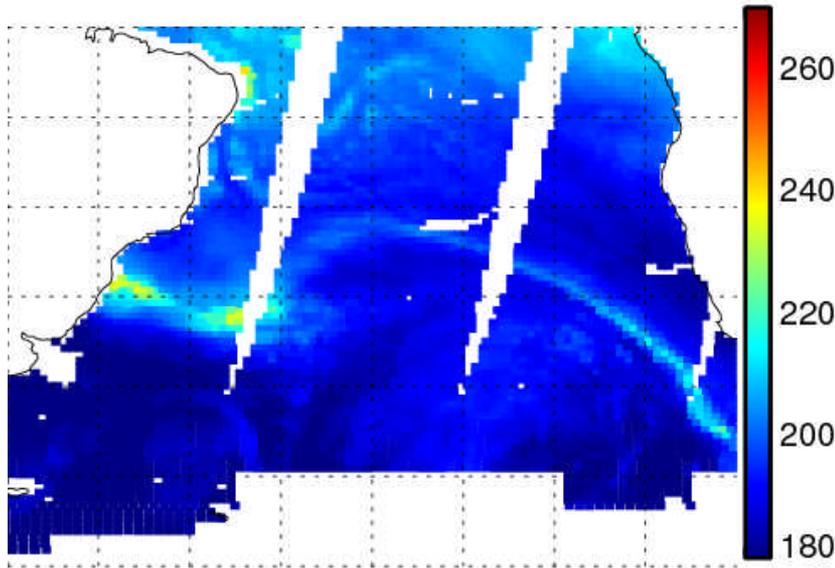


# Representativity - summary

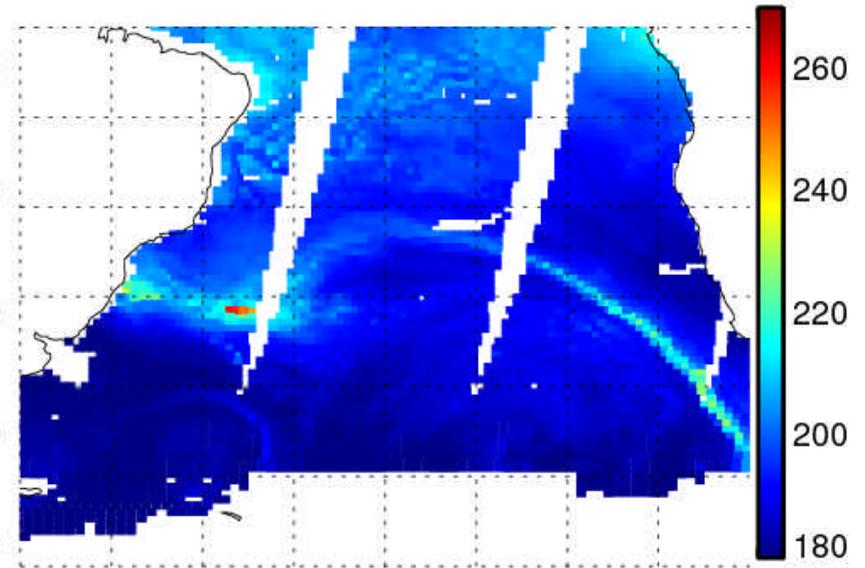
- High-res PDFs (e.g. of precipitation or brightness temperature) are very different to lo-res PDFs
- Subsampling (or use of single observations) is wrong
- High-res observations → lo-res model
  - Must spatially average (“superob”) observations to appropriate model scale.
- High-res model → lo-res observation
  - Must spatially average (“superob”) model to appropriate observation scale
  - But in practice, model cloud and FG error scales are much coarser than nominal resolution
    - So it’s ~OK to subsample.
    - Model vs. observation colocation distance not too important (at least over 100-200km)
- Sub-grid cloud/precip variability
  - Well-known issue for moist physics and observation operators

# **Biases between model and cloud / precipitation affected observations**

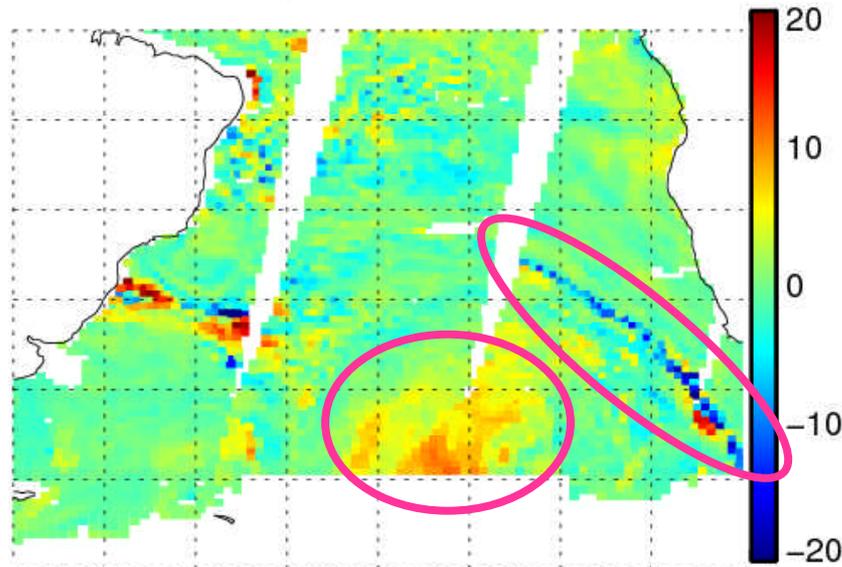
a) Obs



b) FG



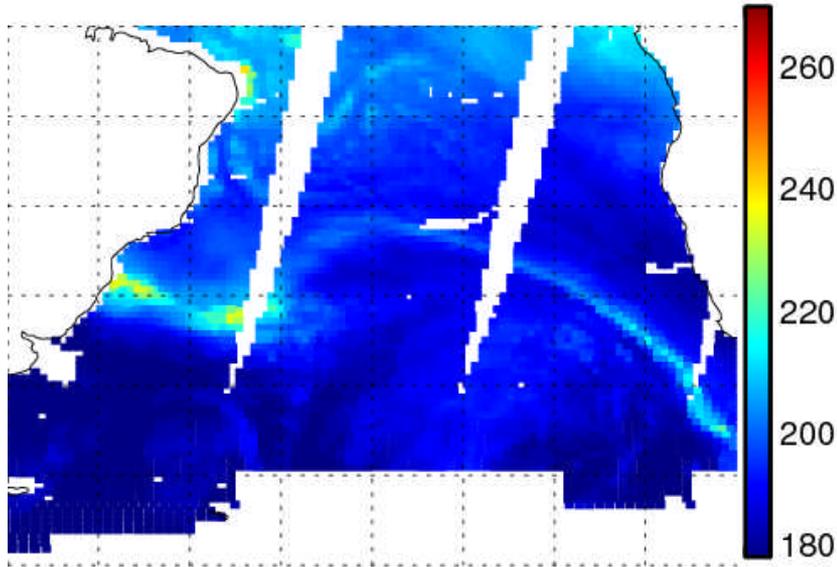
c) Obs - FG



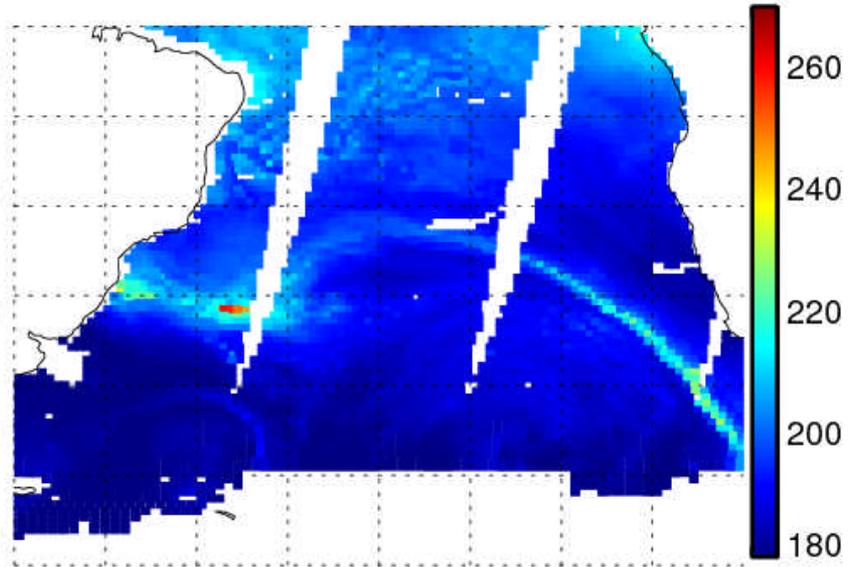
**SSM/I  
Channel 19v**

00Z 9-Aug-2009

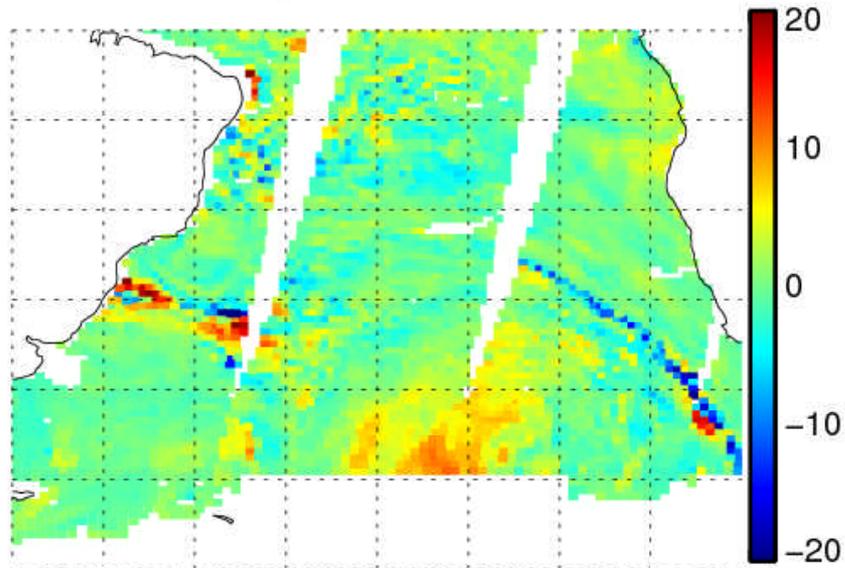
a) Obs



b) FG

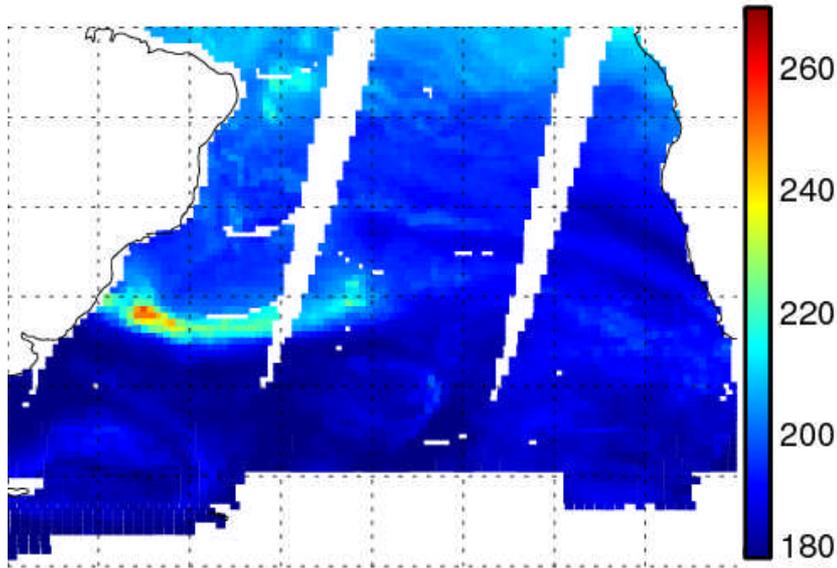


c) Obs - FG

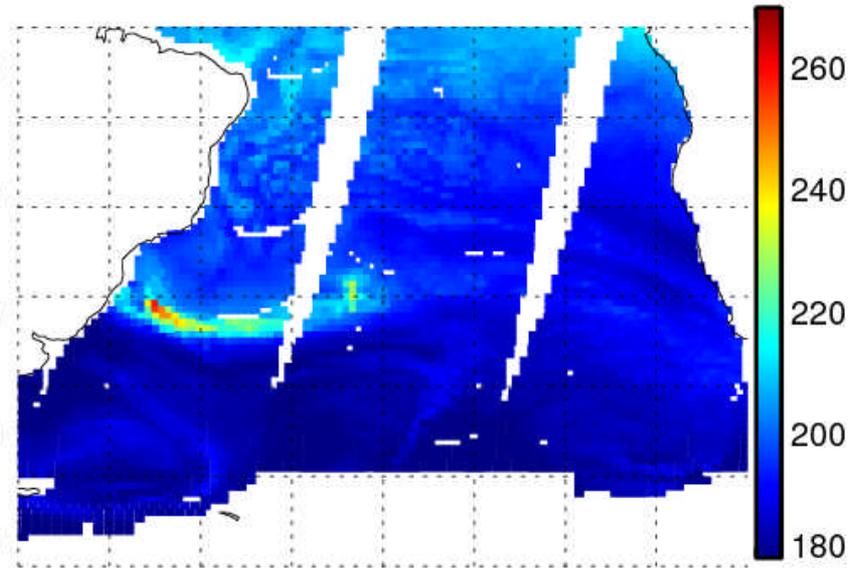


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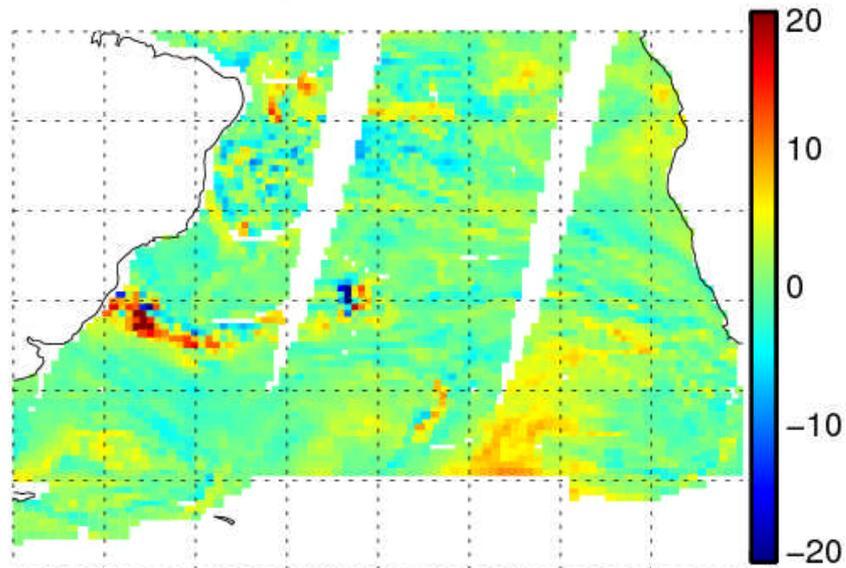
a) Obs



b) FG

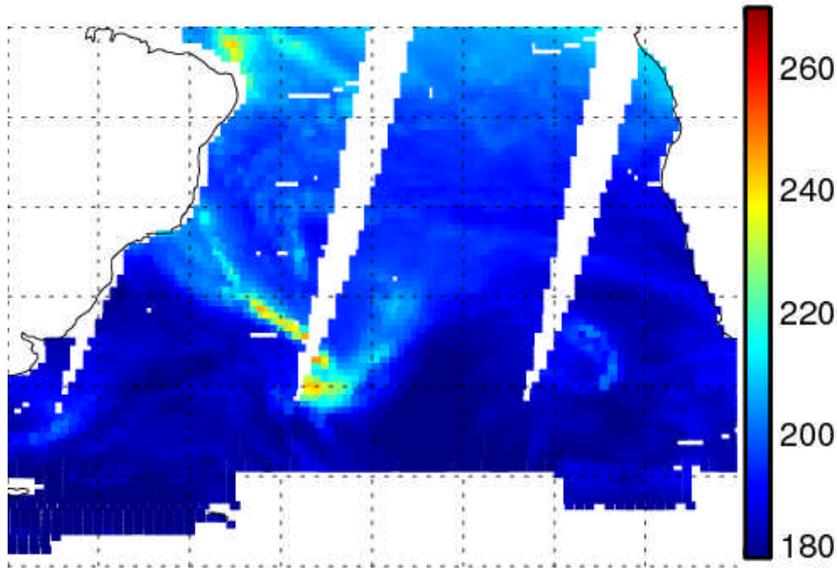


c) Obs - FG

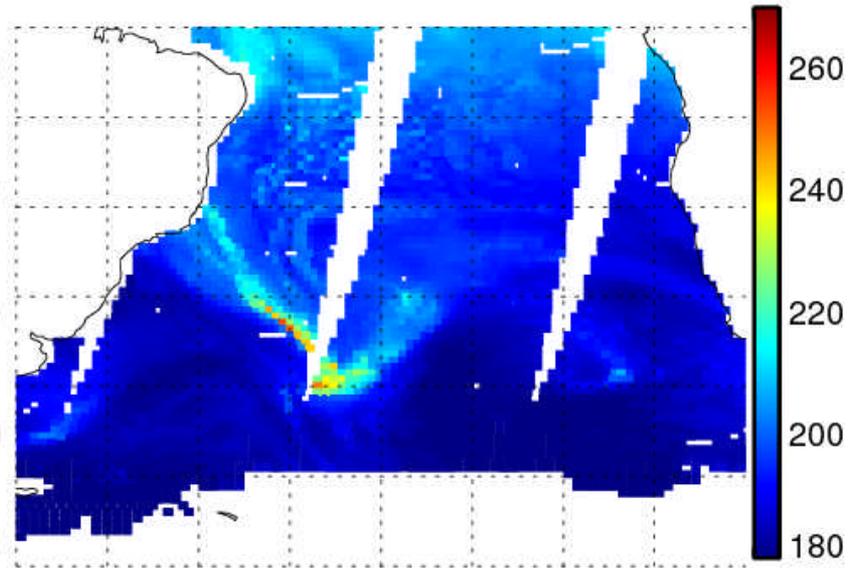


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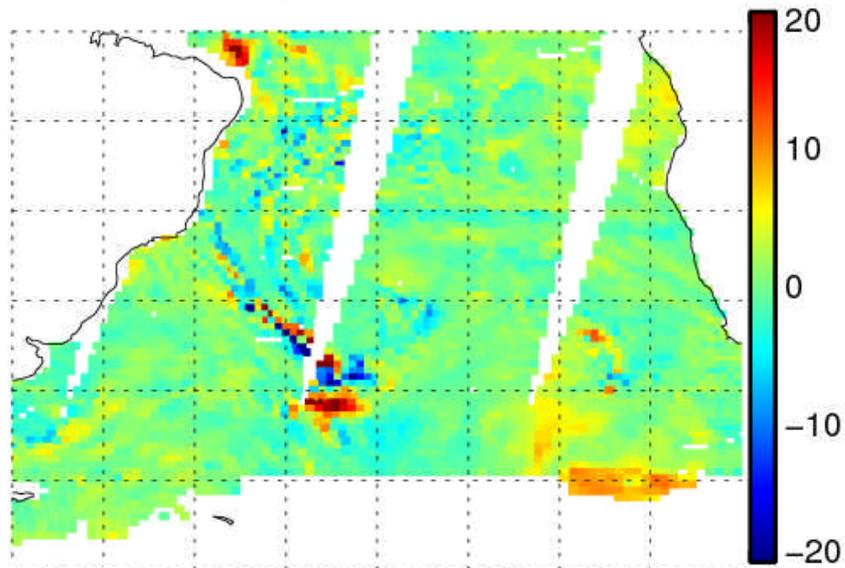
a) Obs



b) FG

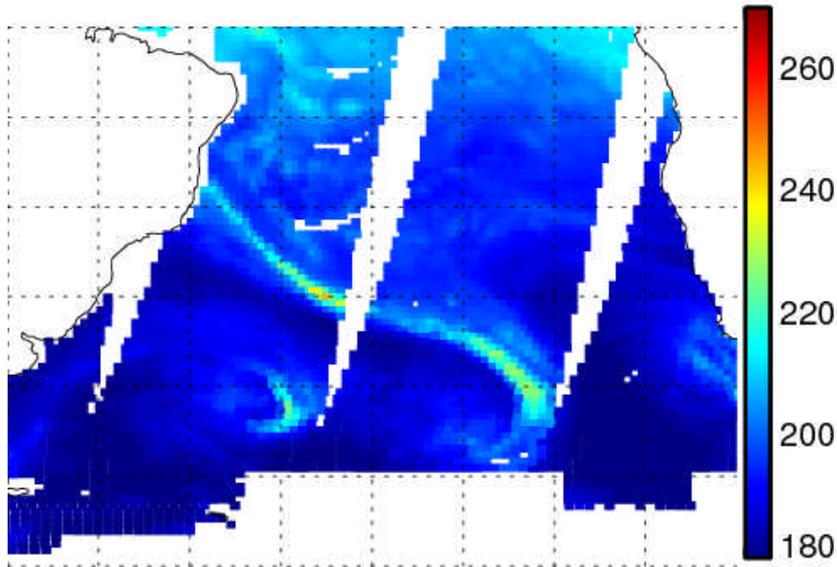


c) Obs - FG

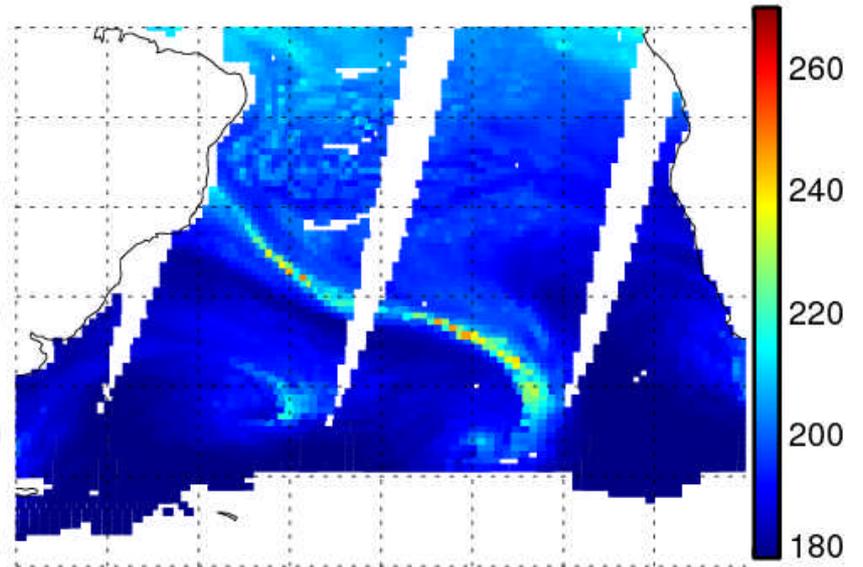


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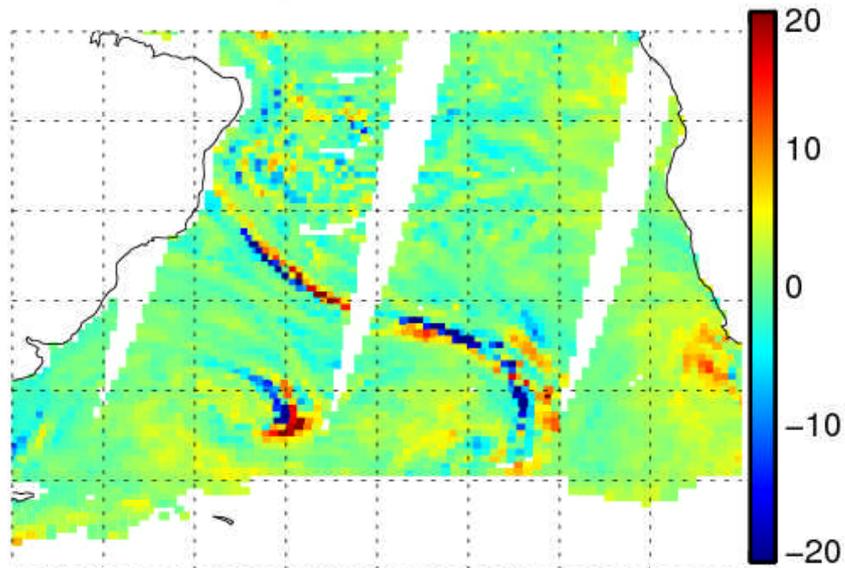
a) Obs



b) FG

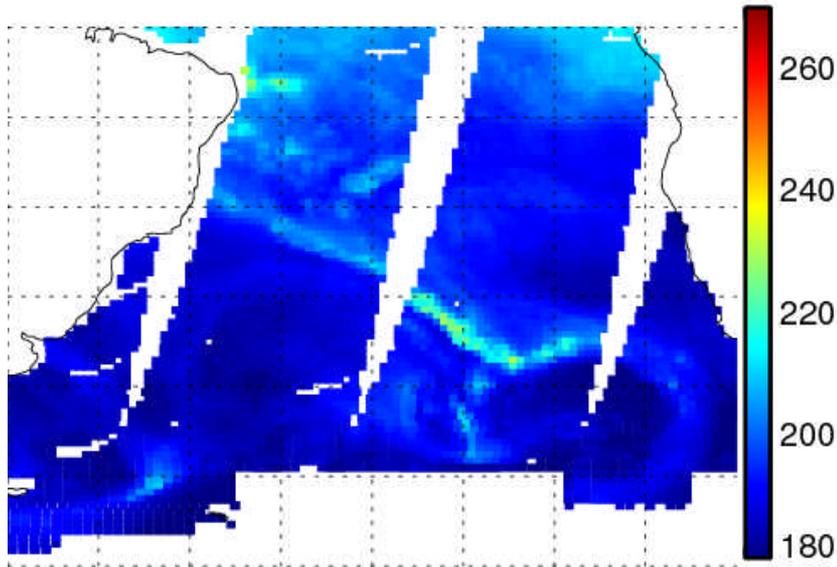


c) Obs - FG

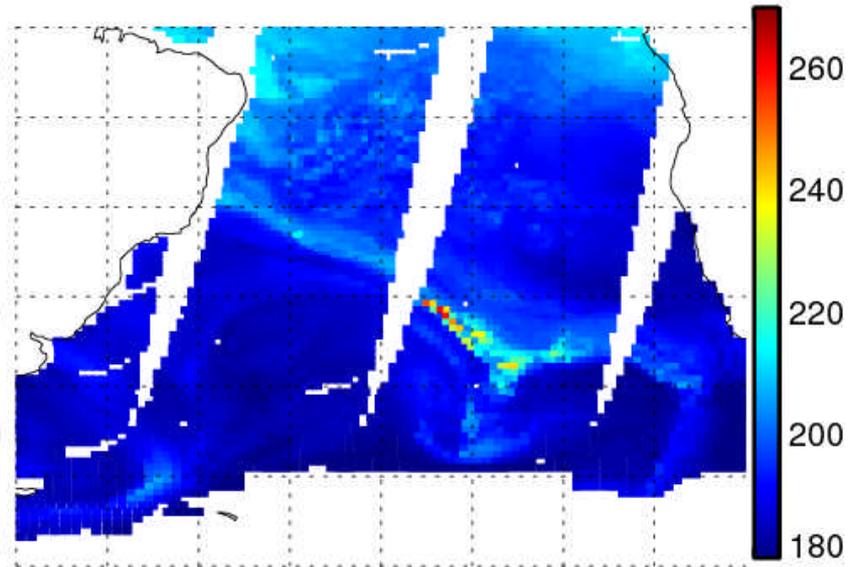


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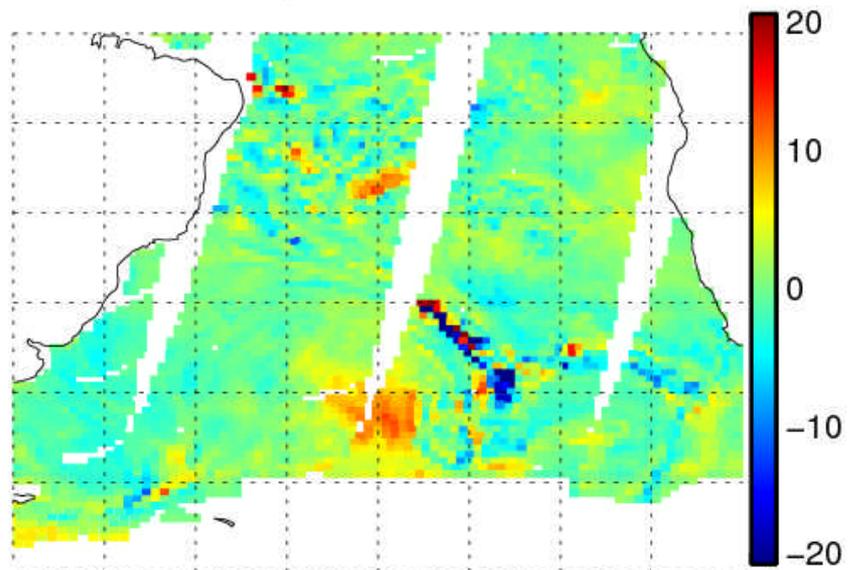
a) Obs



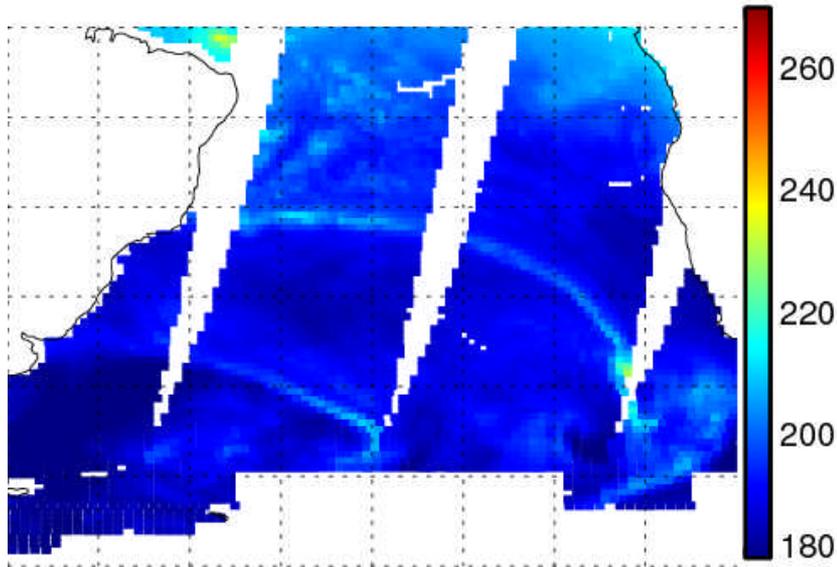
b) FG



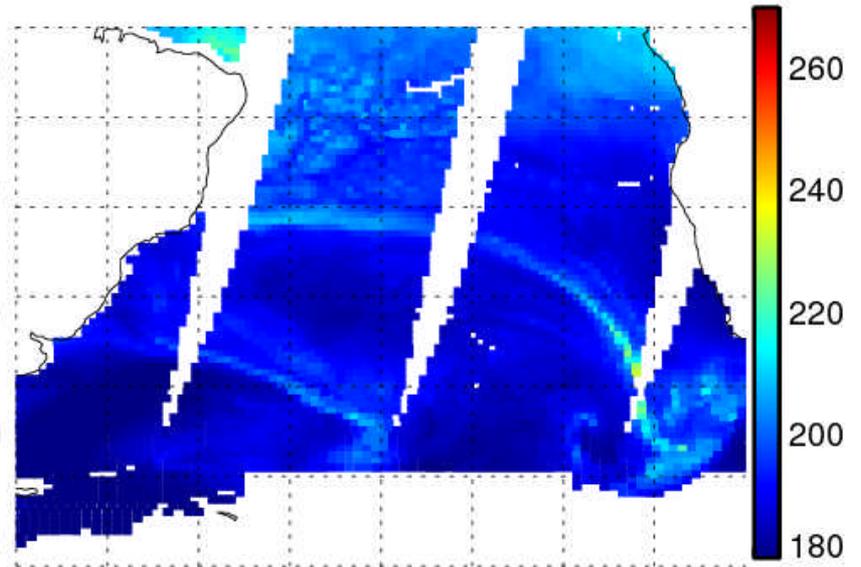
c) Obs - FG



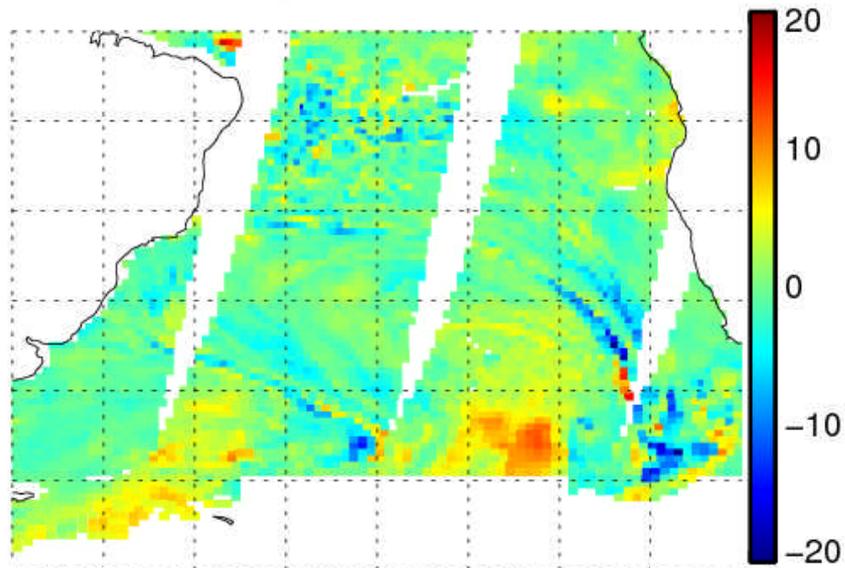
a) Obs



b) FG

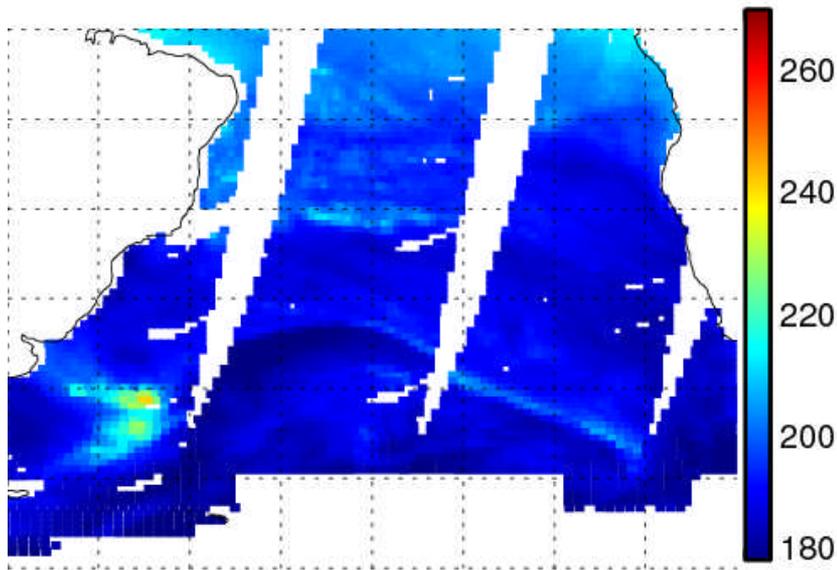


c) Obs - FG

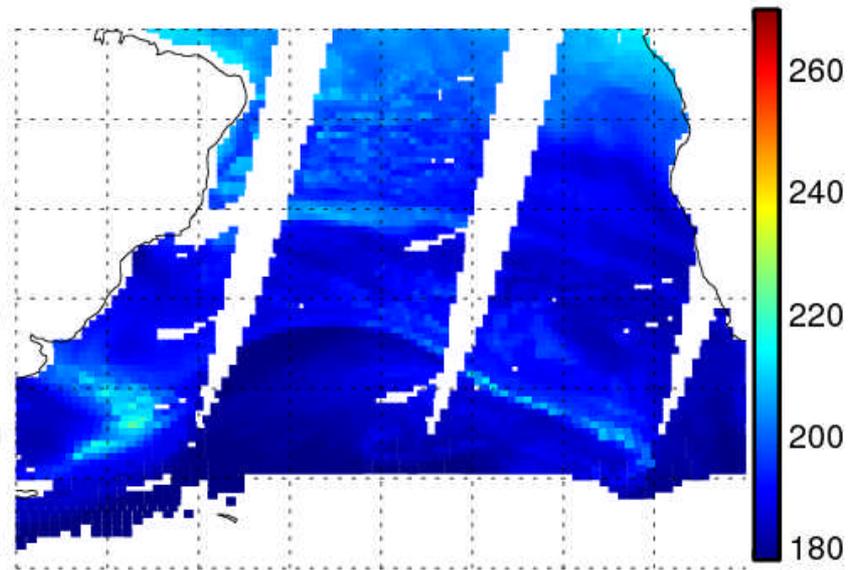


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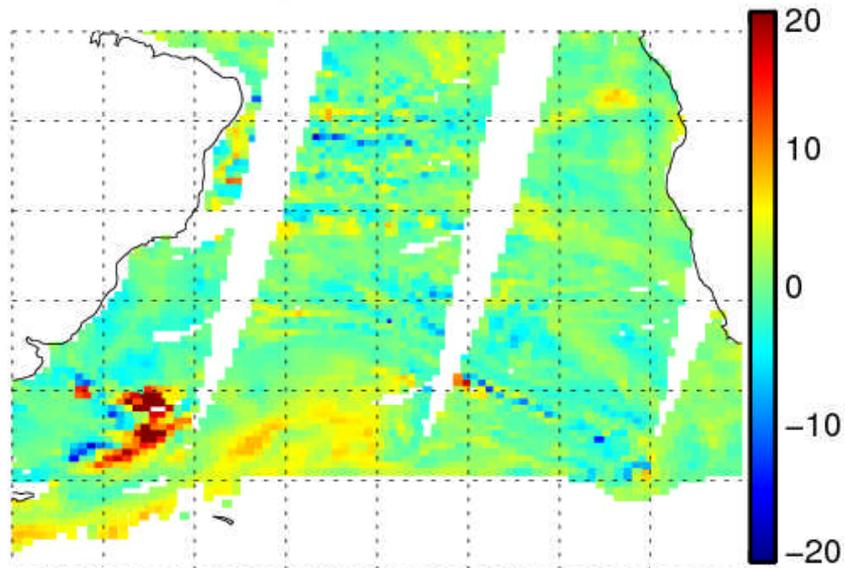
a) Obs



b) FG

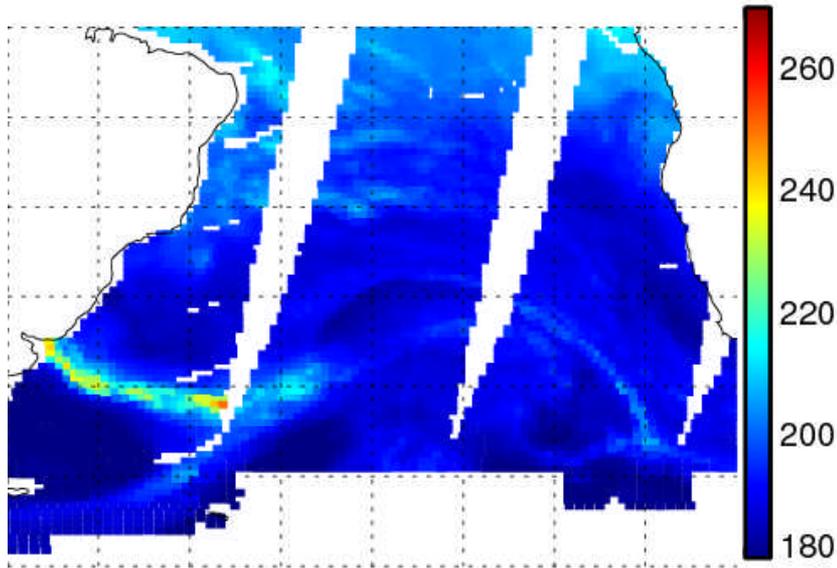


c) Obs - FG

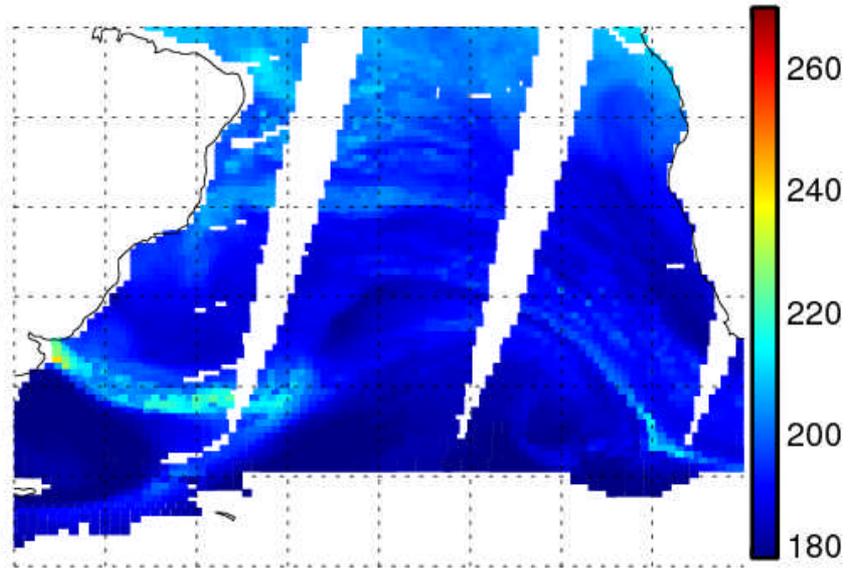


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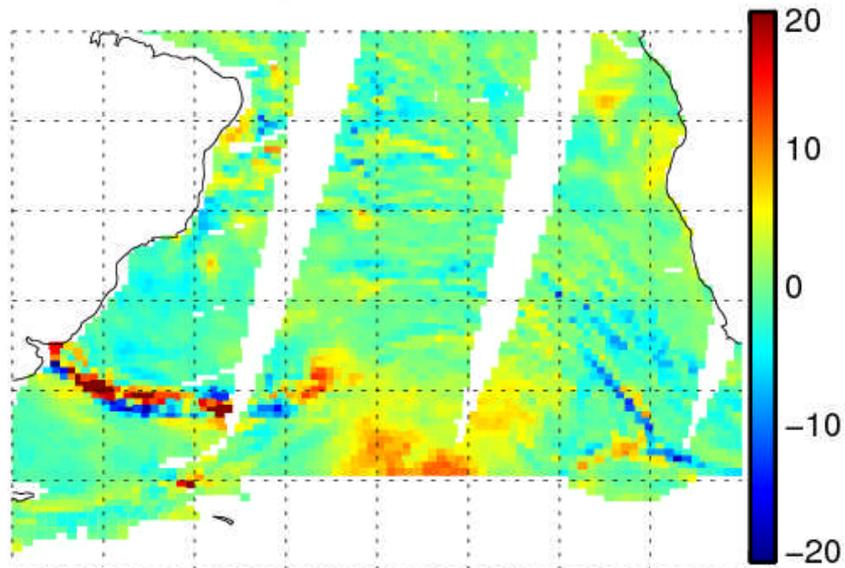
a) Obs



b) FG

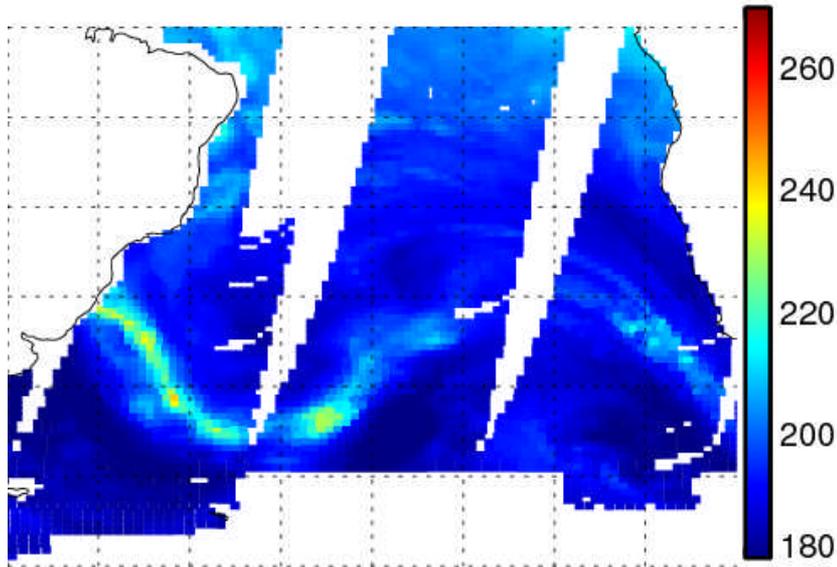


c) Obs - FG

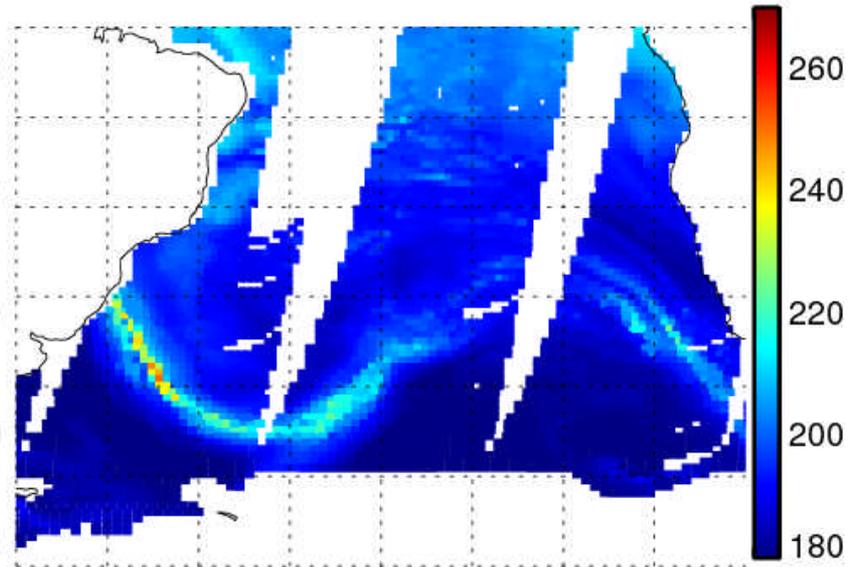


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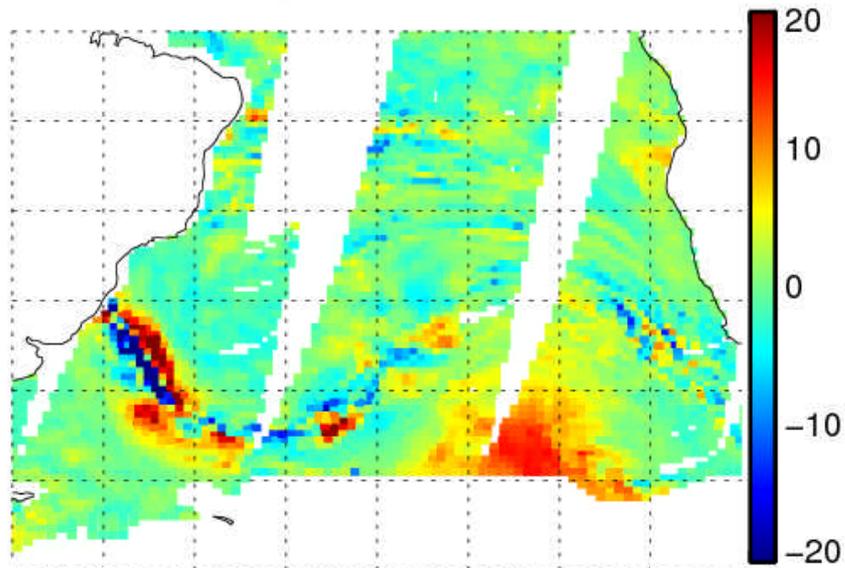
a) Obs



b) FG

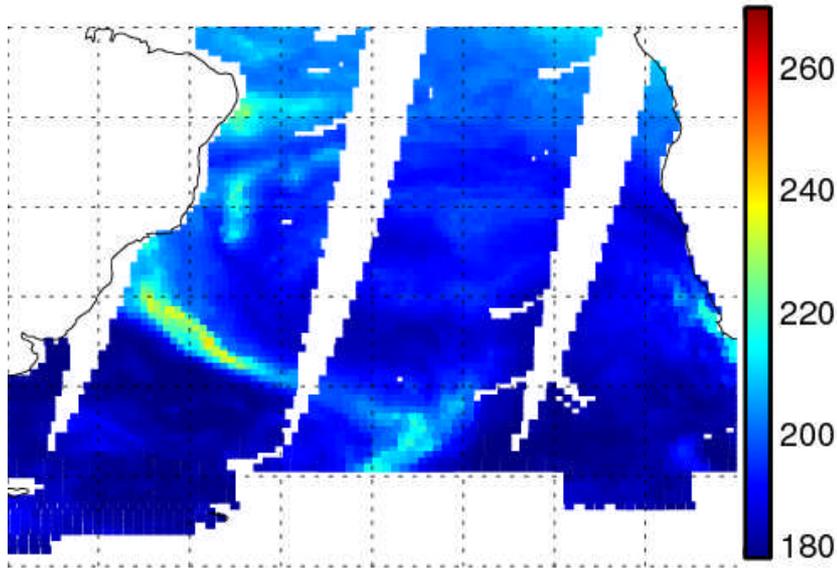


c) Obs - FG

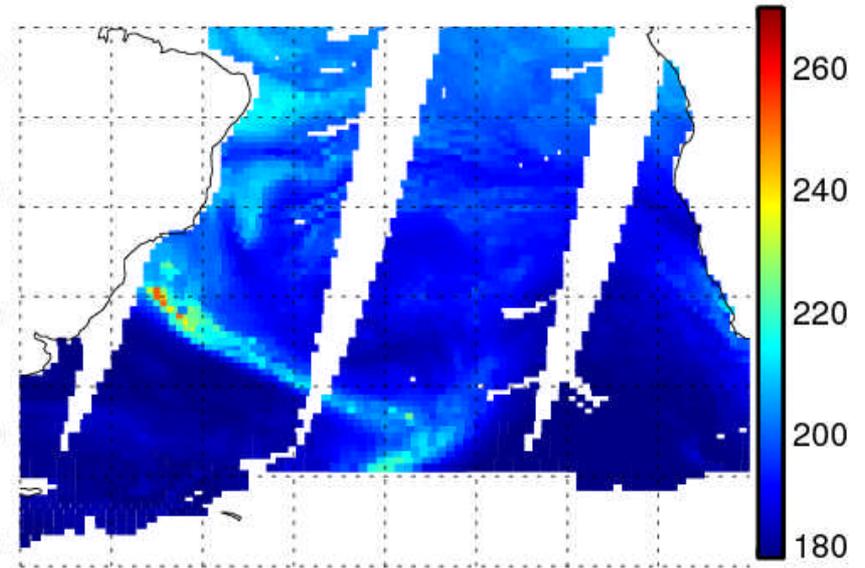


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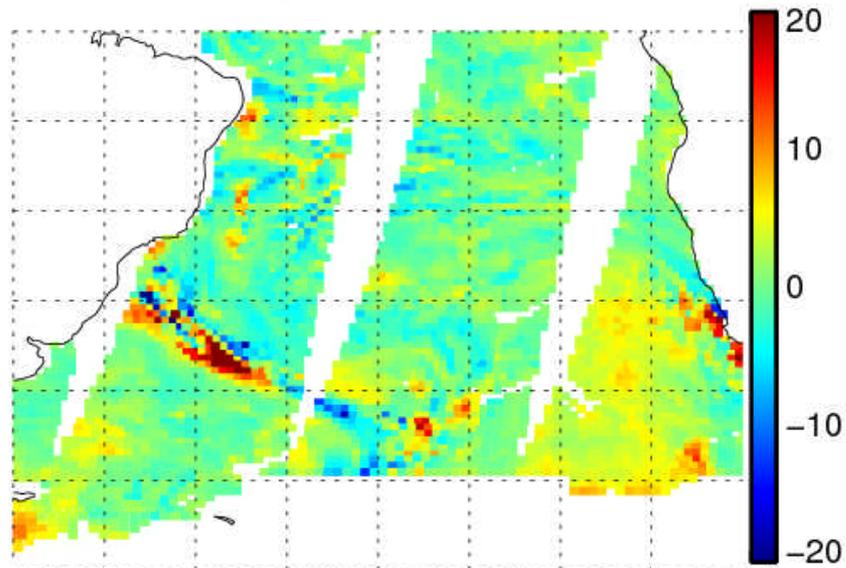
a) Obs



b) FG

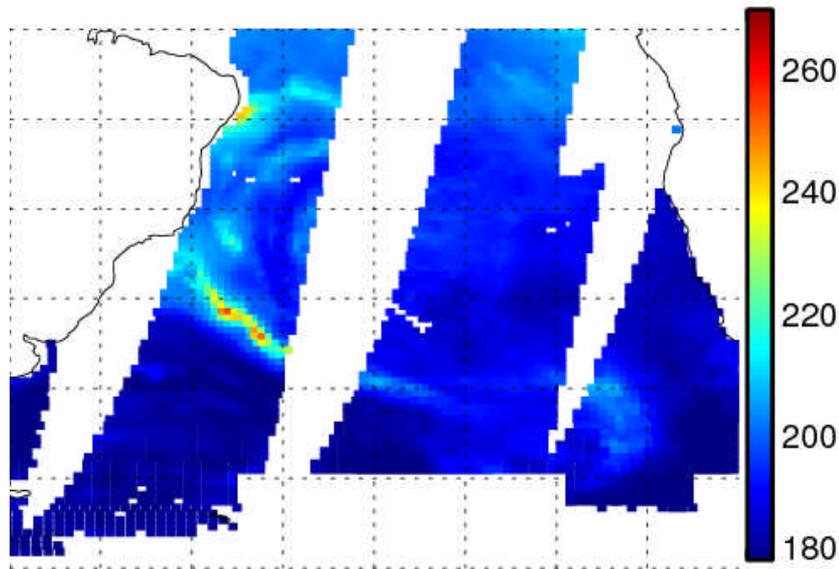


c) Obs - FG

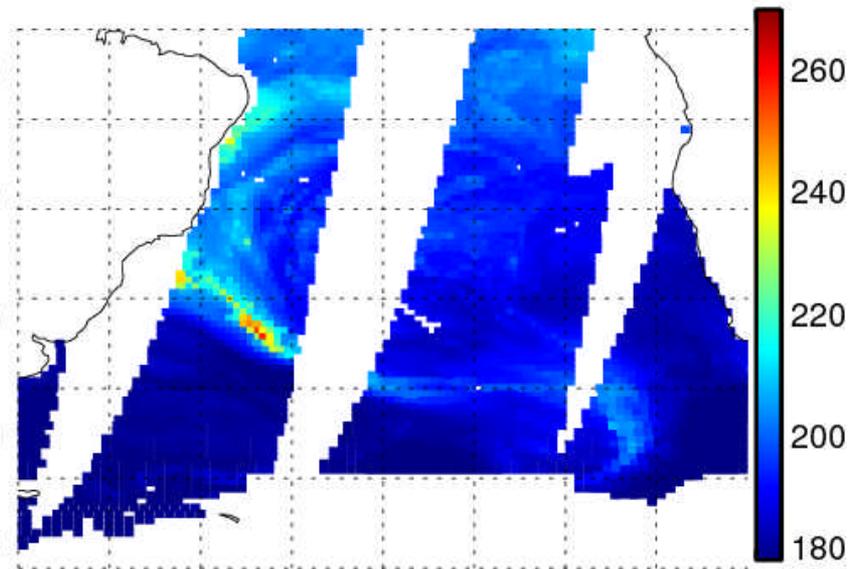


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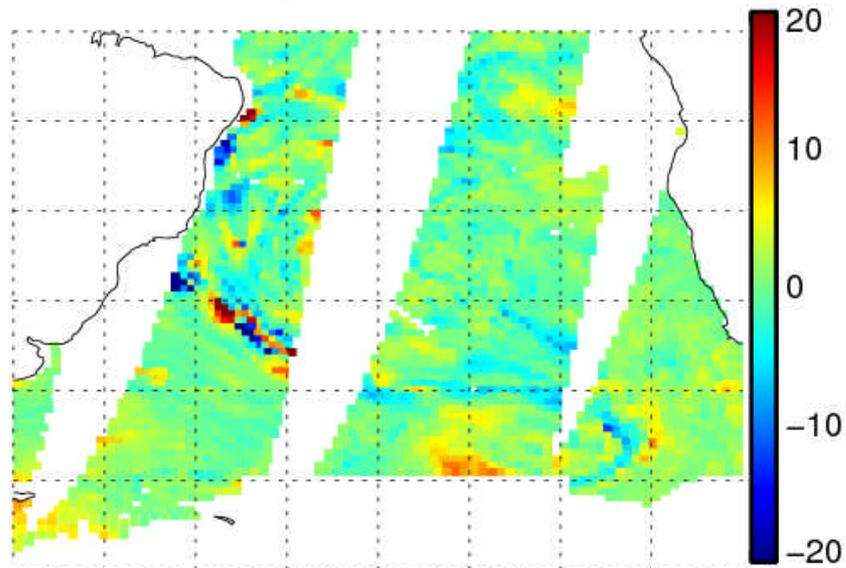
a) Obs



b) FG

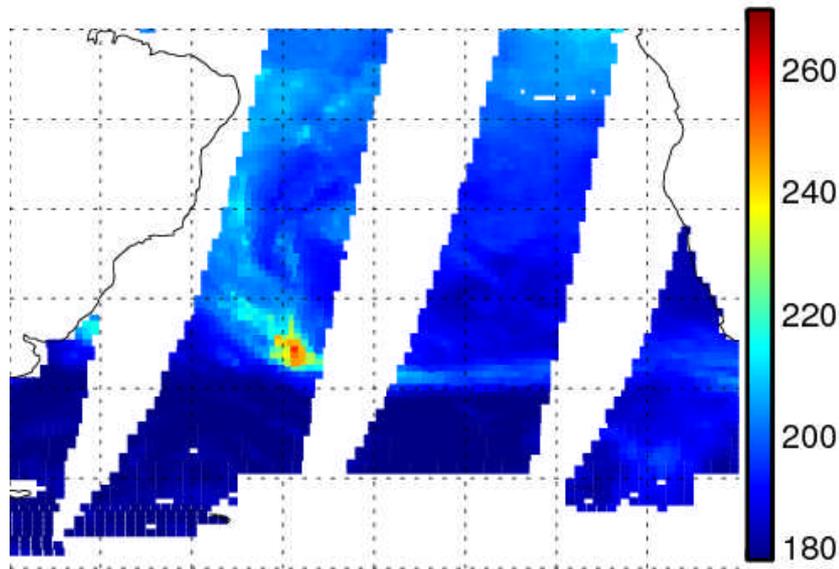


c) Obs - FG

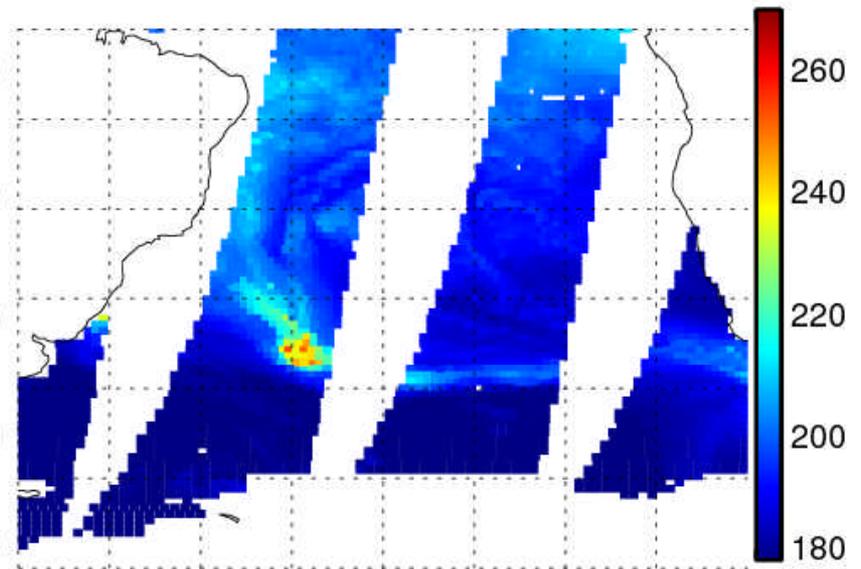


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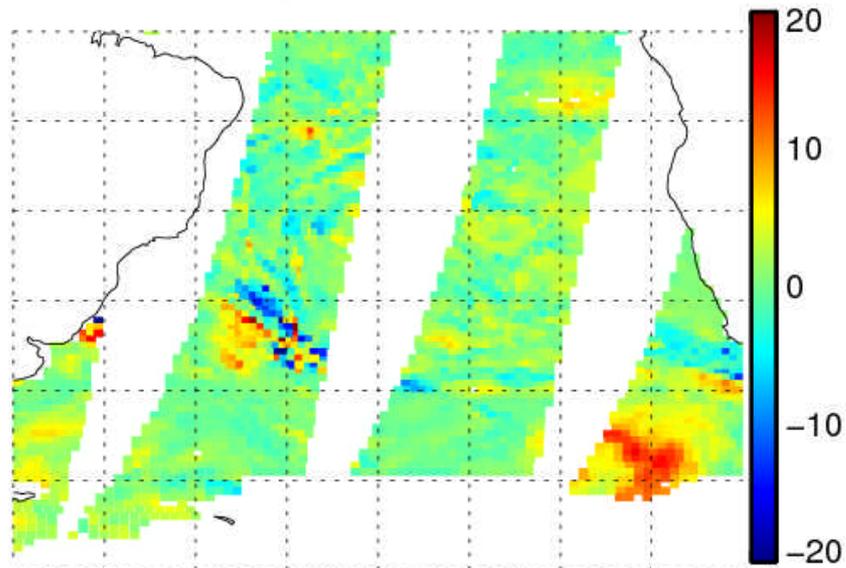
a) Obs



b) FG

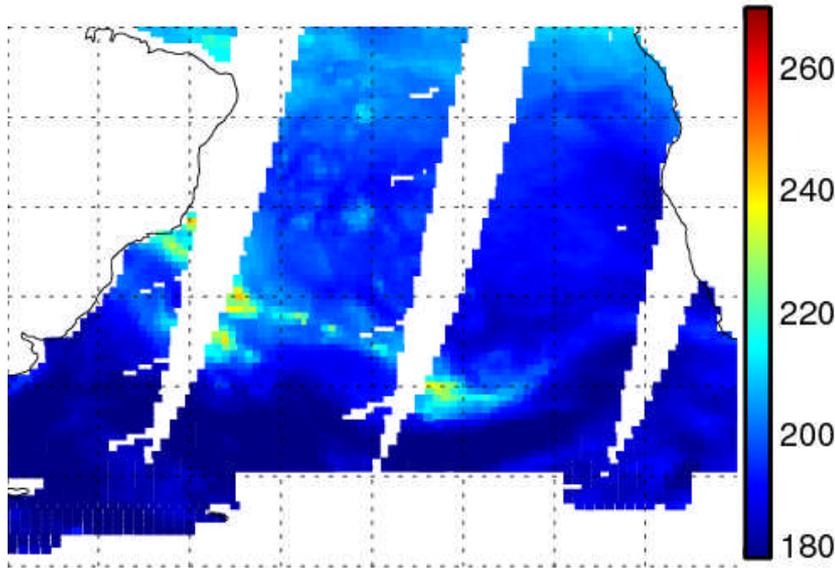


c) Obs - FG

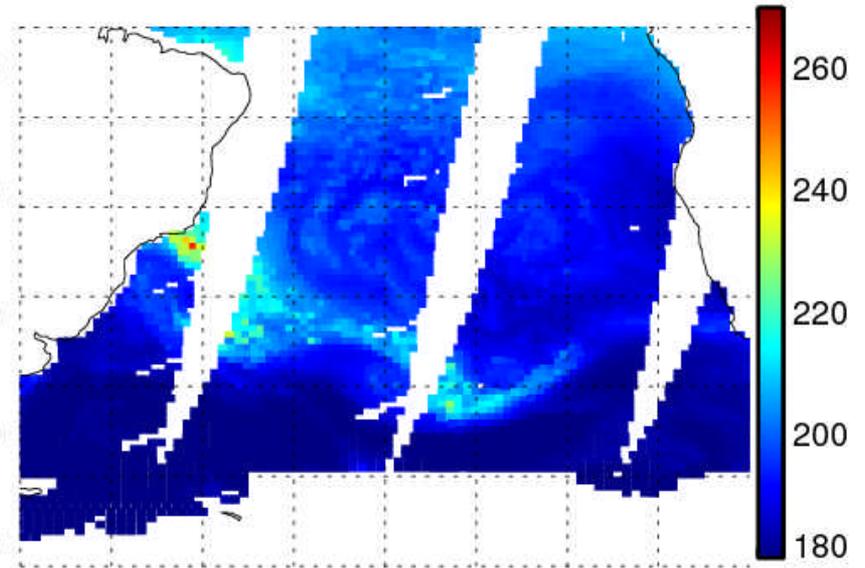


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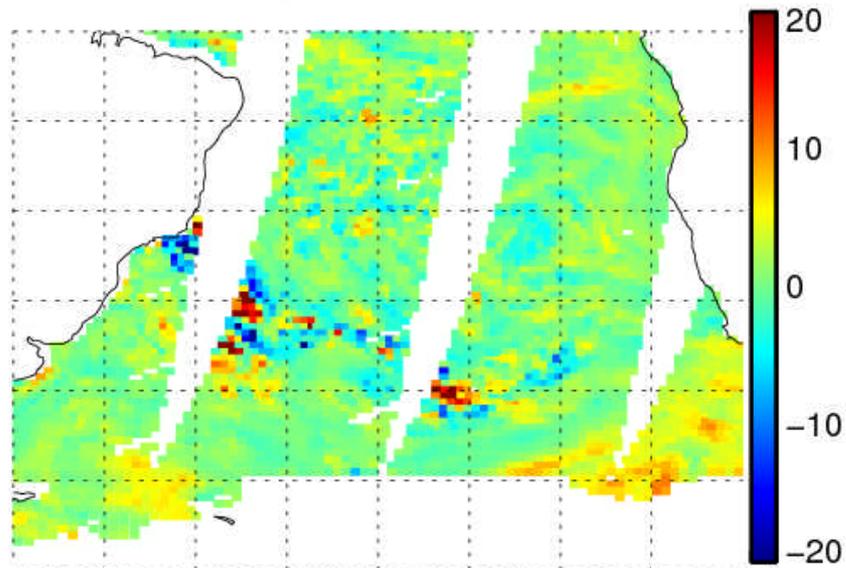
a) Obs



b) FG



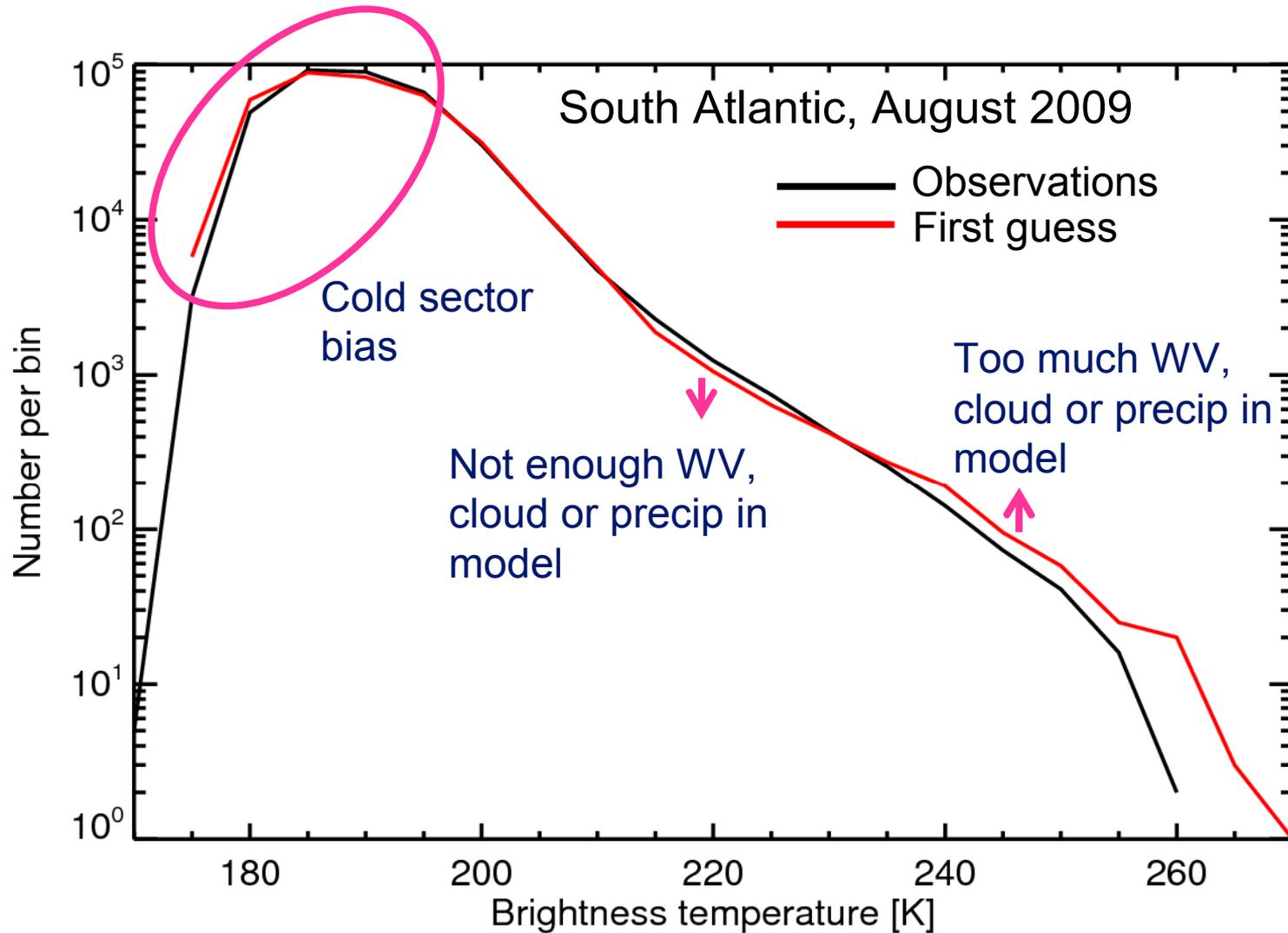
c) Obs - FG



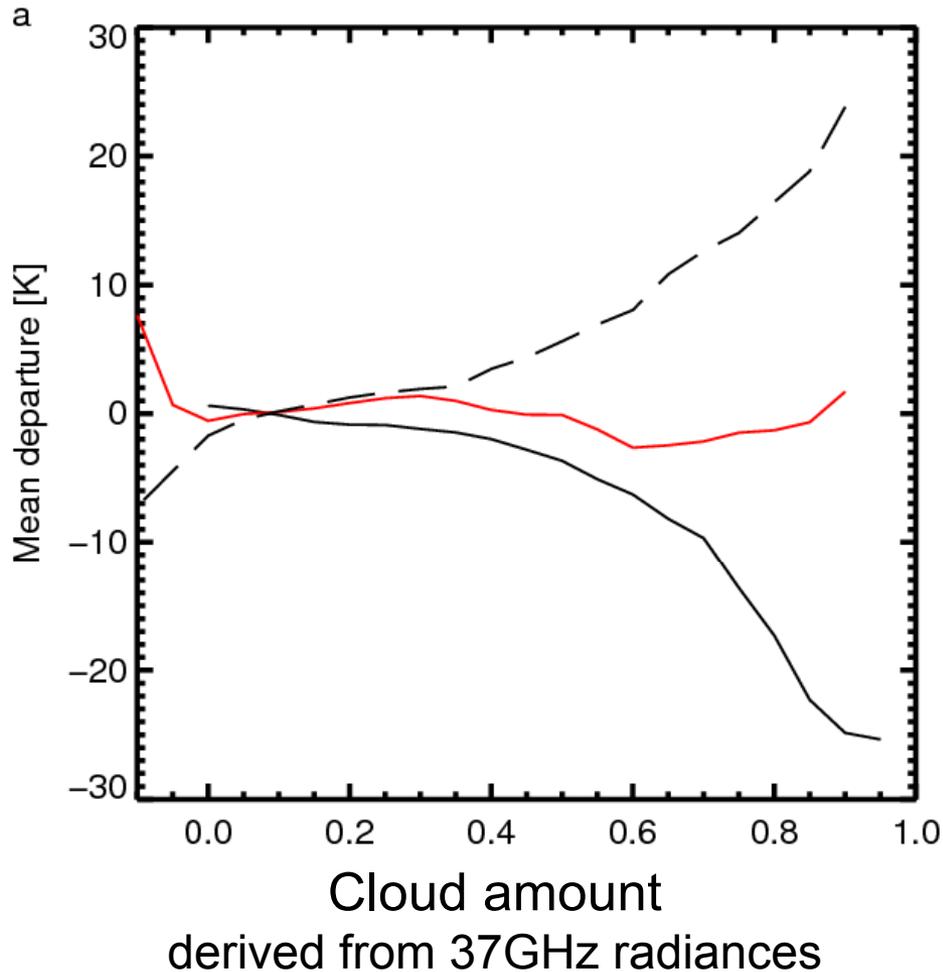
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# PDF of brightness temperature: Channel 19v



# Bias correction as a function of cloud

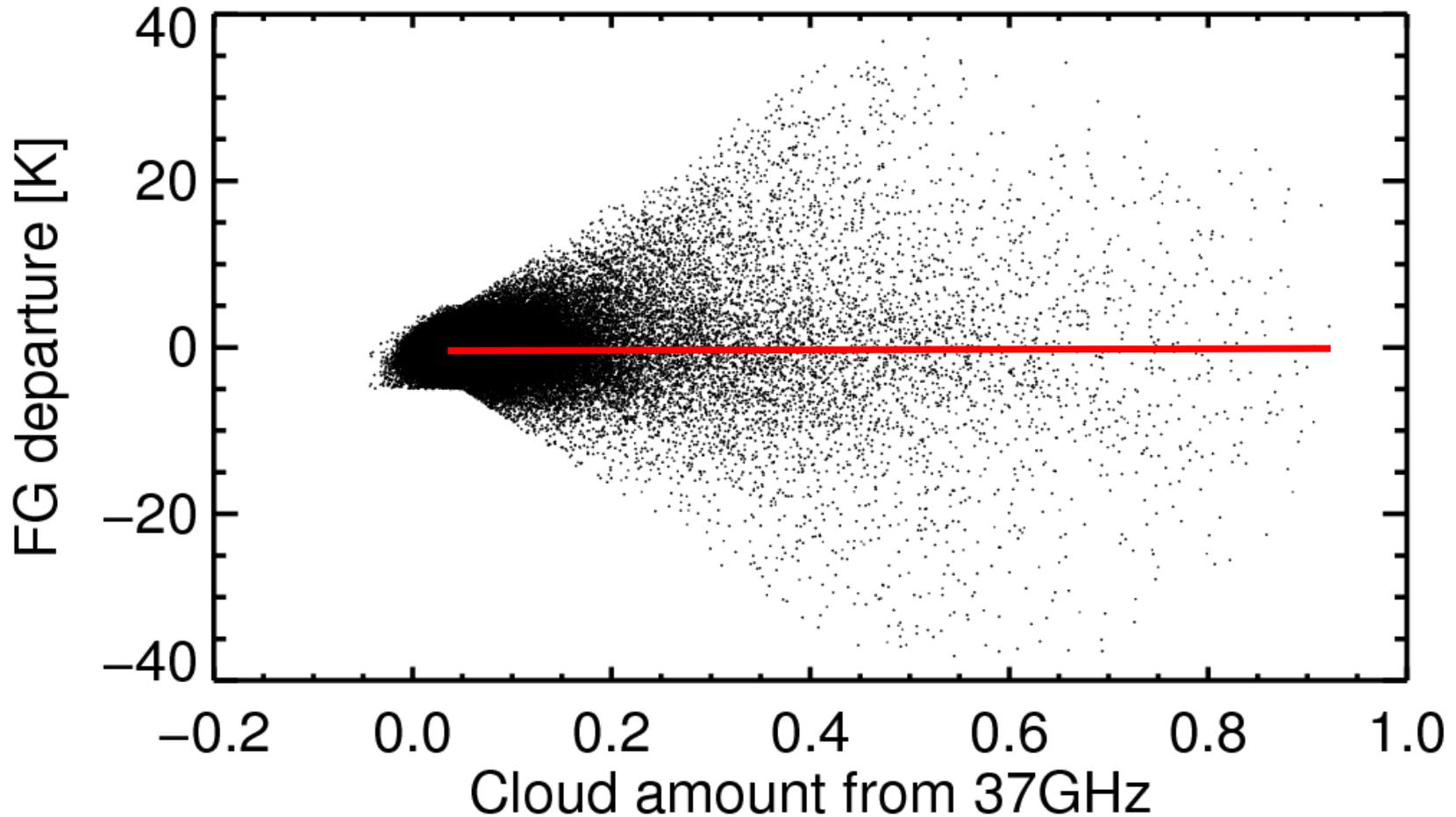


~~as a function of  
observed  
cloud~~

as a function of mean of  
observed and forecast cloud

~~as a function  
of forecast  
cloud~~

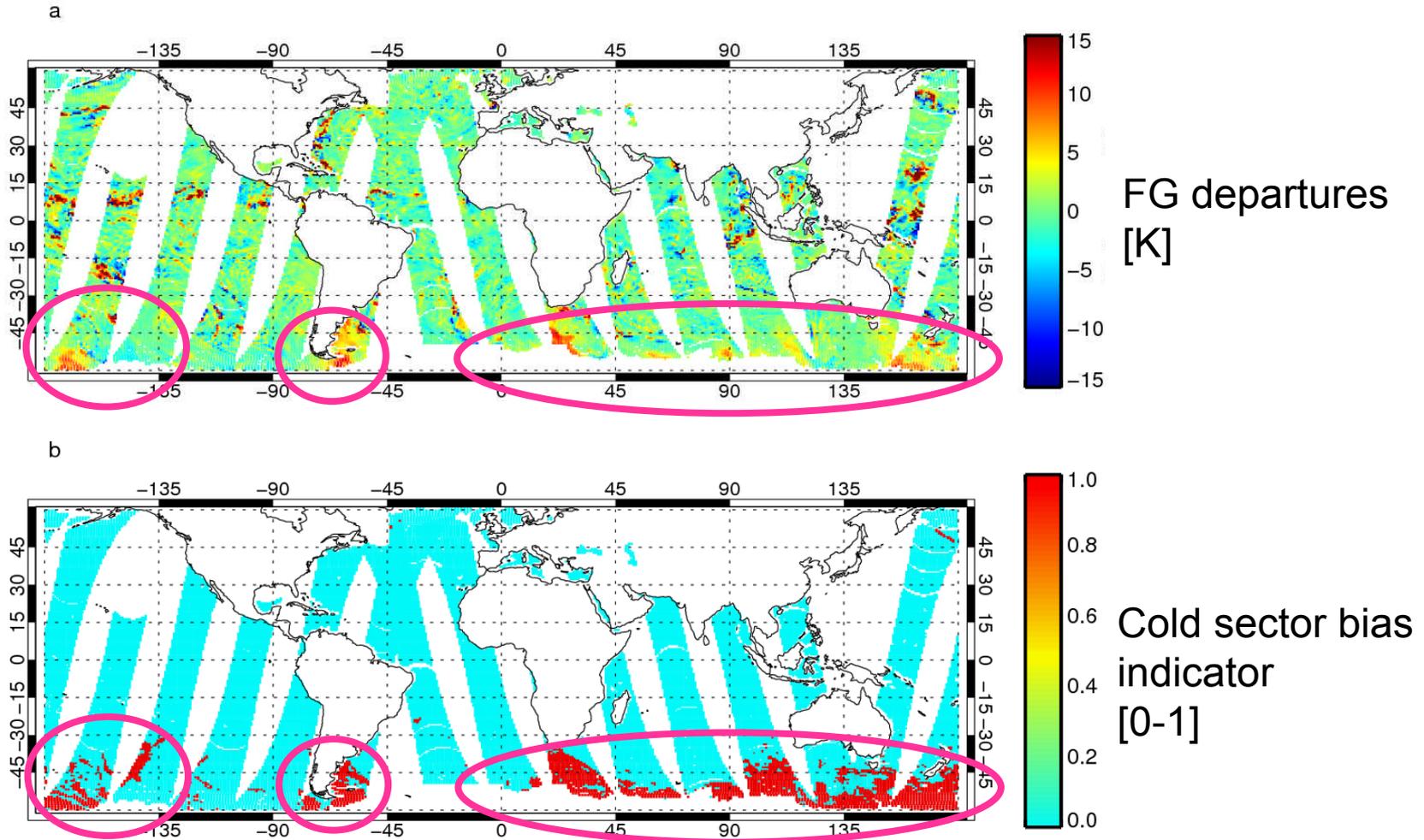
# Difficulties with adaptive bias correction



# Difficulties with adaptive bias correction

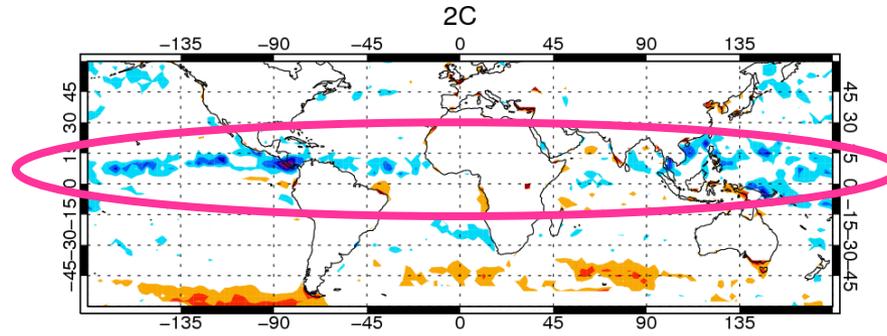
- Signal to noise:
  - biases of ~2K against standard deviations of 15K
- Biases can be determined by a few observations at the extreme cloudy end
  - Vulnerable to interactions with quality control
- “Mean cloud” predictor is not well targeted
  - But no success with more precise approaches either e.g., tropics vs. midlatitude separation

# Screening criteria for bad biases

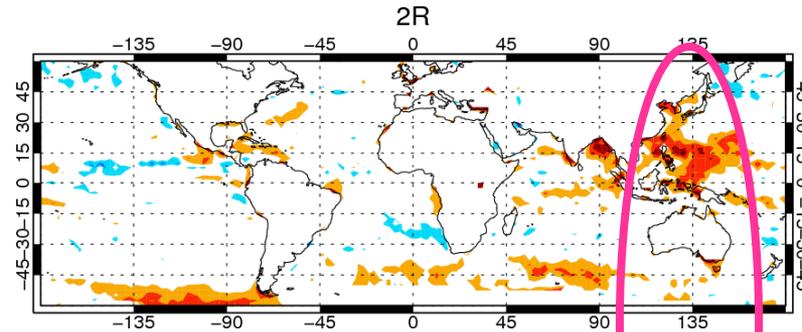


# Biases fixed: cloud overlap in the RTTOV-SCATT radiative transfer model

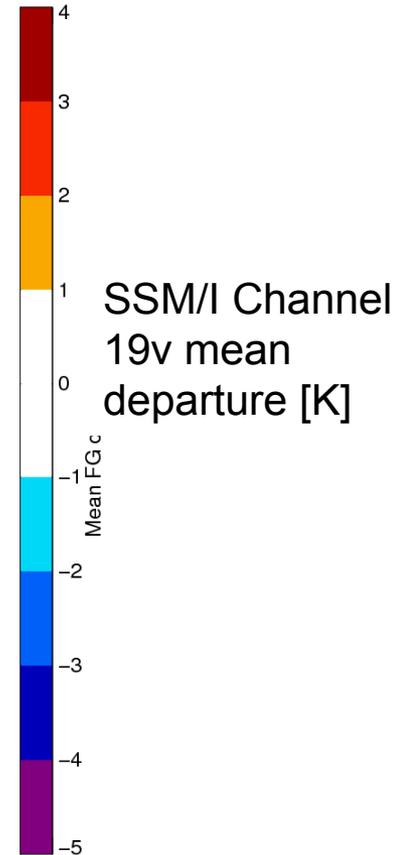
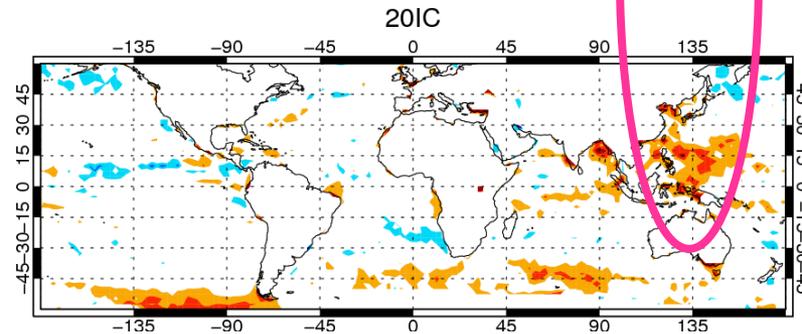
Original overlap



Revised overlap

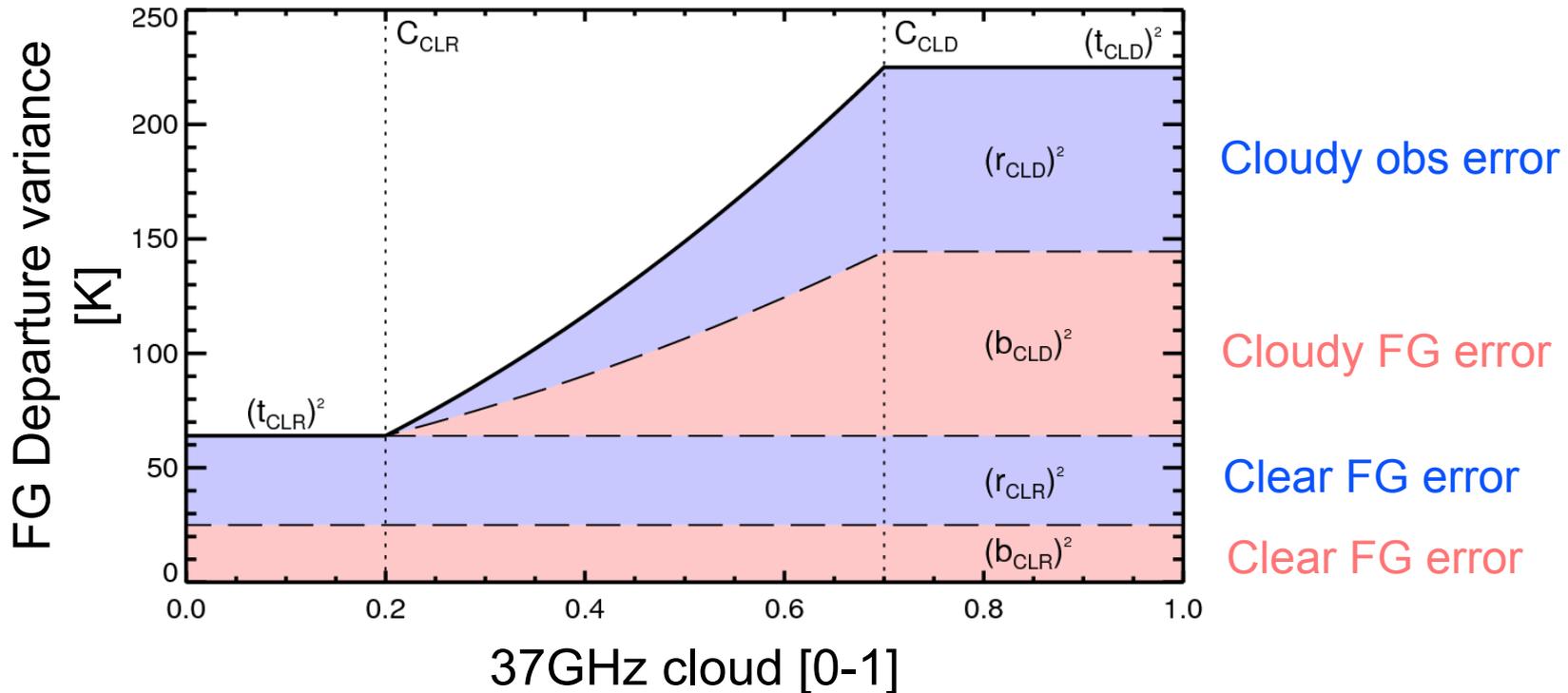


20 independent column reference

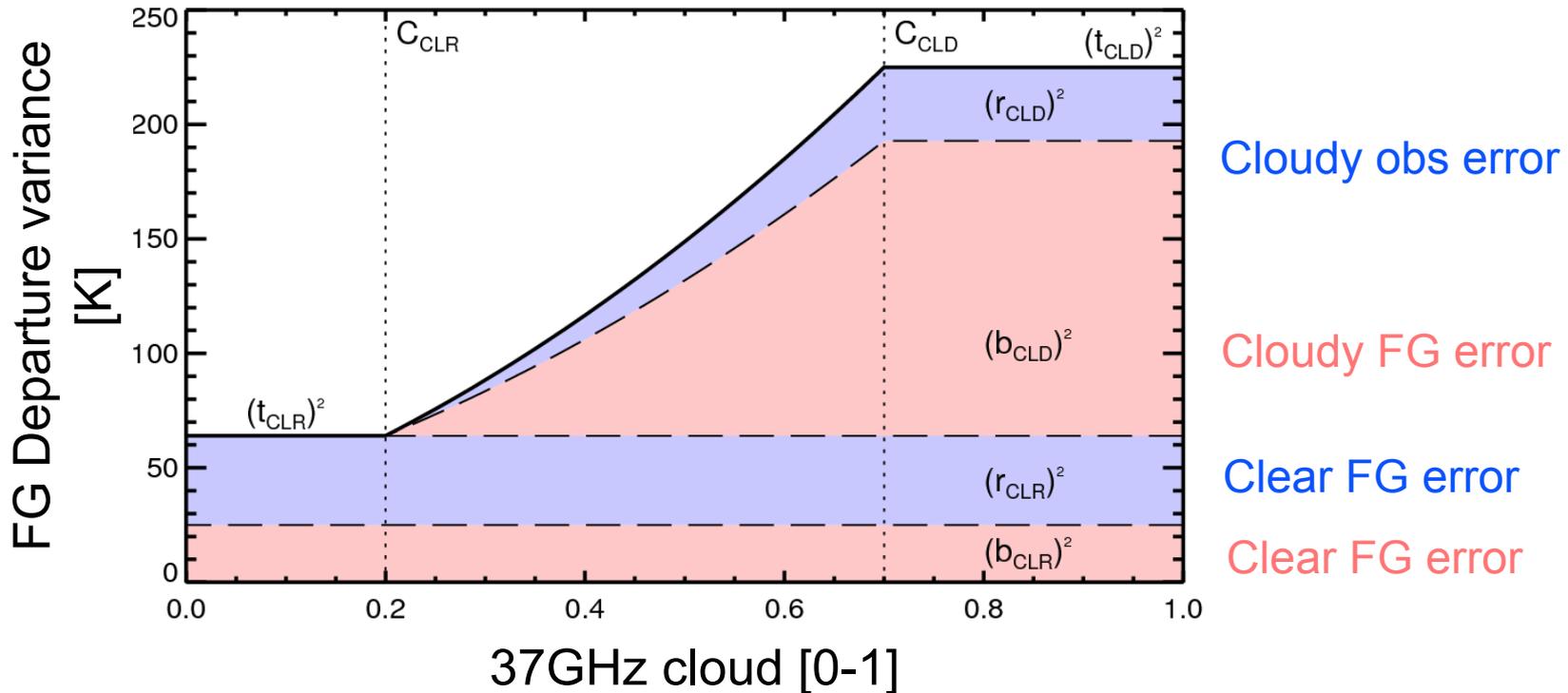


# Error tuning experiments

# Symmetric model for all-sky observation error

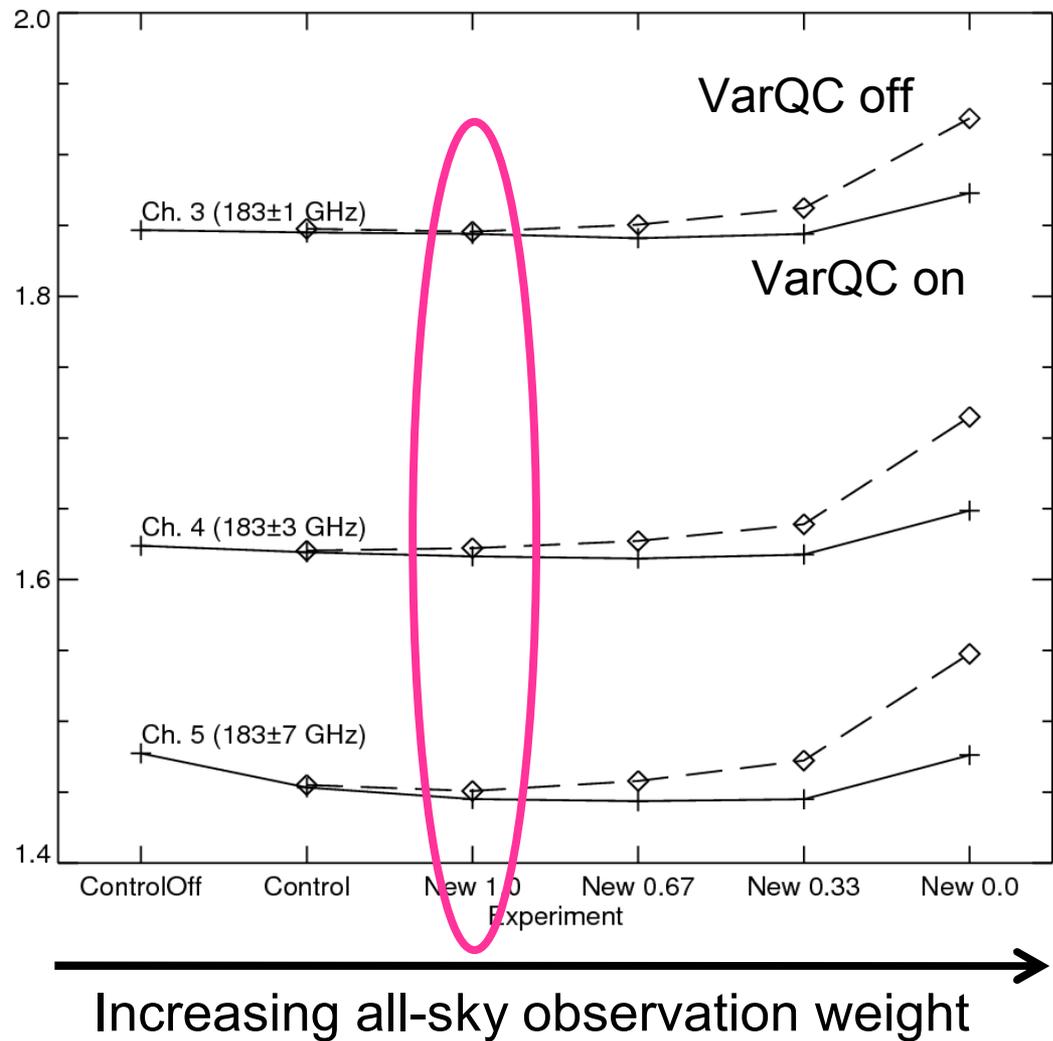


# Symmetric model for all-sky observation error

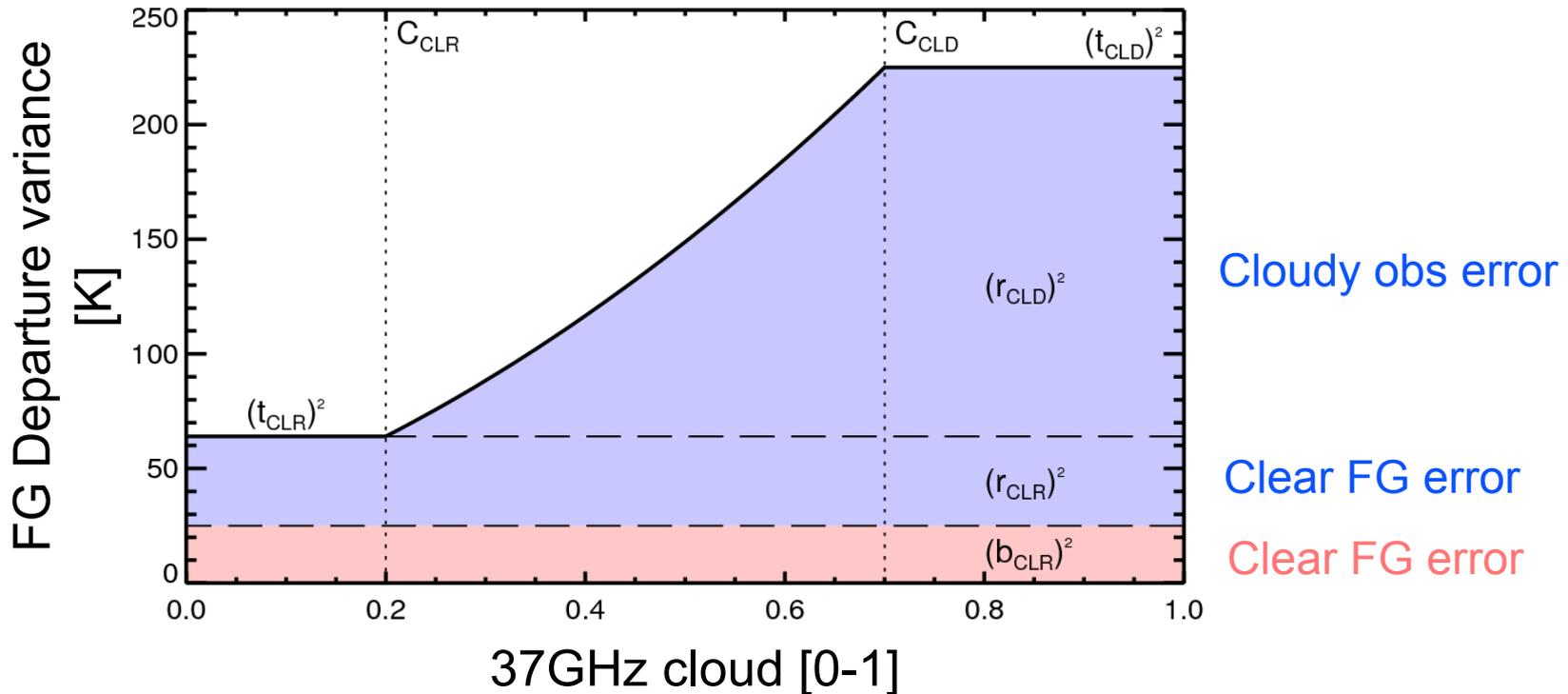


# All-sky observation error tuning

AMSU-B  
FG departure  
std. dev. [K]



# All-sky observation error in practice



# All-sky observation error after tuning experiments

- Channel 19v in cloudy areas:
  - FG departure standard deviation: 15 K
  - Observation error: 14.96 K
- In practice, ALL cloudy error is assigned as observation error. Why?
  - ECMWF system does not correctly represent background error covariances in cloudy areas?
  - Error correlations not considered – see Niels Bormann’s talk.
  - **Forecast model bias**

# Status

- Observation errors – *Stopgap solution*
  - Need to be symmetric (i.e. not causing sampling biases)
  - Symmetric approach for all-sky assimilation
  - Observation error being used to account for forecast model error!
- Quality control - *OK*
  - Threshold checks using symmetric model for FG departures
  - VarQC
- Gaussianity and linearity – *OK for now*
- Representativity – *Saved by very broad scales of model cloud*
- Model biases – *The real problem*
  - E.g. fronts, cold sectors
  - Correlated errors

# Recommendations

- Background errors

- Need to represent broad areas of uncertainty around fronts and clouds
- Ensemble methods should help

- Bias correction

- Predictors must be symmetric
- Refine current methods (e.g. better VarBC predictors)
- New methods to represent cloud and precipitation biases?

- Model biases

- Screen out observations that disagree with the model
- Improve the models
- Weak constraint 4D-Var
- Parameter estimation