A satellite image of a coastline, likely the Gulf of Mexico, showing a large, dense cluster of clouds over the ocean. The text is overlaid on the image in white boxes.

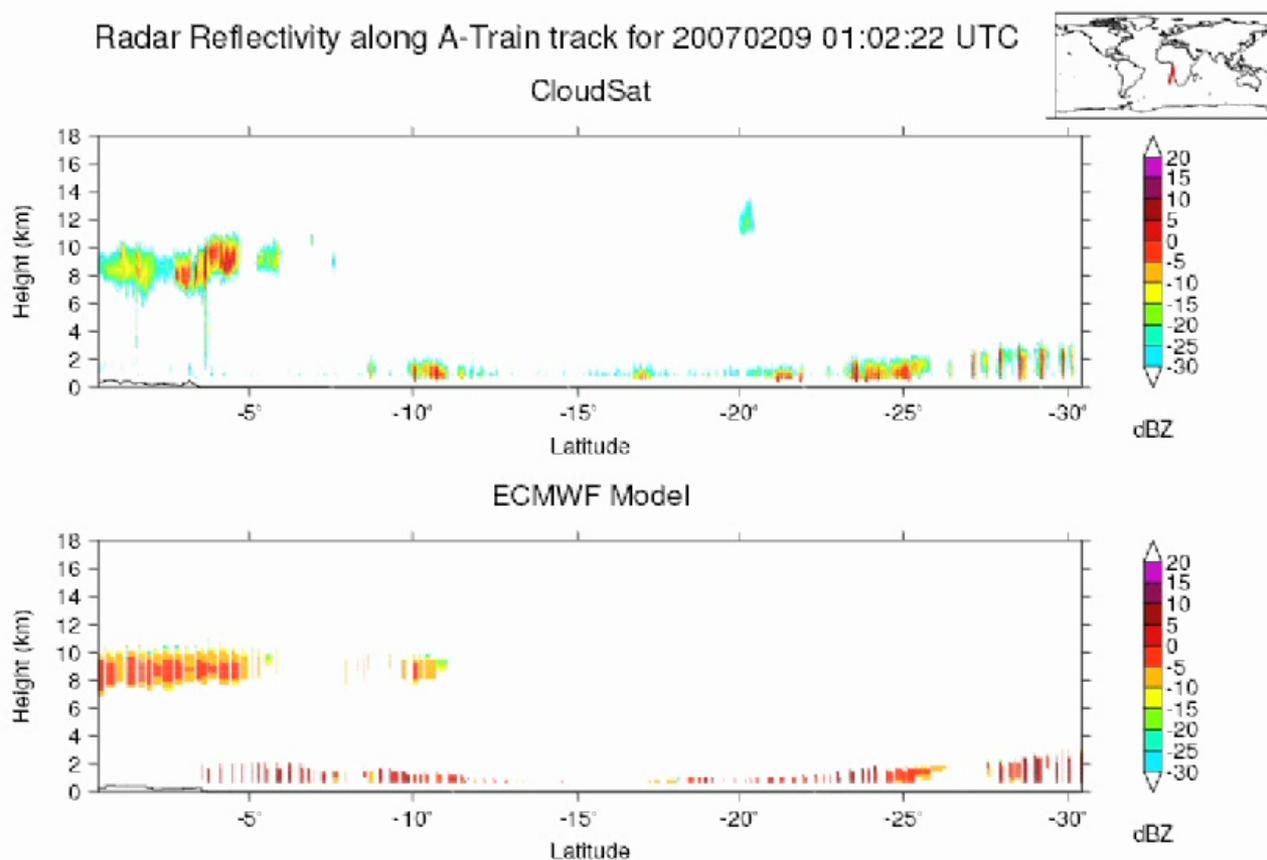
Diagnosing Model Systematic Error for Clouds and Precipitation

Richard Forbes (ECMWF)

With Thanks to Maike Ahlgrimm, Peter Bechtold, Martin Köhler and ECMWF colleagues, and Graeme Stephens (CSU), Julien Delanoë (Univ. Reading)

ECMWF Annual Seminar, Sep 2009

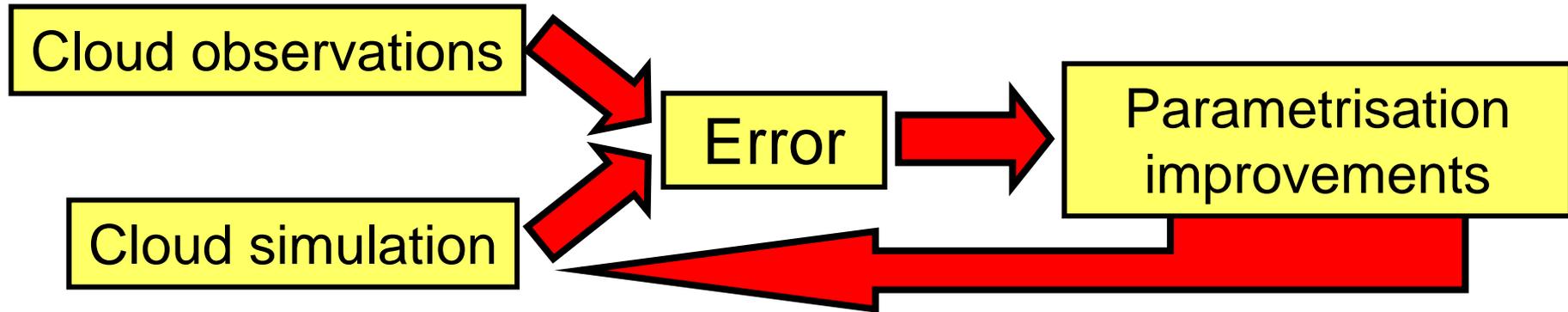
Diagnosing Model Systematic Error for Clouds and Precipitation



Richard Forbes (ECMWF)

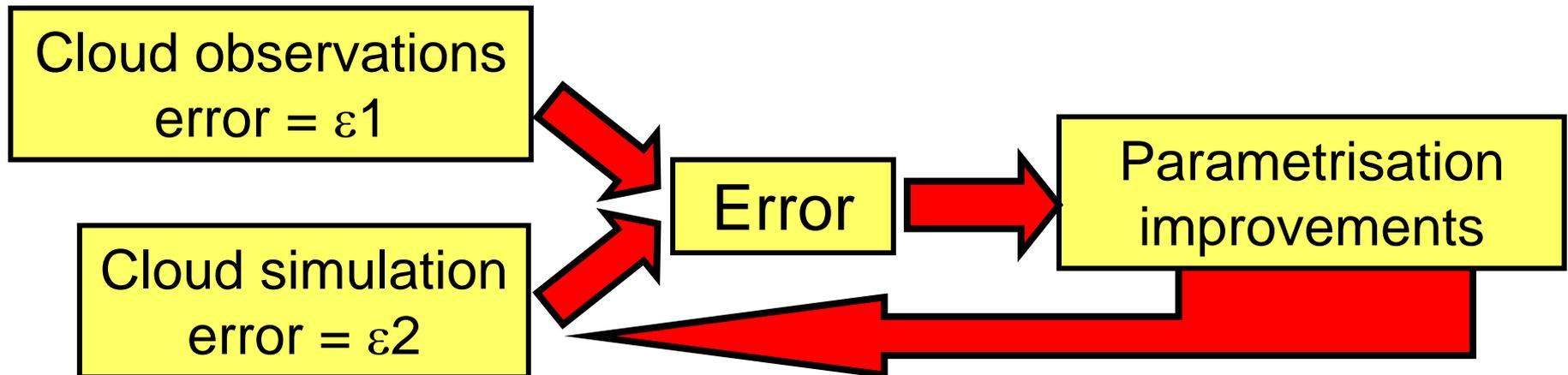
**With Thanks to Maïke Ahlgrimm and ECMWF colleagues, Robin Hogan
and Julien Delanoë (Univ. Reading), Graeme Stephens (CSU)**

Cloud Validation: The issues



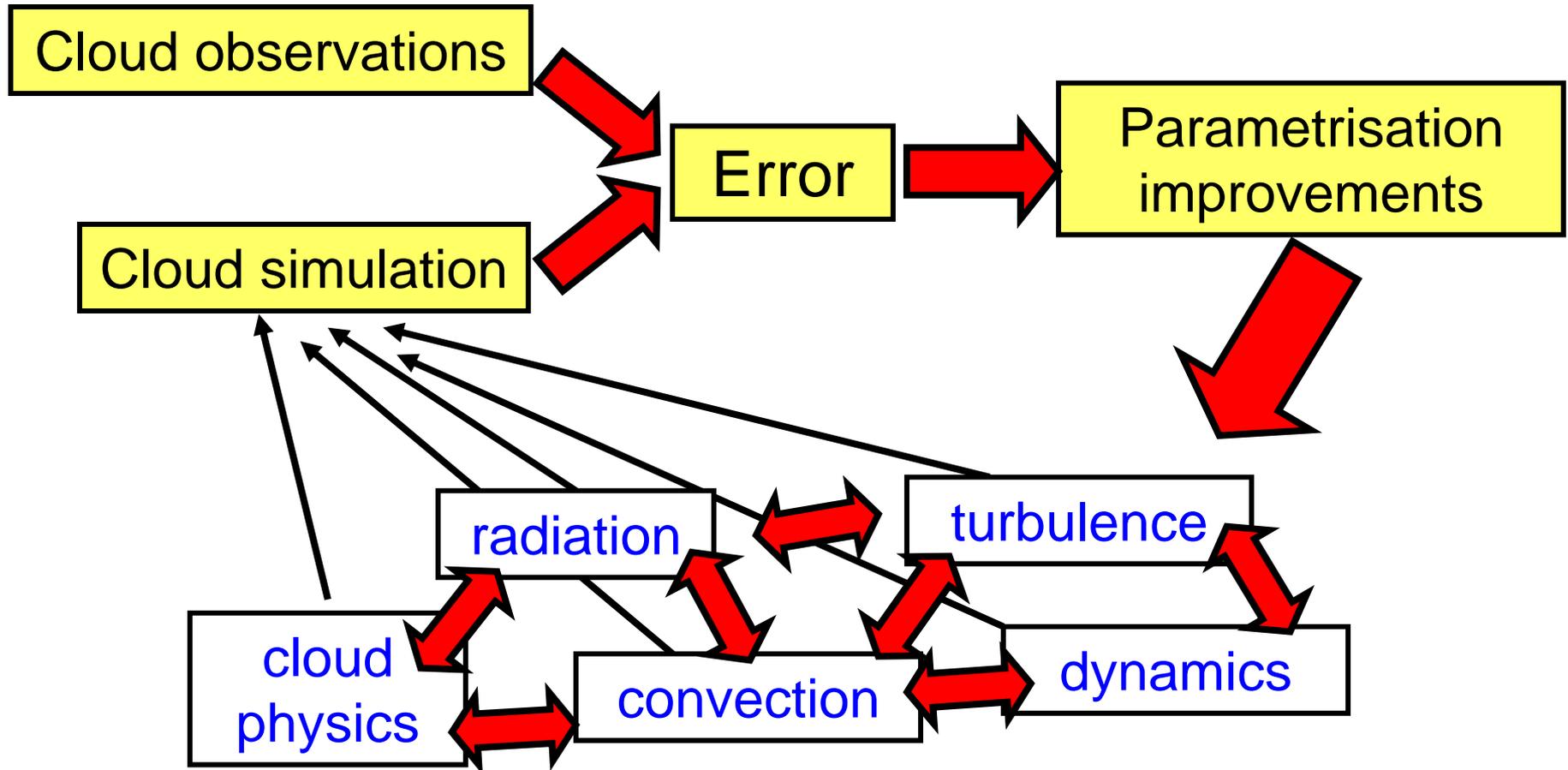
Sounds easy.....

- How much of the 'error' derives from observations?

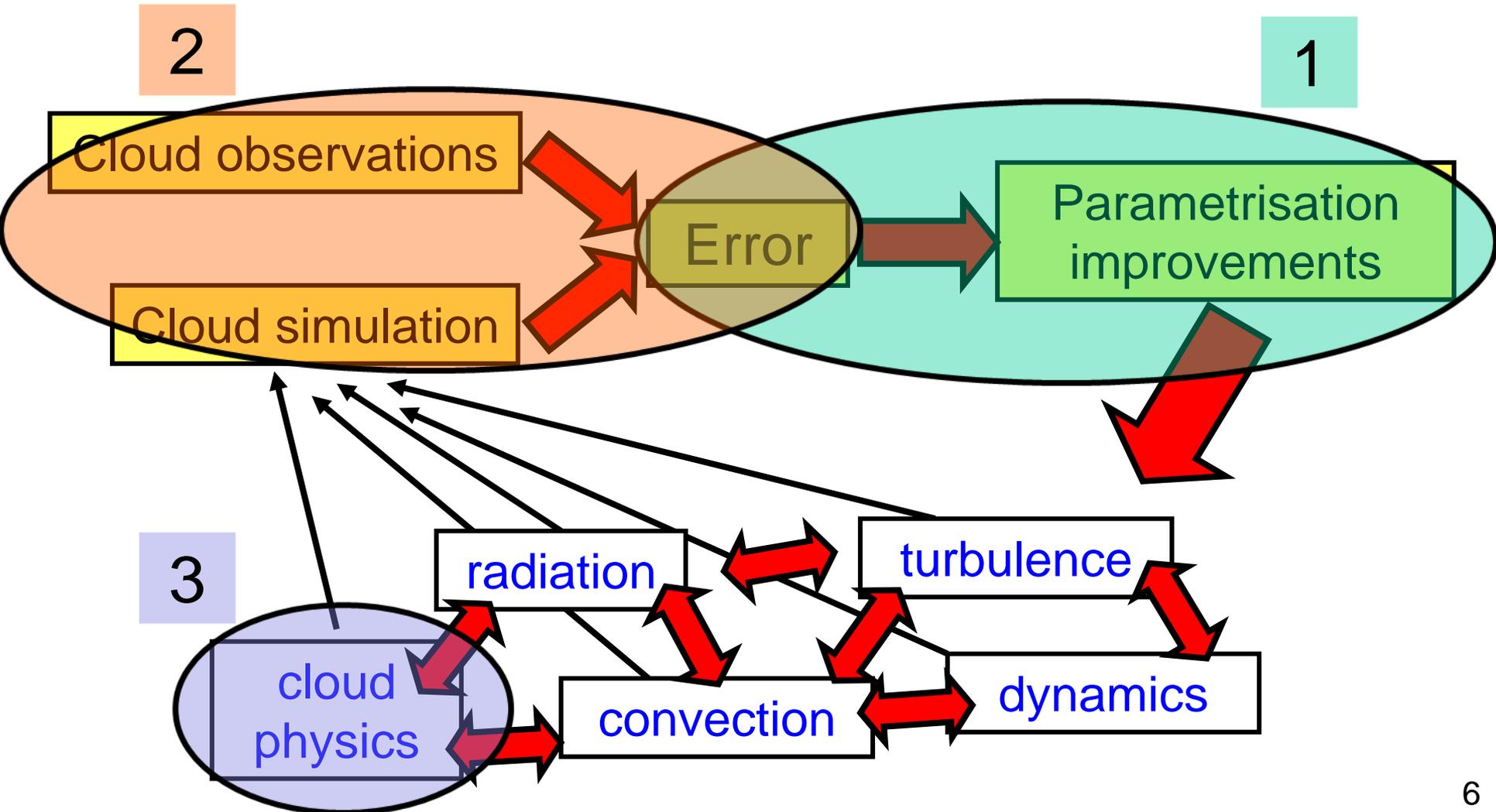


Cloud Validation: The problems

- Which Physics is responsible for the error?



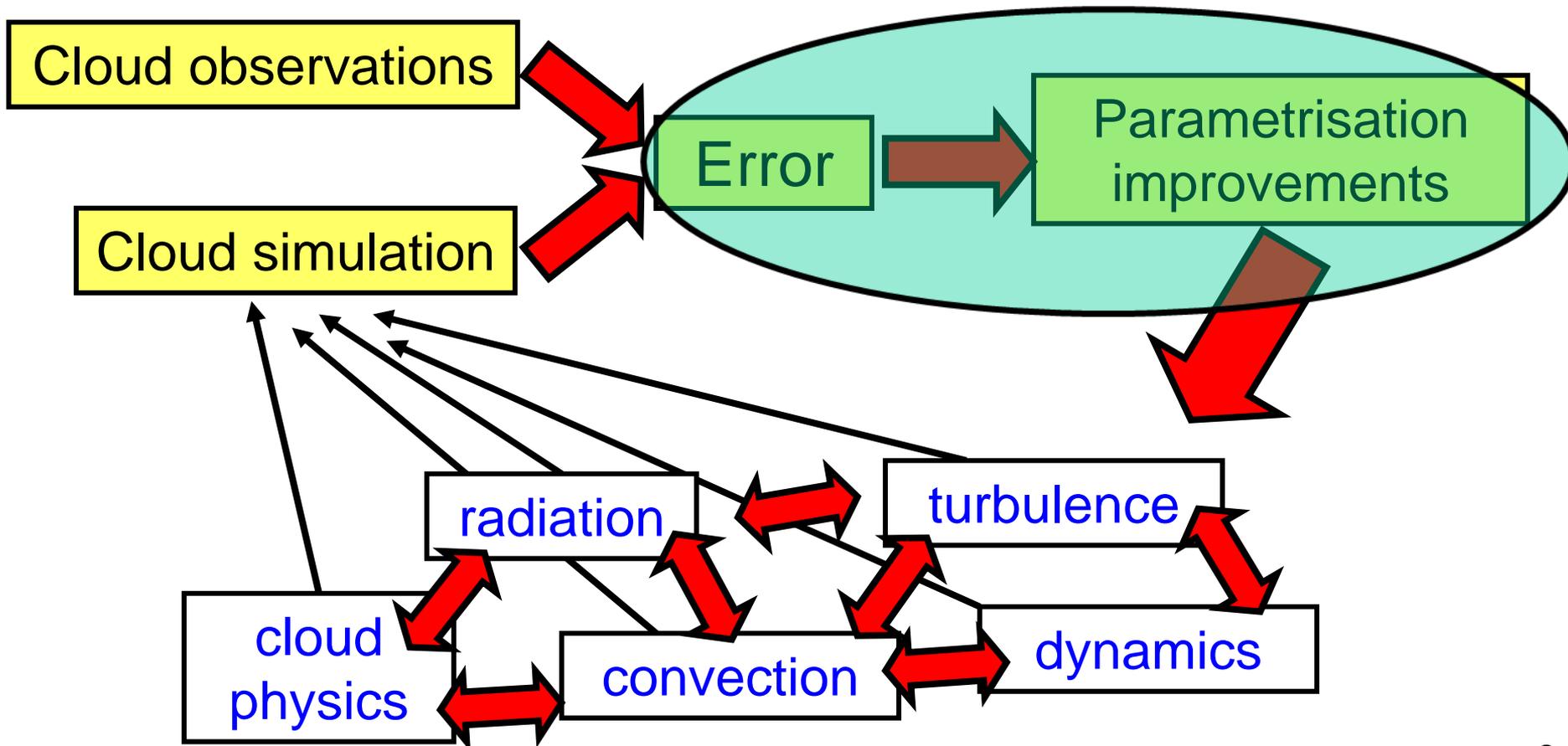
Cloud Validation: The problems



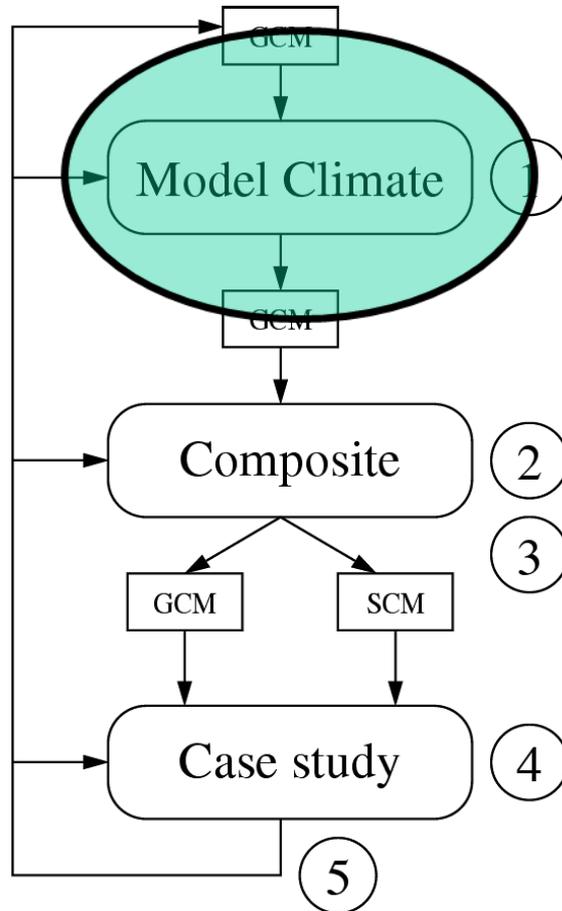
1. Methodology for diagnosing errors and improving parametrizations

Cloud Validation: The problems

1. Methodology



A strategy for cloud parametrization evaluation



Step 1 : identify major problem areas

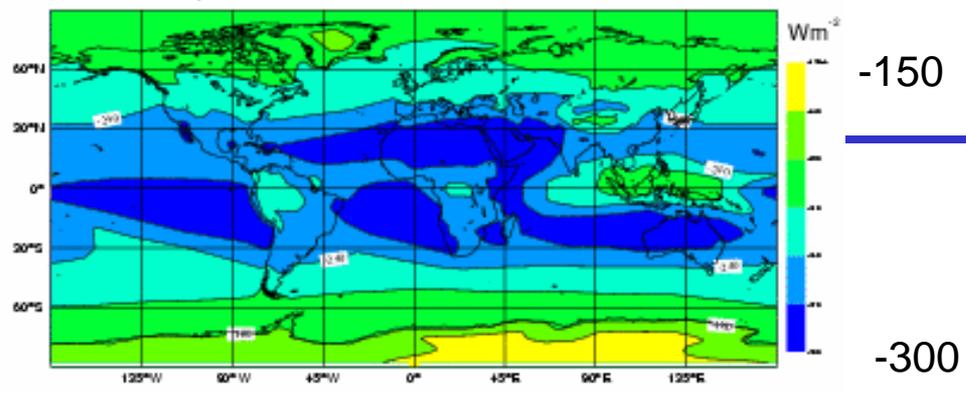
Step 2 : identify major problem regimes

Step 3 : identify typical case

Step 4 : identify detailed problems

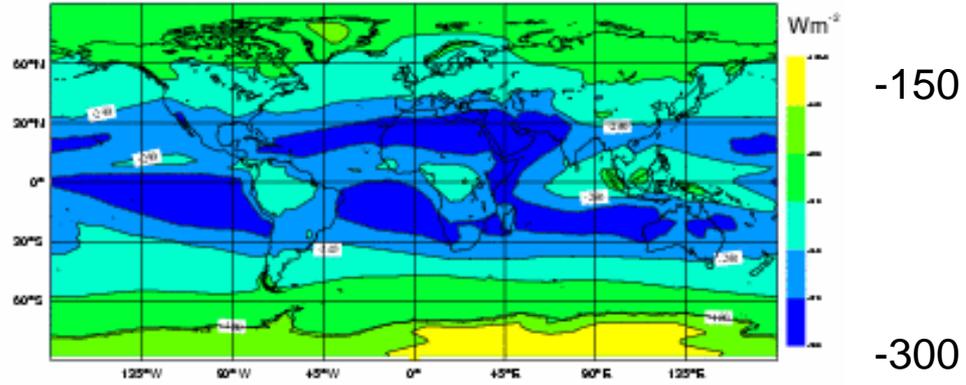
Step 5 : improve parametrization

TOA lw ezzn Sep 2000 rmon=12 nens=4 Global Mean: -241 50S-50N Mean: -253



Model
T159
L91

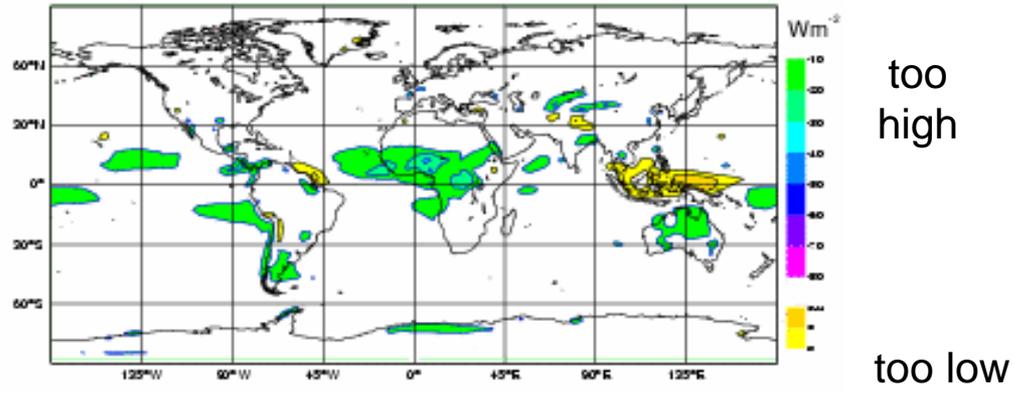
TOA lw CERES aqua Sep 2000 rmon=12 Global Mean: -239 50S-50N Mean: -250



CERES

Top-of-atmos
net LW
radiation

Difference ezzn - CERES aqua 50N-S Mean err -2.58 50N-S rms 7.17

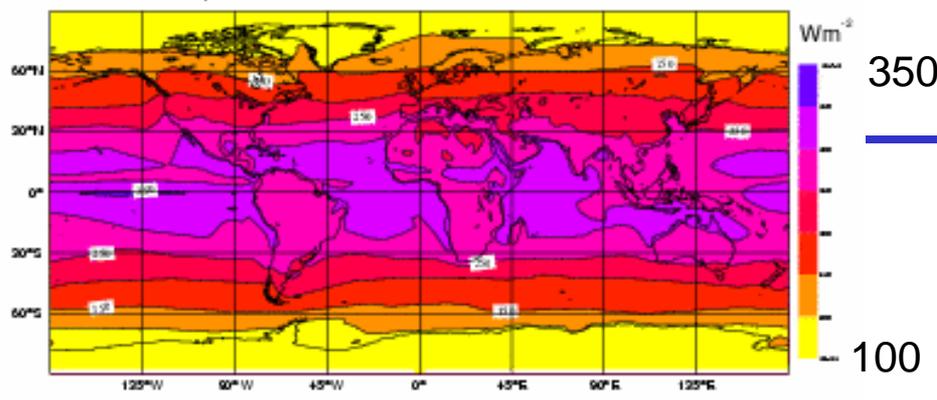


Difference

too low

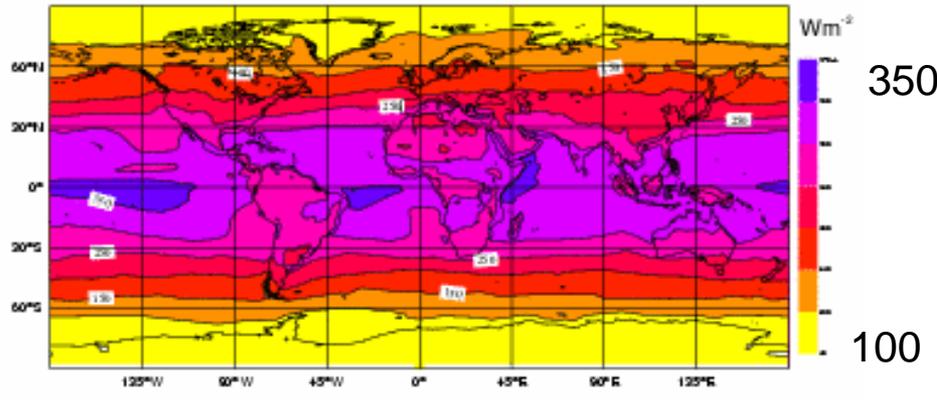
too high

TOA sw ezn Sep 2000 nmon=12 nens=4 Global Mean: 238 50S-50N Mean: 270



Model
T159
L91

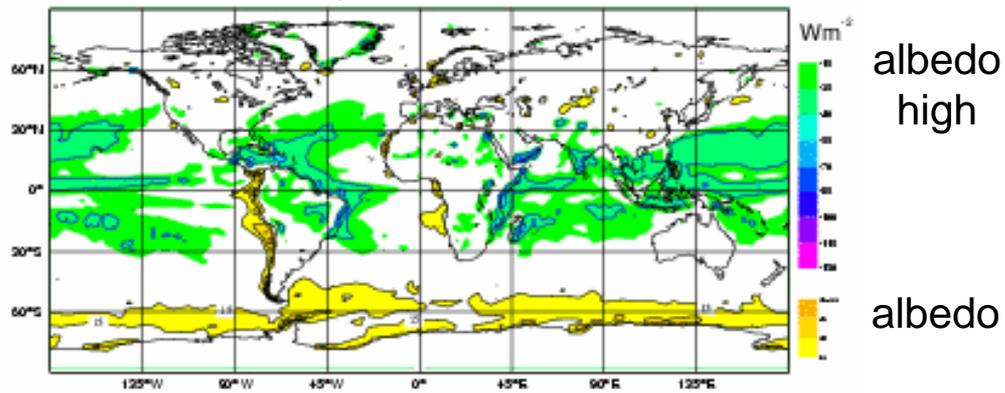
TOA sw CERES aqua Sep 2000 nmon=12 Global Mean: 244 50S-50N Mean: 280



CERES

Top-of-atmos
net SW
radiation

Difference ezn - CERES aqua 50N-S Mean err -10.2 50N-S rms 16.7

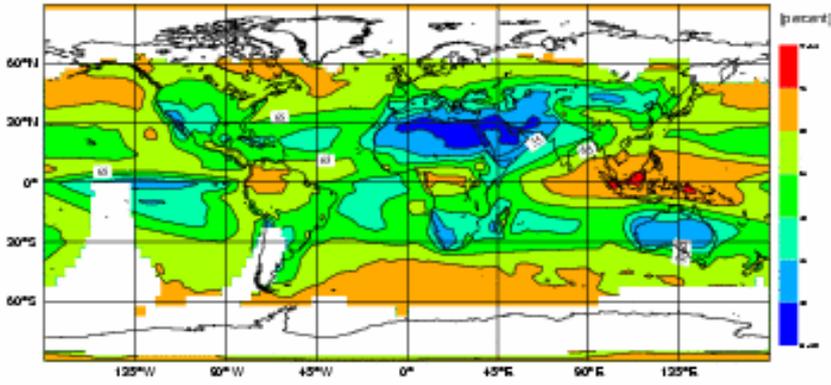


Difference

albedo
high

albedo
low

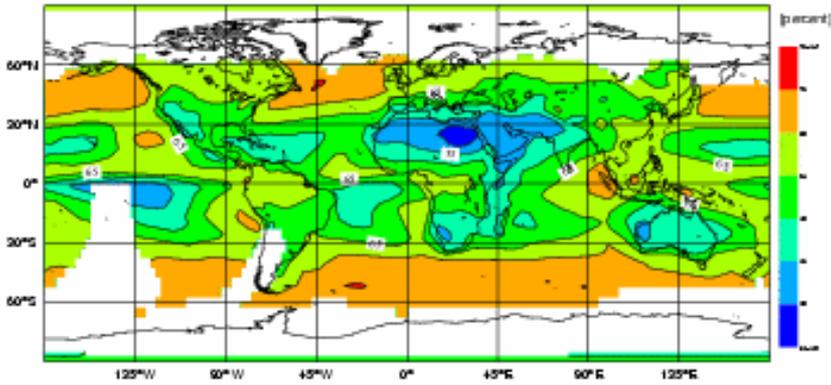
Total Cloud Cover ezzn Sep 2000 nmon=12 nens=4 Global Mean: 63.1 50N-S Mean: 61.1



80
10

Model
T159
L91

Total Cloud Cover ISCCP Sep 2000 nmon=12 50N-S Mean: 62.2

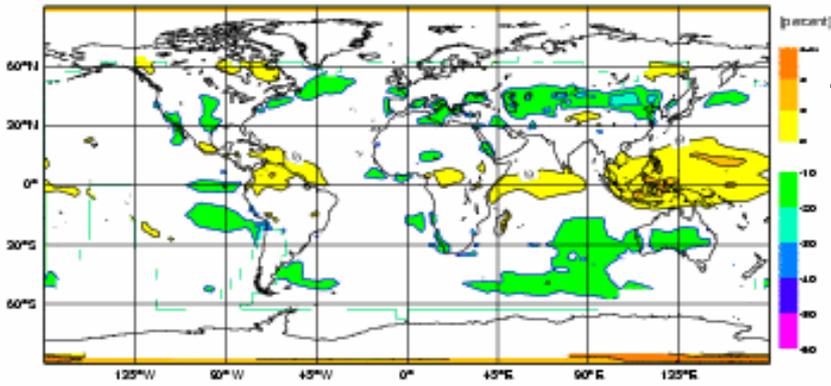


80
10

ISCCP

Total Cloud
Cover
(TCC)

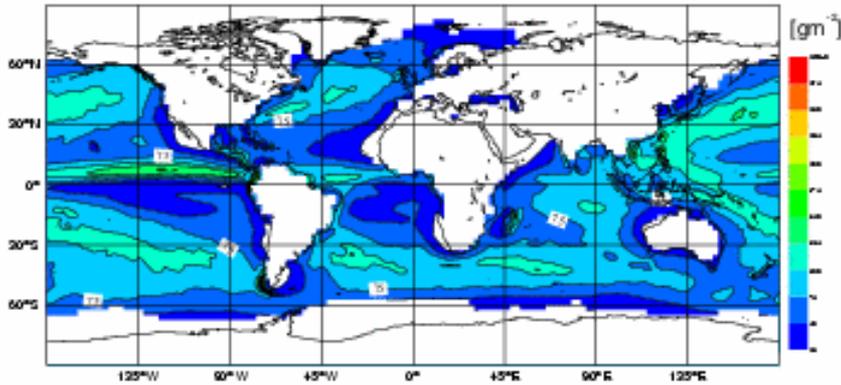
Difference ezzn - ISCCP 50N-S Mean err -1.1 50N-S rms 8.5



TCC high
TCC low

Difference

Liquid Water Path ezn Sep 2000 rmon=12 nens=4 Global Mean: 71.9

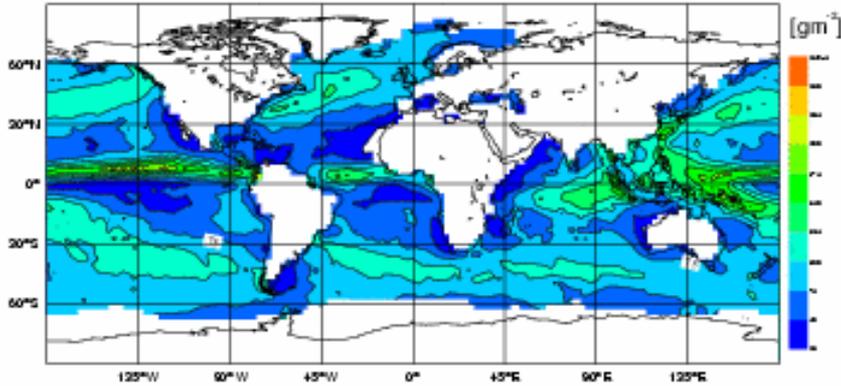


250

25

Model
T159
L91

Liquid Water Path SSMI Wentz V6 Sep 2000 rmon=12 Global Mean: 84.5



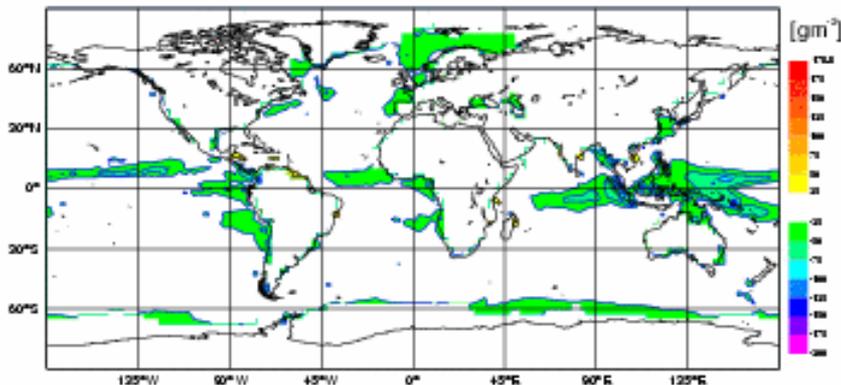
250

25

SSMI

Total Column
Liquid Water
(TCLW)

Difference ezn - SSMI Wentz V6 Global Mean err -12.5 RMS 21.4



high

low

Difference

- ECMWF Global Atmospheric Model (IFS)
 - T159 (125km) Monthly and Seasonal Prediction, (+Model Testing)
 - T399 (50km) Ensemble Prediction System (EPS)
 - T511 (40km) Previous NWP
 - T799 (25km) Current Deterministic Global NWP 10 day f/c
 - T1279 (16km) NWP (soon!)
 - 62 and 91 levels in use
- Need a model with a “climate” that is robust to resolution.

1. Choice and formulation of microphysical processes

- As resolution increases, the range of scales of dynamical forcing increases. Non-linear microphysical processes can respond differently.
- Parametrization schemes are based on time/space scale separation. As resolution increases, require change from diagnostic to prognostic variables.

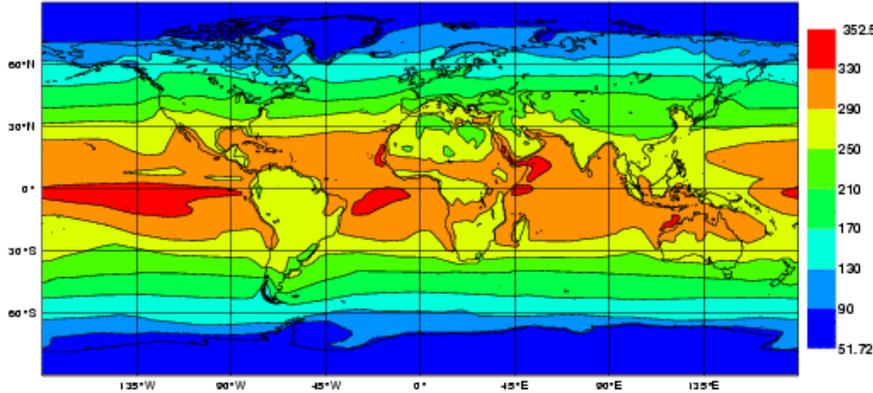
2. Representation of sub-gridscale inhomogeneities

3. Numerical techniques for efficient implementation

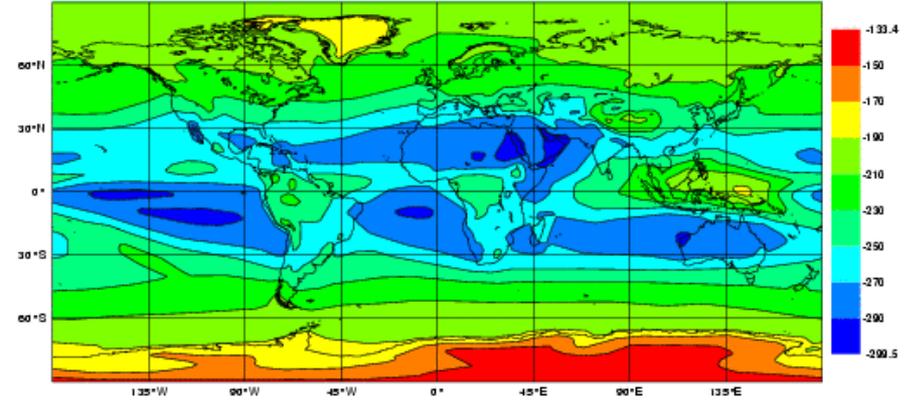
- Long timesteps used for computational efficiency.
- Explicit vs implicit formulations.

TOA Net Radiation (T511 vs T159)

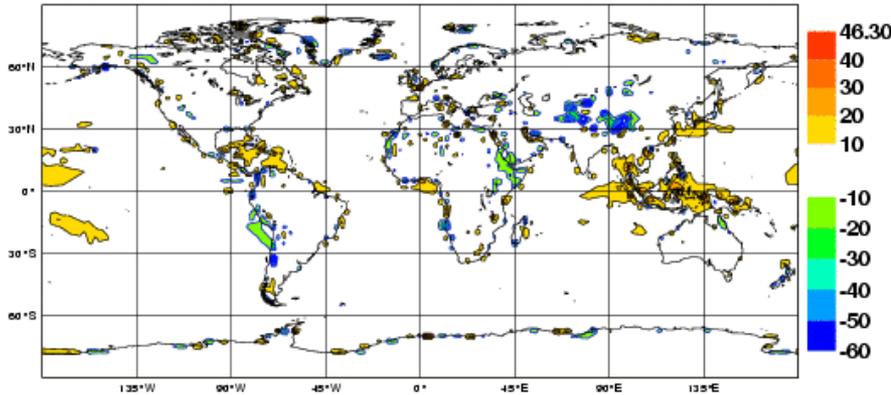
**Top solar radiation ([W m⁻² s]) exw9 200009 nmon=12 nens=4 Mean: 236.5



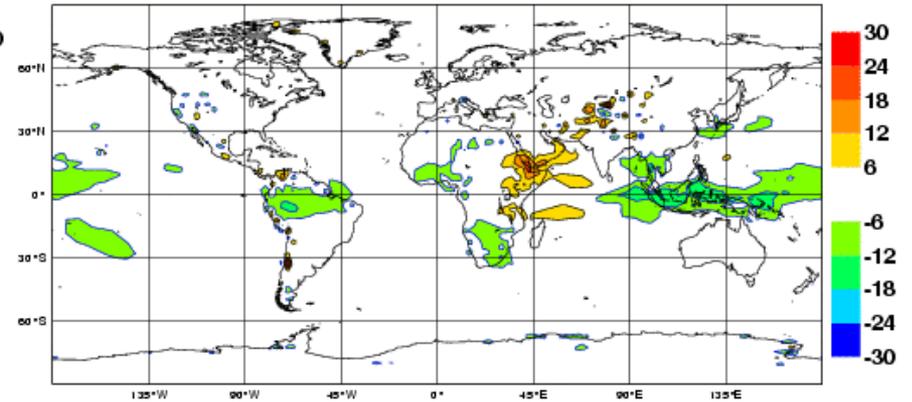
**Top thermal radiation ([W m⁻² s]) exw9 200009 nmon=12 nens=4 Mean: -241.7



**Top solar radiation ey0u-exw9 200009 nmon=12 nens=4 Diff: 1.52 Stdev: 6.616



**Top thermal radiation ey0u-exw9 200009 nmon=12 nens=4 Diff: -1.693 Stdev: 3.577



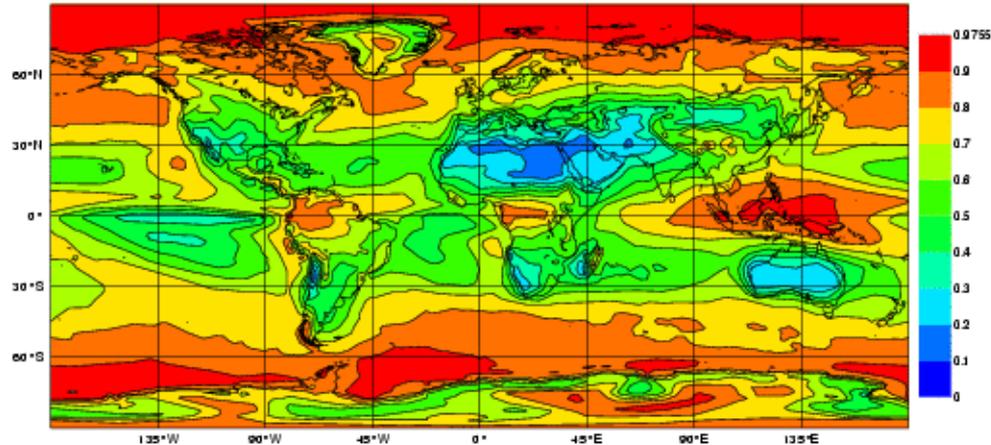
TOA Net SW

TOA Net LW

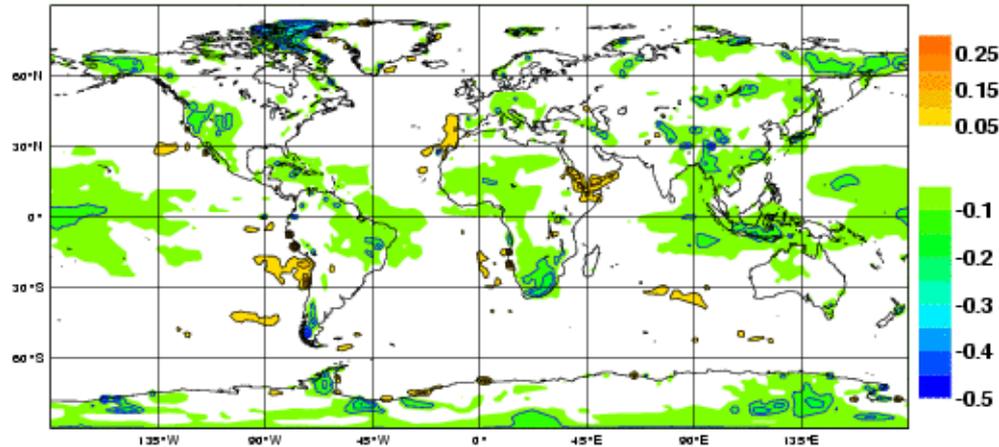
Sensitivity to resolution

Total Cloud Cover (T511 - T159)

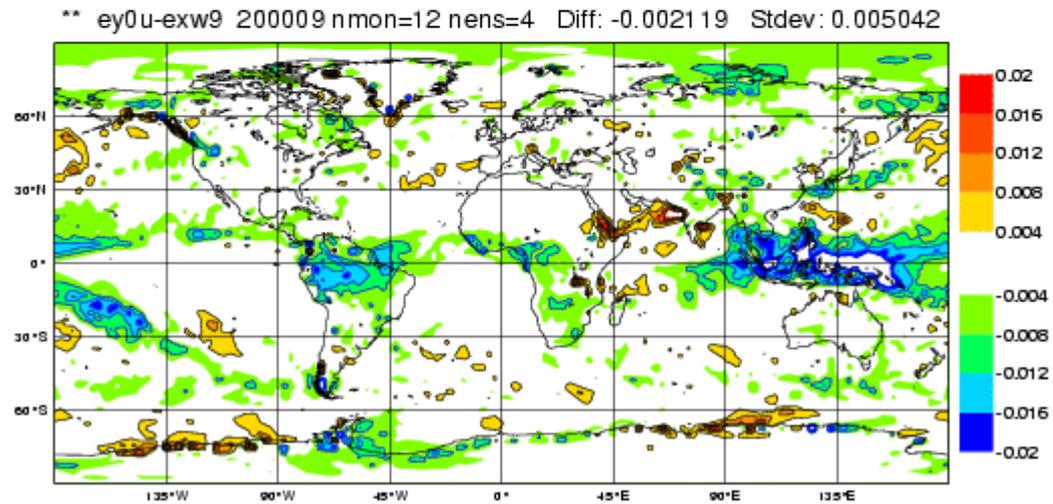
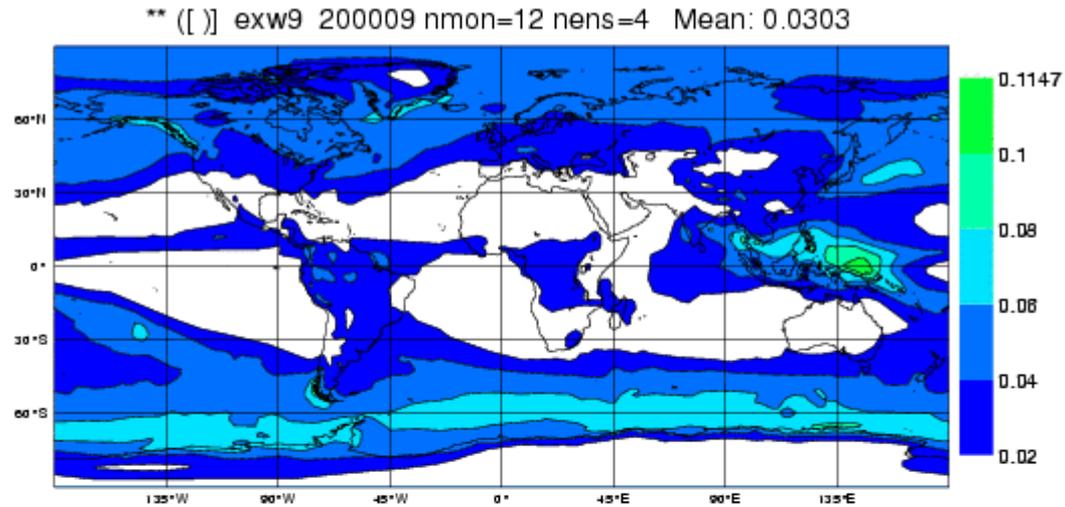
**Total cloud cover ([(0 - 1)]) exw9 200009 nmon=12 nens=4 Mean: 0.6603



**Total cloud cover ey0u-exw9 200009 nmon=12 nens=4 Diff: -0.01878 Stdev: 0.04294



Sensitivity to resolution Ice Water Content (T511 - T159)



Vertical resolution sensitivity

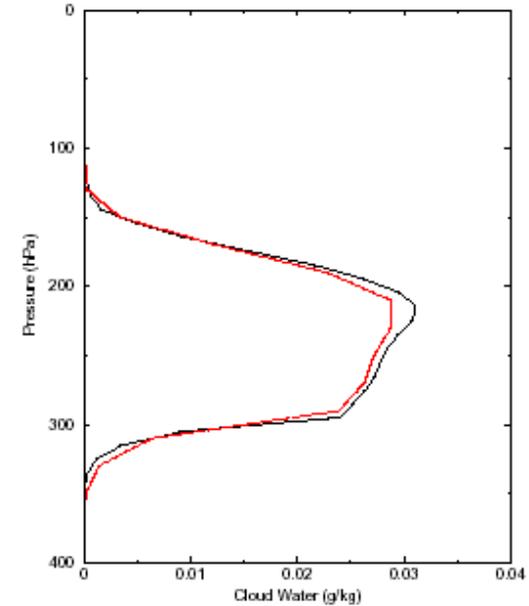
Ice Sedimentation

100 vs 50
layer resolution

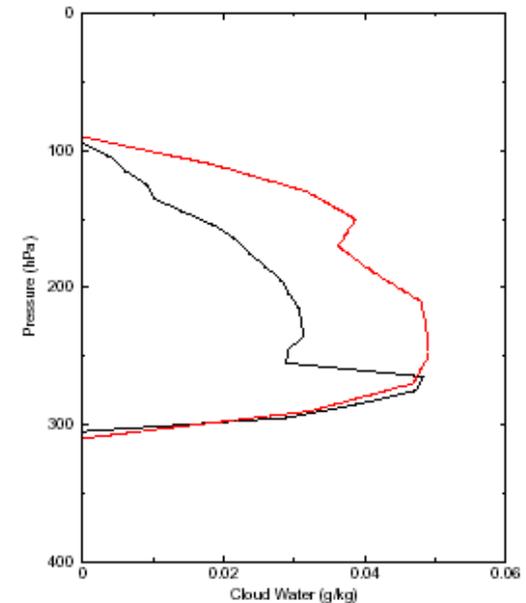
- Forward-in-time upstream implicit solver.
- Small sensitivity to vertical resolution / timestep.

- At earlier cycles, the problem was **much** worse.
- Caused by the “exact” solver of Tiedtke in combination with ice sedimentation acting as a proxy for autoconversion if ice fell into clear sky.

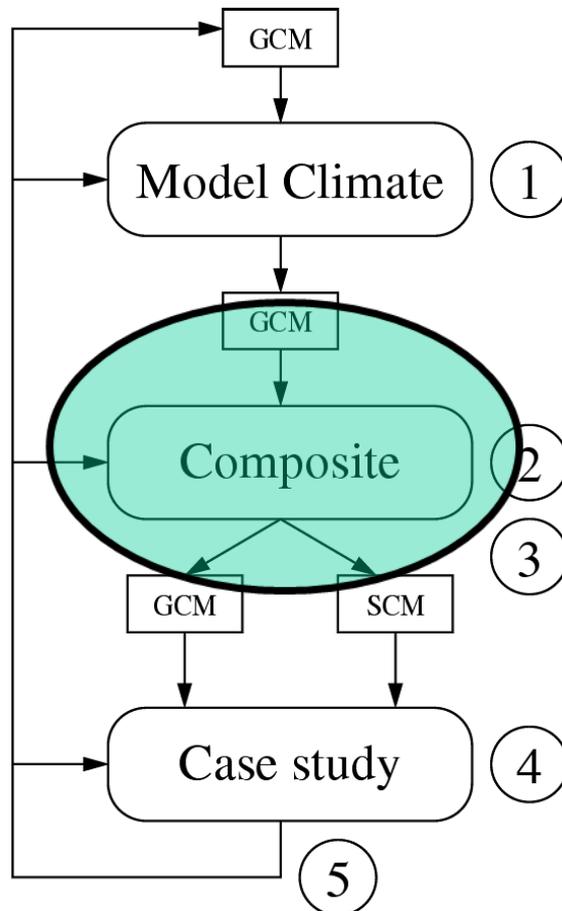
30r2 Scheme



29r1 Scheme



A strategy for cloud parametrization evaluation



Step 1 : identify major problem areas

Step 2 : identify major problem regimes

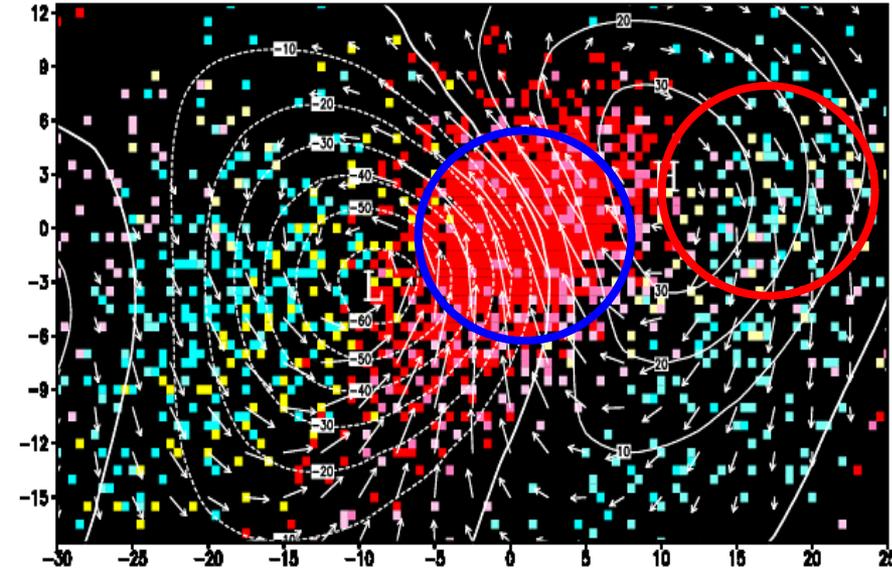
Step 3 : identify typical case

Step 4 : identify detailed problems

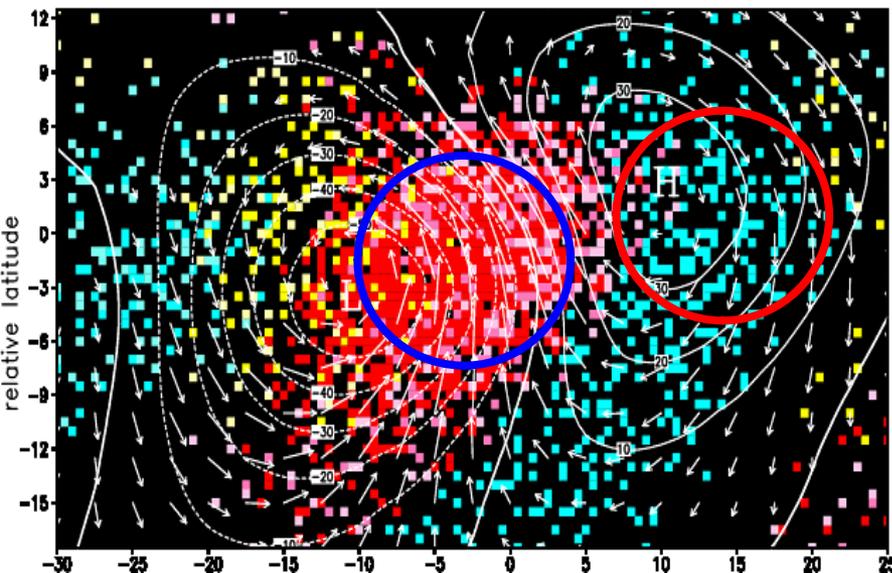
Step 5 : improve parametrization

- We want to isolate the sources of error. Focus on particular phenomena/regimes, e.g.
 - Extra tropical cyclones
 - Stratocumulus regions
- An individual case may not be conclusive: Is it typical?
- On the other hand general statistics may swamp this kind of system
- Can use compositing technique (extra-tropical cyclones)
- Focus on distinct regimes if can isolate (SCu, Trade Cumulus)

ISCCP clouds



ECMWF clouds



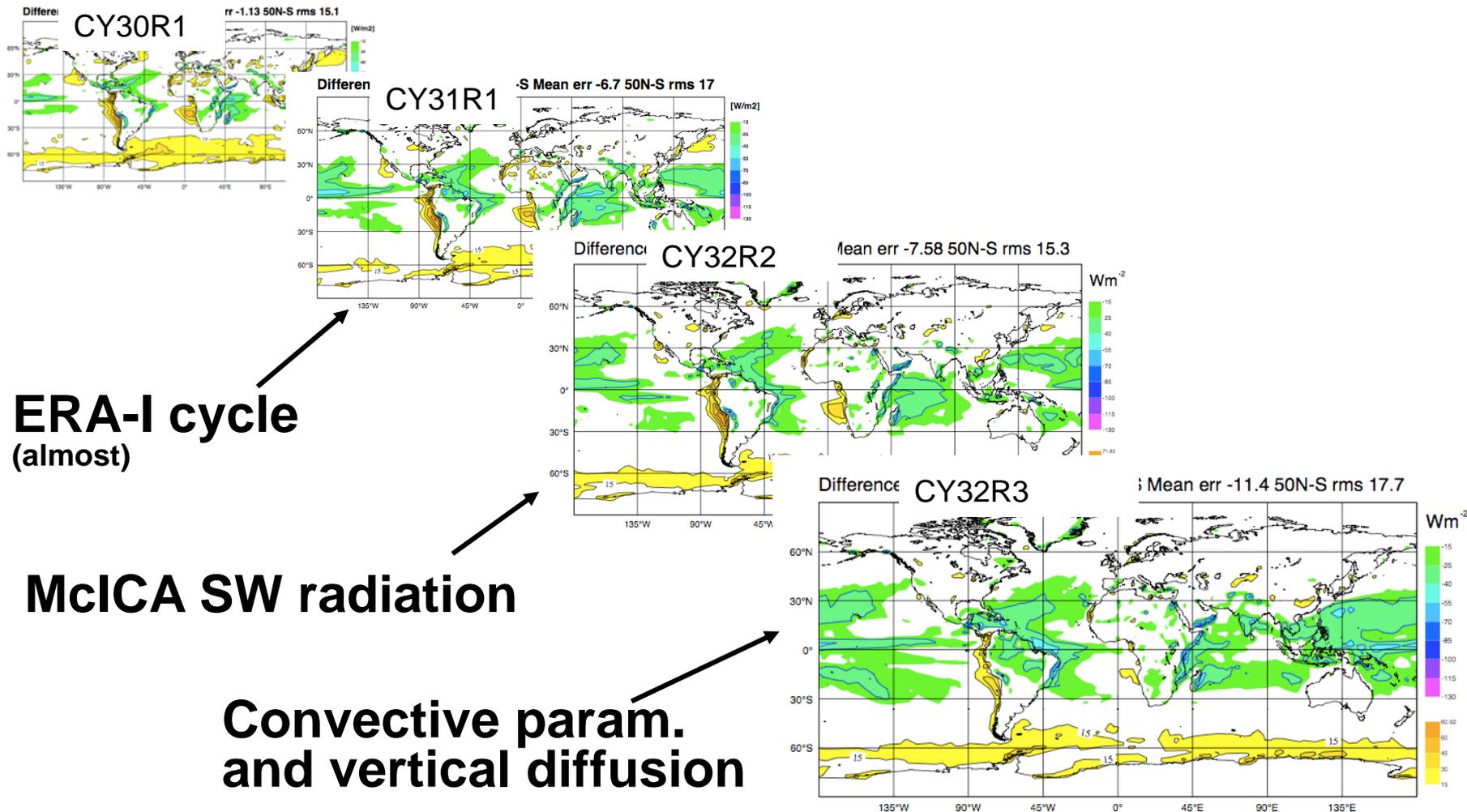
Overlay about 1000 cyclones,
defined about a location of
maximum optical thickness

Plot predominant cloud types
by looking at anomalies from
5-day average

- High Clouds too thin
- Low clouds too thick

High tops=Red, Mid tops=Yellow, Low tops=Blue

Model Climate: Regime dependent error?



ERA-I cycle
(almost)

McICA SW radiation

Convective param.
and vertical diffusion

TOA net SW radiation vs. CERES:

Too much reflectance from TCu, not enough from Sc

Maik
Ahlgrimm

Does the model have “correct” trade cumulus cloudiness?

Three aspects:

Cloud amount
when present
(AWP)

helps identify
cloud type



Cloud frequency
of occurrence
(FOO)

with AWP gives
total cloud cover

Radiative
properties

radiative balance
ultimately drives
the system

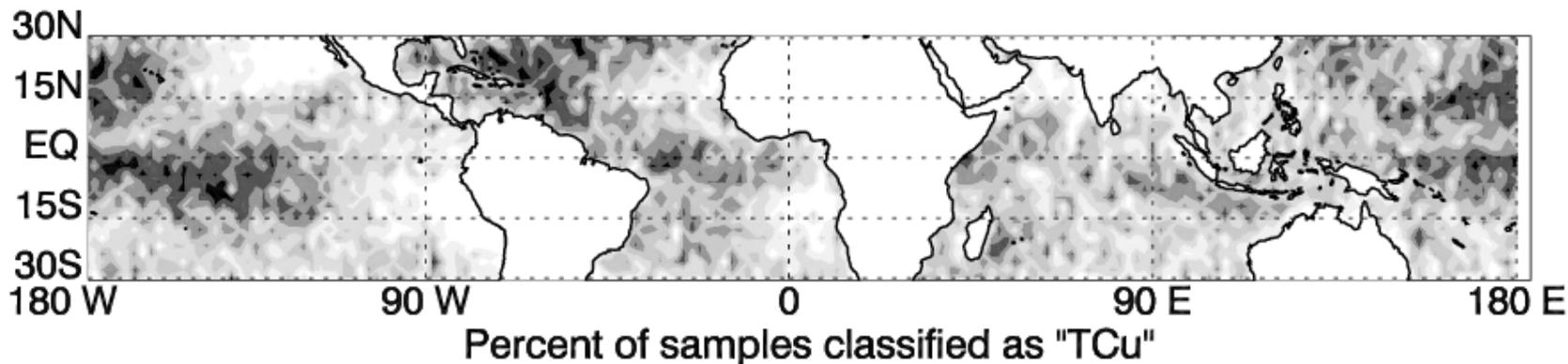
Maike Ahlgrimm

Identify cloud samples as:

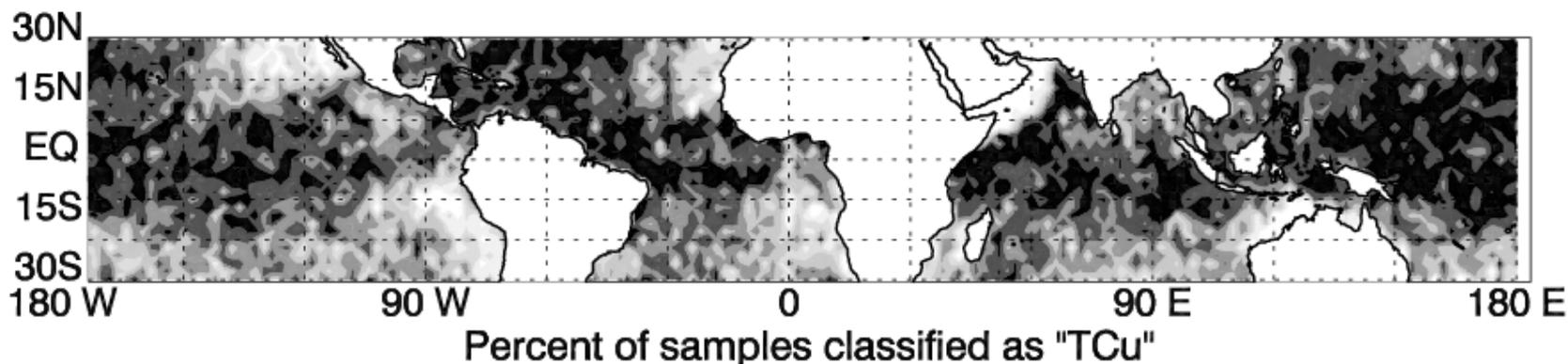
- with less than 50% cloud fraction
- cloud top below 4km
- over ocean
- between 30S and 30N

TCu frequency of occurrence (FOO)

CALIPSO frequency of occurrence of TCu samples 46.5%



CY31R1 frequency of occurrence of TCu samples 70.8%



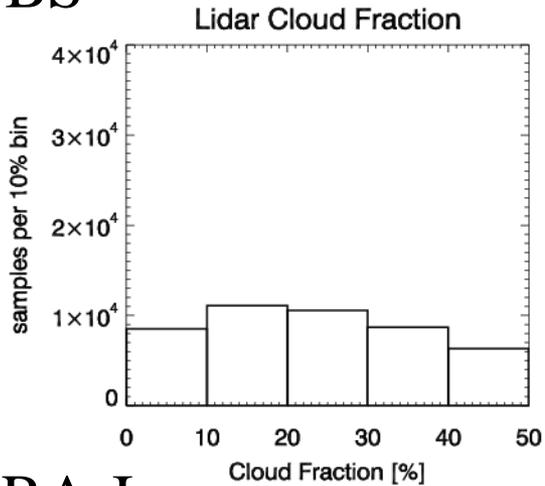
0 14 28 42 57 71 85 100

Model has TCu more frequently than observed

Maike Ahlgrimm

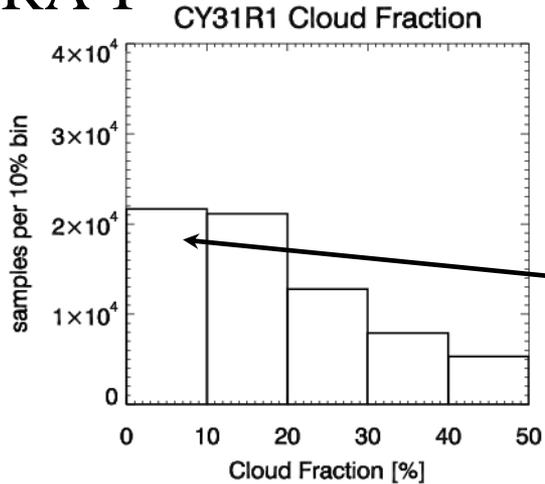
Cloud amount when present (AWP)

OBS



Cloud fraction is subject to representativity error. Observations have not been corrected!

ERA-I



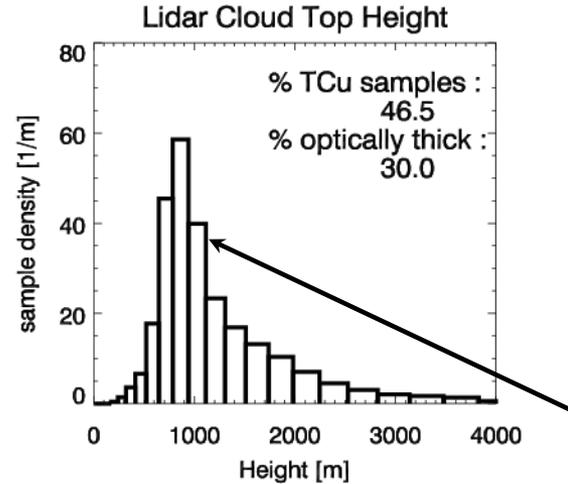
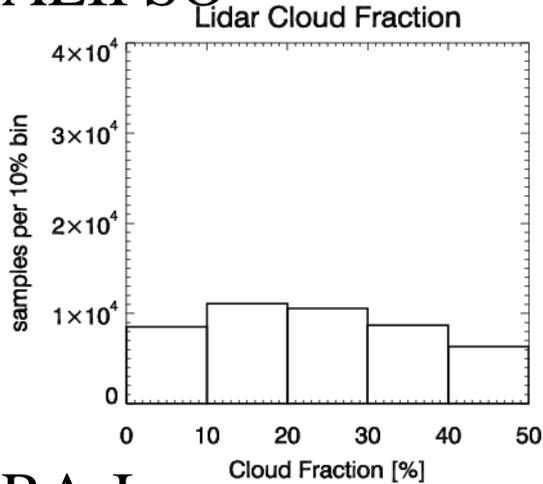
Most of the additional TCu samples have very small cloud fractions

Cloud top height

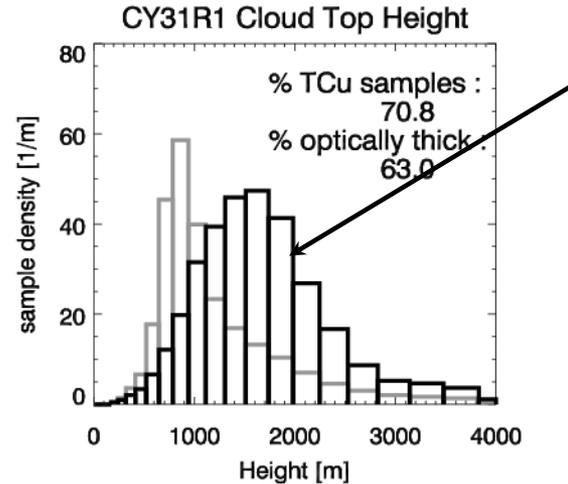
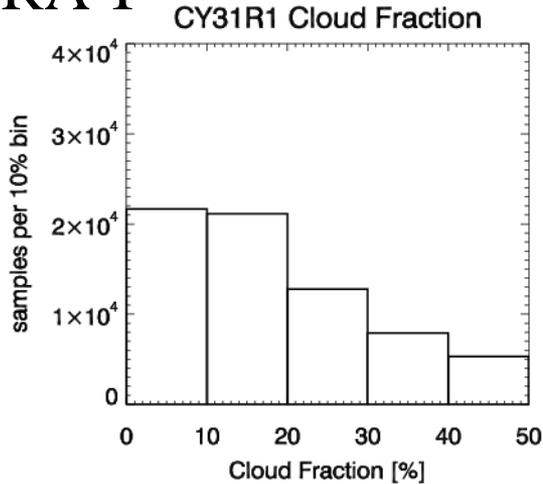
Skewed distribution

with low peak:
Majority of TCu clouds
are very shallow, few
grow deeper

CALIPSO

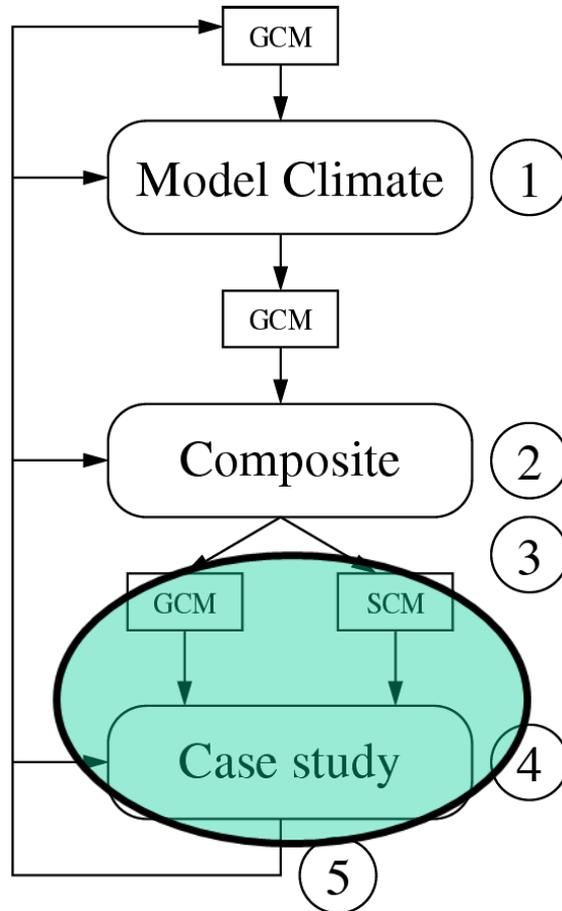


ERA-I



Model clouds have
higher cloud tops
than observed

A strategy for cloud parametrization evaluation



Step 1 : identify major problem areas

Step 2 : identify major problem regimes

Step 3 : identify typical case

Step 4 : identify detailed problems

Step 5 : improve parametrization

GCSS - GEWEX Cloud System Study

PARAMETERISATION
GCMS - SCMS



Diagnosing Cloud Error, Forbes
ECMWF Seminar 2009

CRMs

OBSERVATIONS

(Moncrieff et al. Bull. AMS 97)

Step 1

Use observations to evaluate parameterizations of subgrid-scale processes in a CRM

Step 2

Evaluate CRM results against observational datasets

Step 3

Use CRM to simulate precipitating cloud systems forced by large-scale observations

Step 4

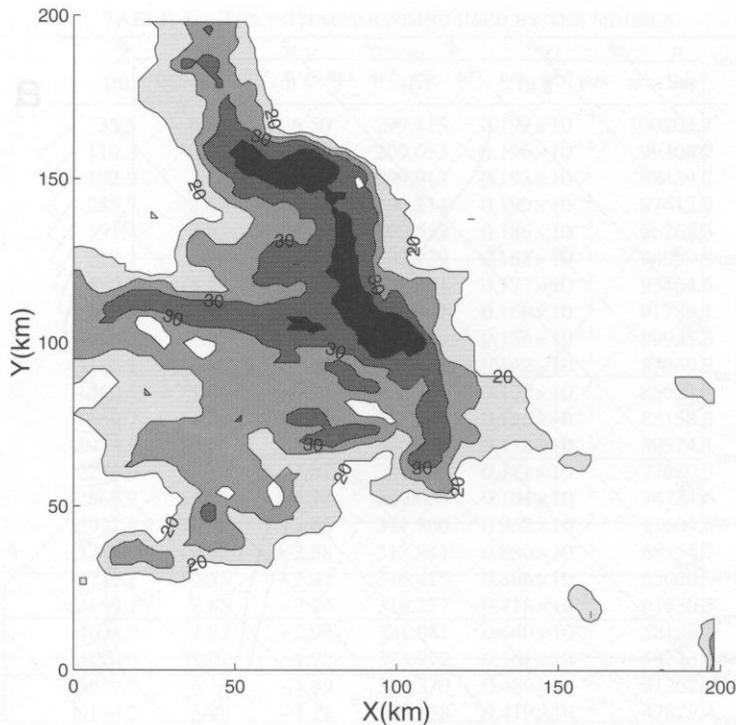
Evaluate and improve SCMs by comparing to observations and CRM diagnostics

GCSS: Validation of CRMs

Redelsperger et al QJRMS 2000

SQUALL LINE SIMULATIONS

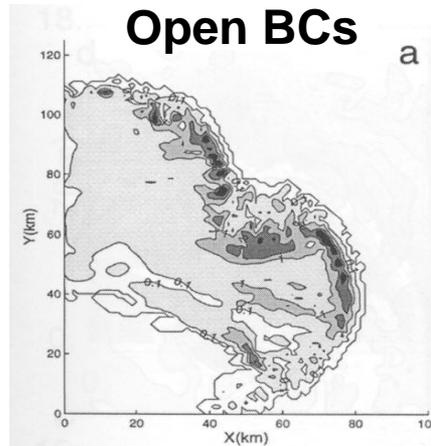
Observations - Radar



Conclude that only 3D models with ice and open BCs reproduce structure well

Simulations from different models (total hydrometeor content)

Open BCs a



GCSS: Comparison of many SCMs with a CRM



Bechtold et al QJRMS 2000 SQUALL LINE SIMULATIONS

Diagnosing Cloud Error, Forbes
ECMWF Seminar 2009

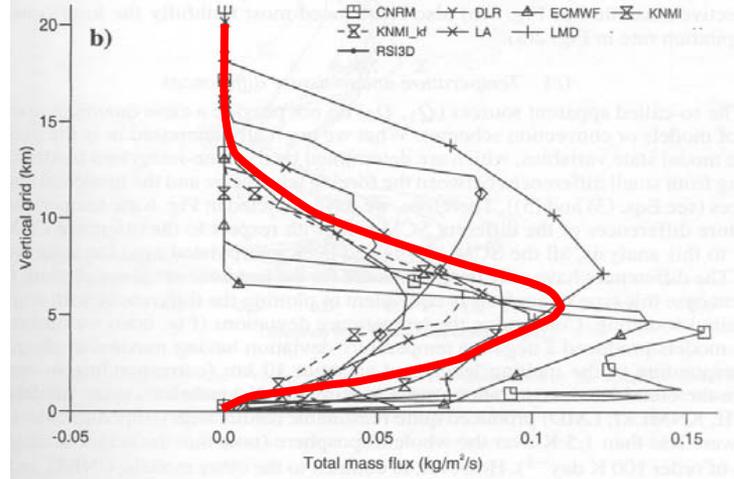
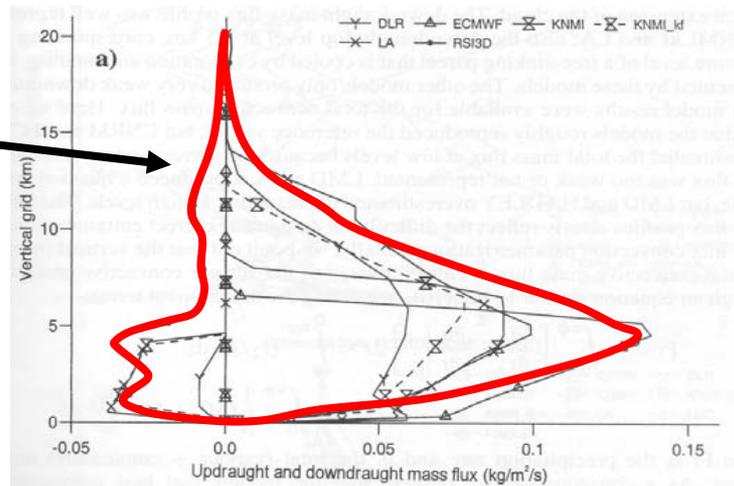
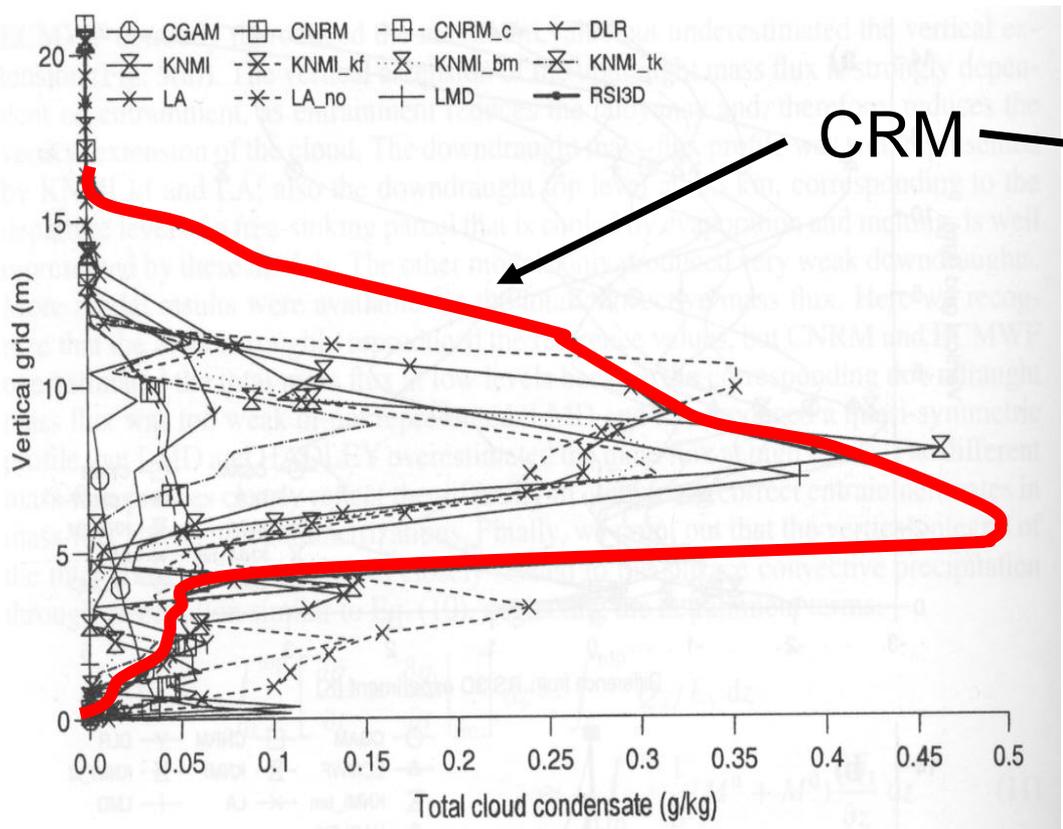
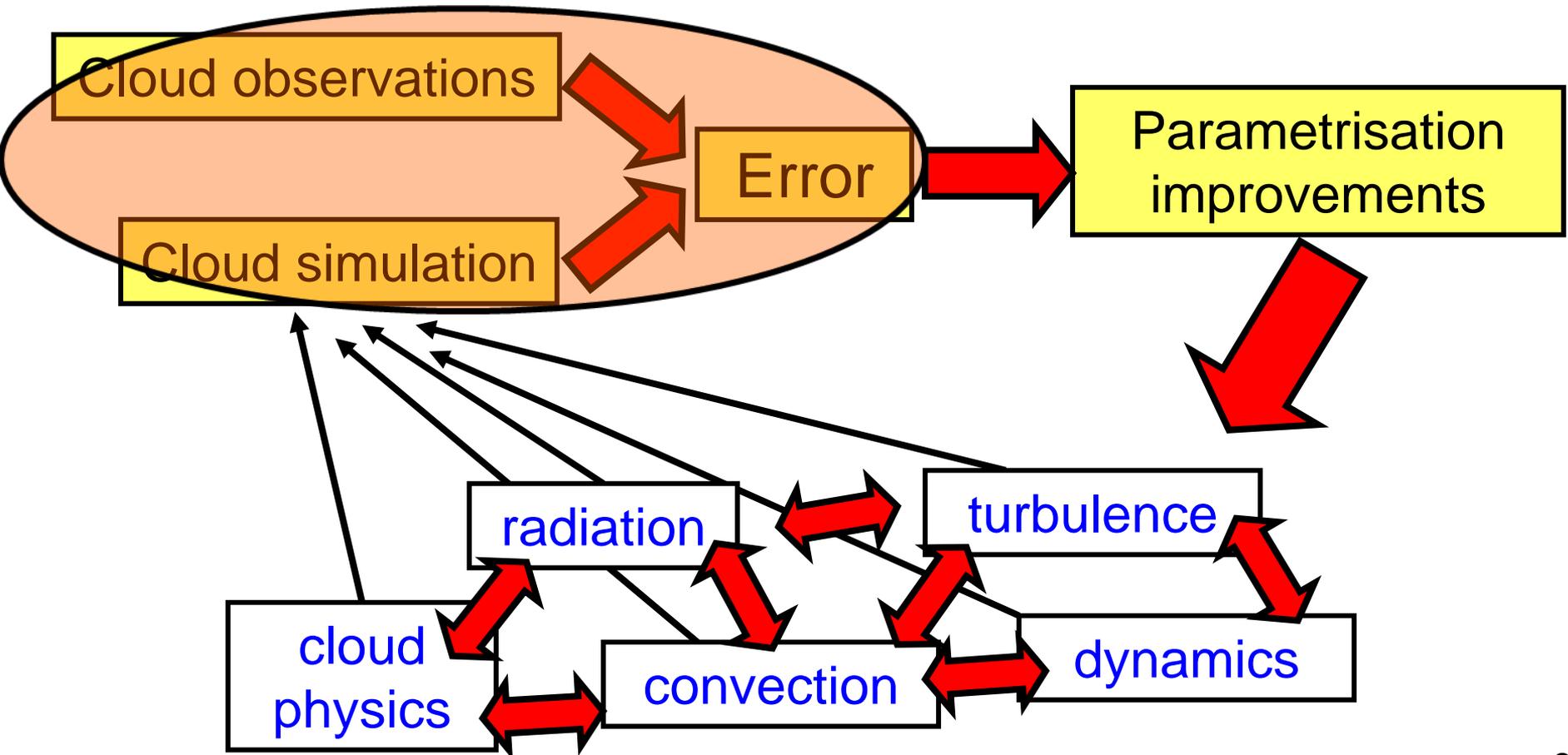


Figure 7. Vertical profiles of the total cloud condensate (liquid + solid) for simulations by different single-column models (see Tables 1 and 2 for explanations of the acronyms).

- **Long term climatologies:**
 - Climate systematic errors – we want to improve the basic state/climatology of the model
 - But which physics is responsible for the errors? Non-linear interactions.
 - Long term response vs. transient response.
 - We want to remove sensitivity to resolution = the parametrization problem!
- **Isolating regimes:** Composites and focus on geographical regions.
- **Case studies**
 - Detailed studies with Single Column Models, Cloud Resolving Models, NWP models
 - Easier to explore parameter space.
 - Are they representative? Do changes translate into global skill?

2. Comparing model and obs: Uncertainty and limitations

2. Uncertainty



What is a cloud ?



What is a cloud ?

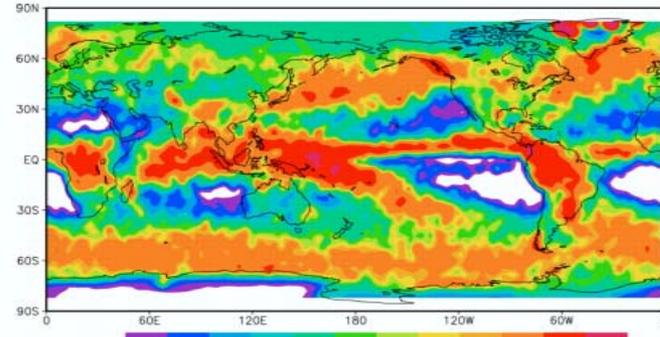
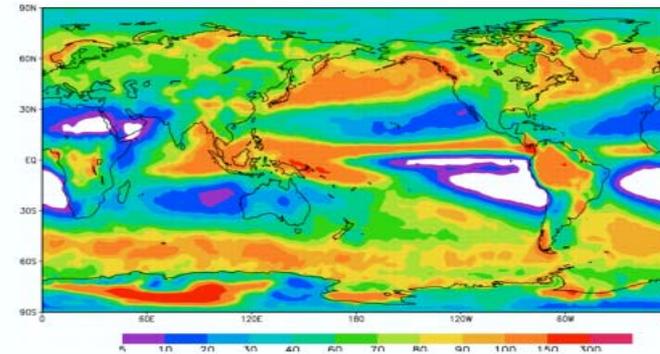
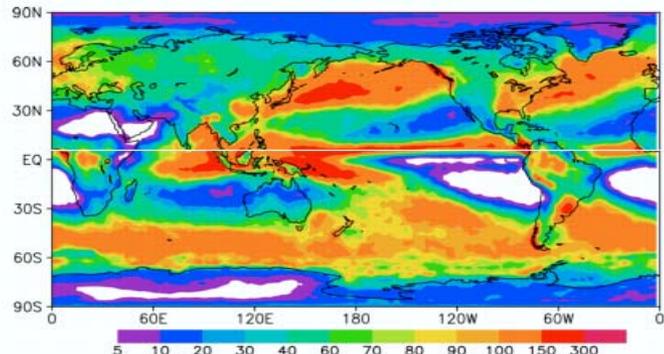
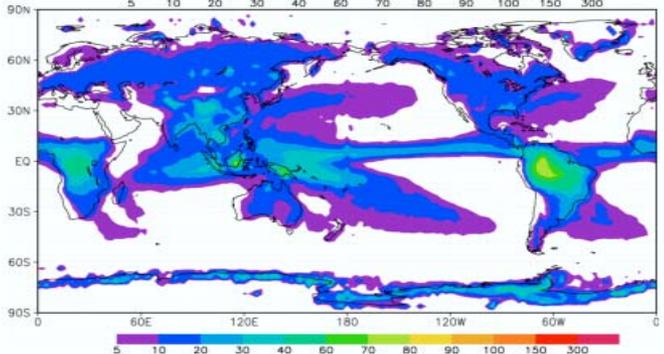
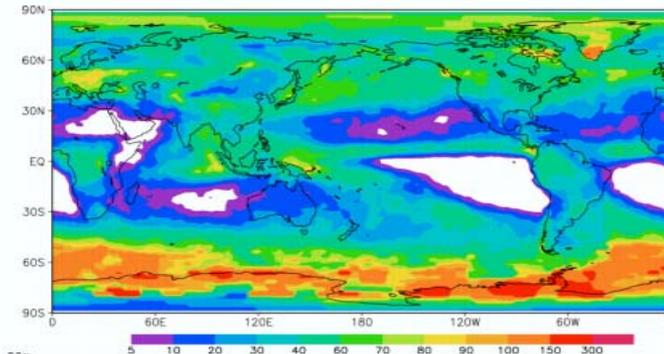
- Different observational instruments will detect different characteristics of clouds.
- A cloud from observations may be different to the representation in models
 - Understanding the limitations of different instruments
 - Benefit of observations from different sources
 - Comparing like-with-like (physical quantity, resolution)

Verification

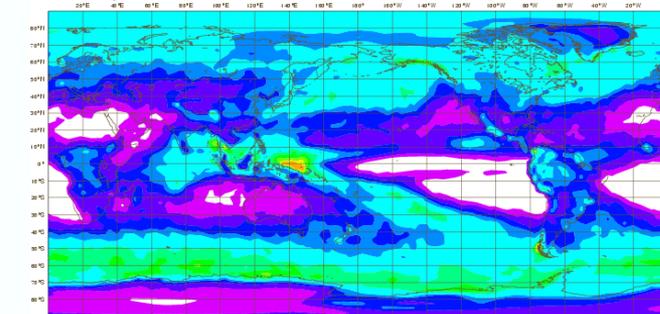
Annual average T159 Ice Water Path vs. Obs

Widely varying estimates of IWP from different satellite datasets!

From
Waliser et
al. (2009),
JGR



Tuesday 1 August 2000 00UTC ECMWF Forecast +31 days V1: Friday 1 September 2000 00UTC Surface: Total column ice water



CloudSat
(From
Waliser et
al 2009)

Current
ECMWF
model
IWP

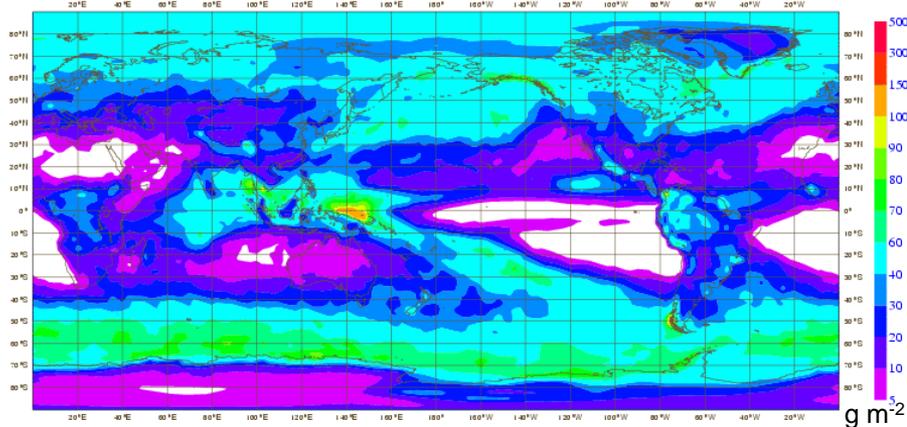
New 5 prognostic cloud microphysics

Ice vs. Snow

Model Ice Water Path (IWP) (1 year climate)

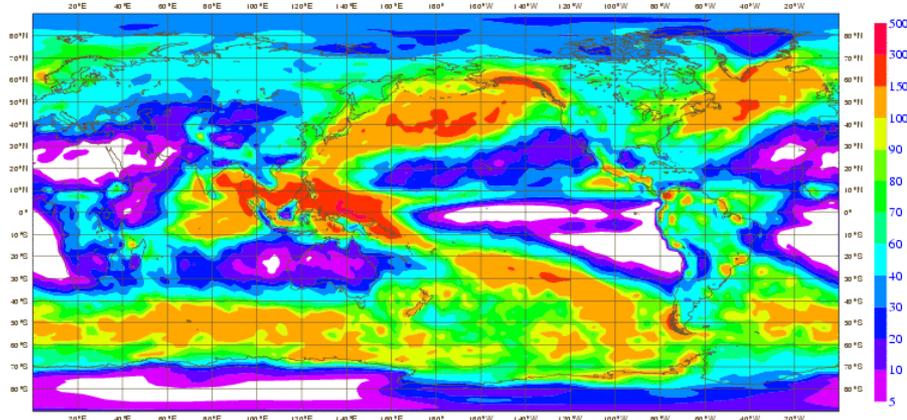
IWP from prognostic cloud ice variable

Tuesday 1 August 2000 00UTC ECMWF Forecast t+31 days VT: Friday 1 September 2000 00UTC Surface: **Total column ice water

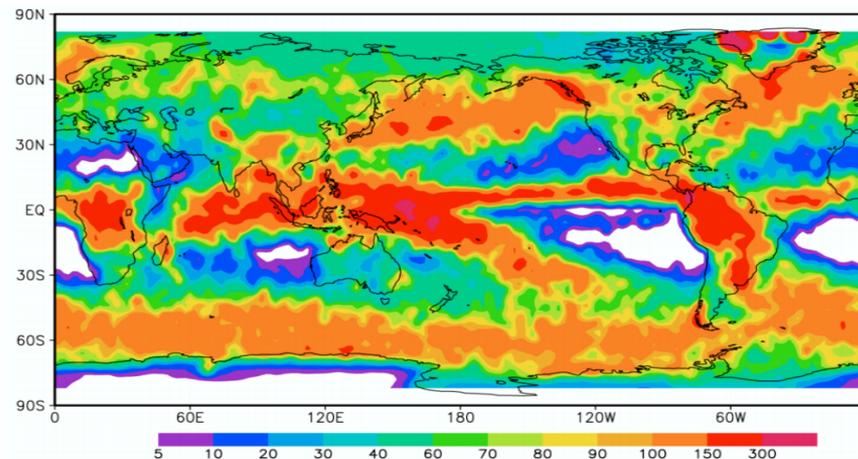


IWP from cloud ice + precipitating snow

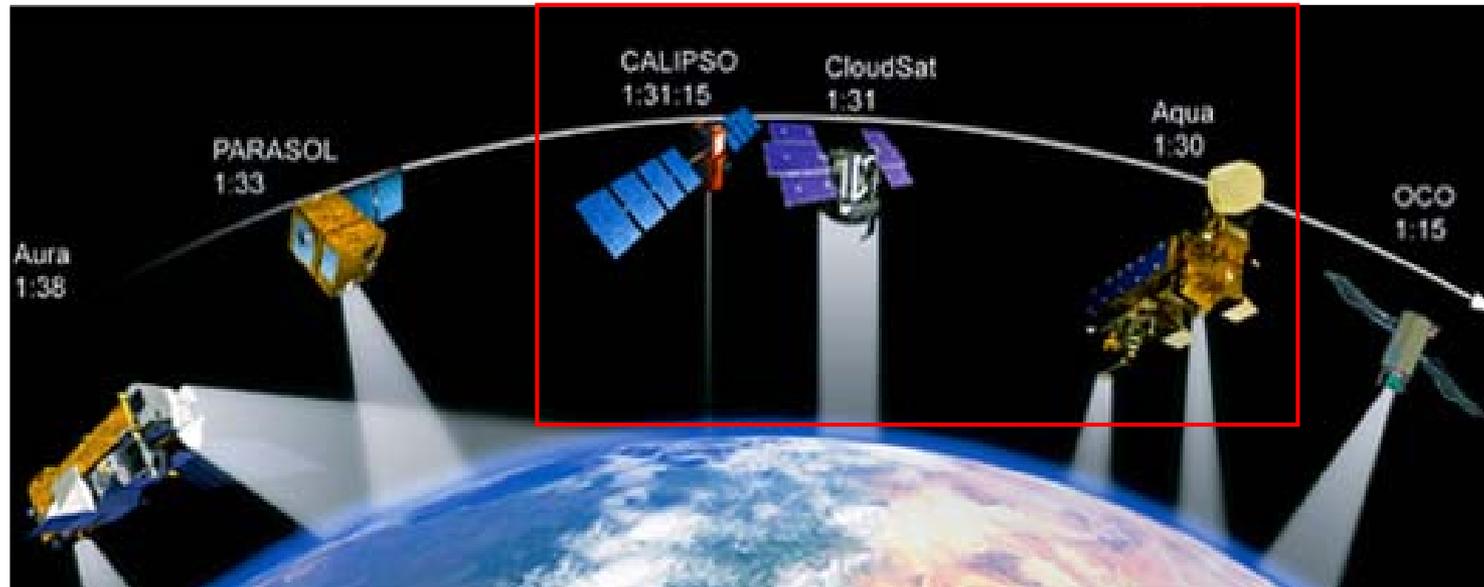
Tuesday 1 August 2000 00UTC ECMWF Forecast t+31 days VT: Friday 1 September 2000 00UTC Surface: **Total column ice water



Observed Ice Water Path (IWP) CloudSat 1 year climatology



A-Train: 28th April 2006



CloudSat: Cloud profiler radar 94GHz

CALIPSO: Cloud profiler lidar 532, 1064nm + Infra Red Imager

AQUA: radiometers MODIS, AIRS, CERES, AMSR-E

Global coverage:

Radar :2.5 km along track X 1.2 km across track / 500m =>250m

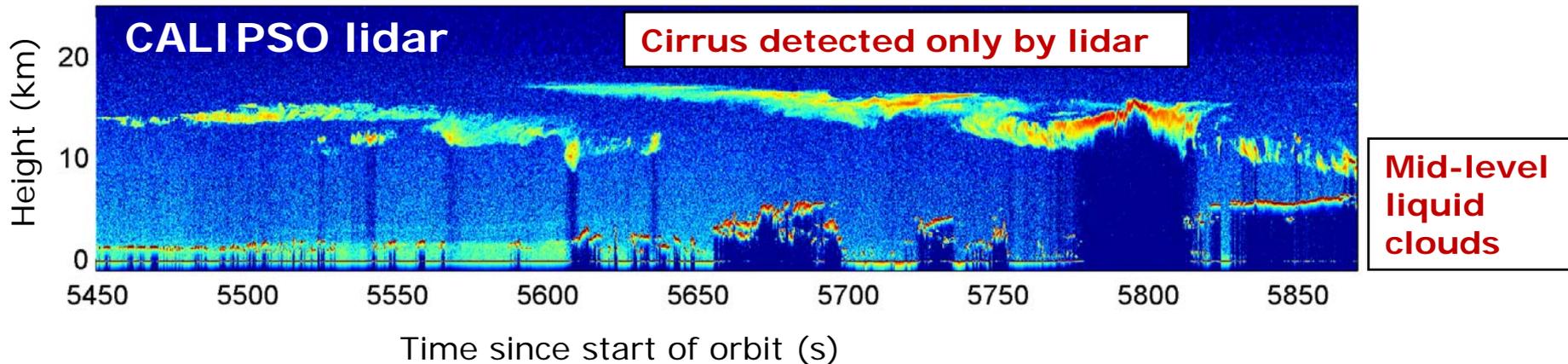
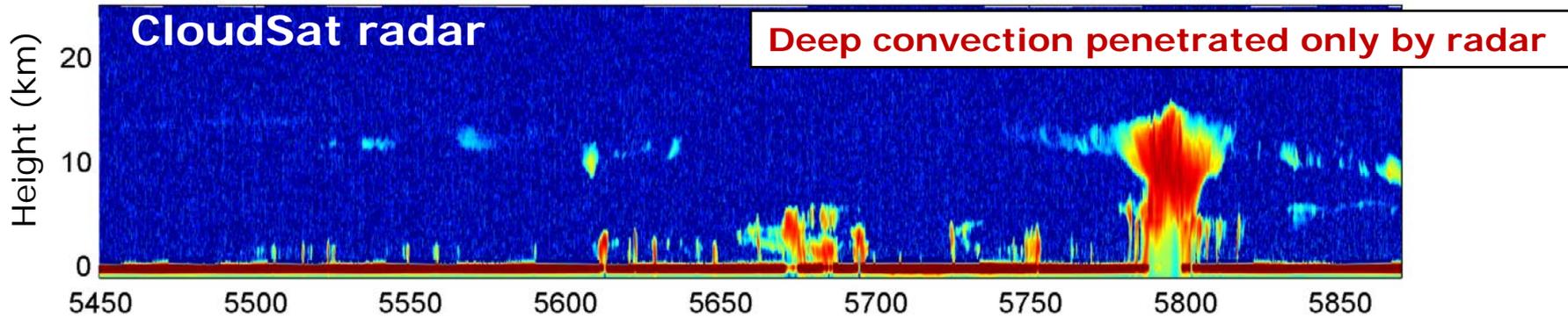
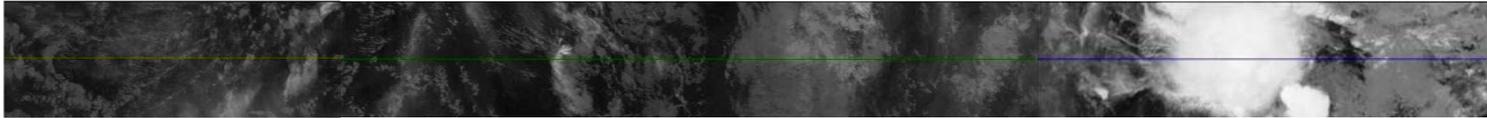
Lidar: 333 m / 30 m

Our merged product: CloudSat footprint/vertical resolution 60m

Julien Delanoë/Robin Hogan

Example of mid-Pacific convection

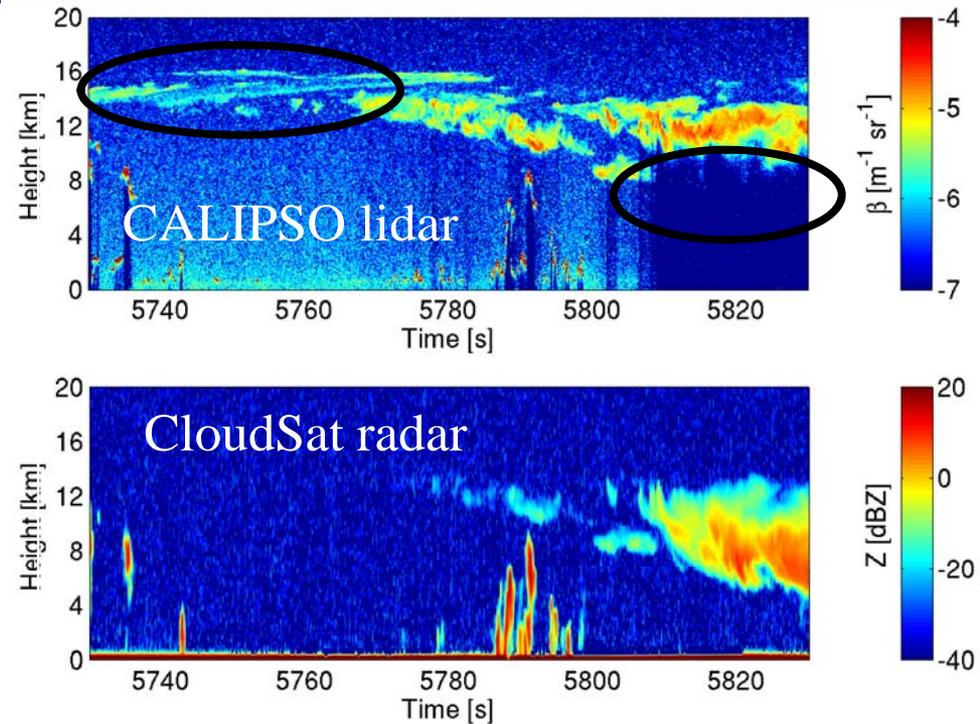
MODIS 11 micron channel



Why combine radar, lidar and radiometers?

Radar $Z \propto D^6$, lidar $\beta' \propto D^2$ so the combination provides particle size

- *Lidar*: sensitive to particle concentration, can be extinguished
- *Radar*: very sensitive to the particle size, not very sensitivity to liquid clouds and small ice particles



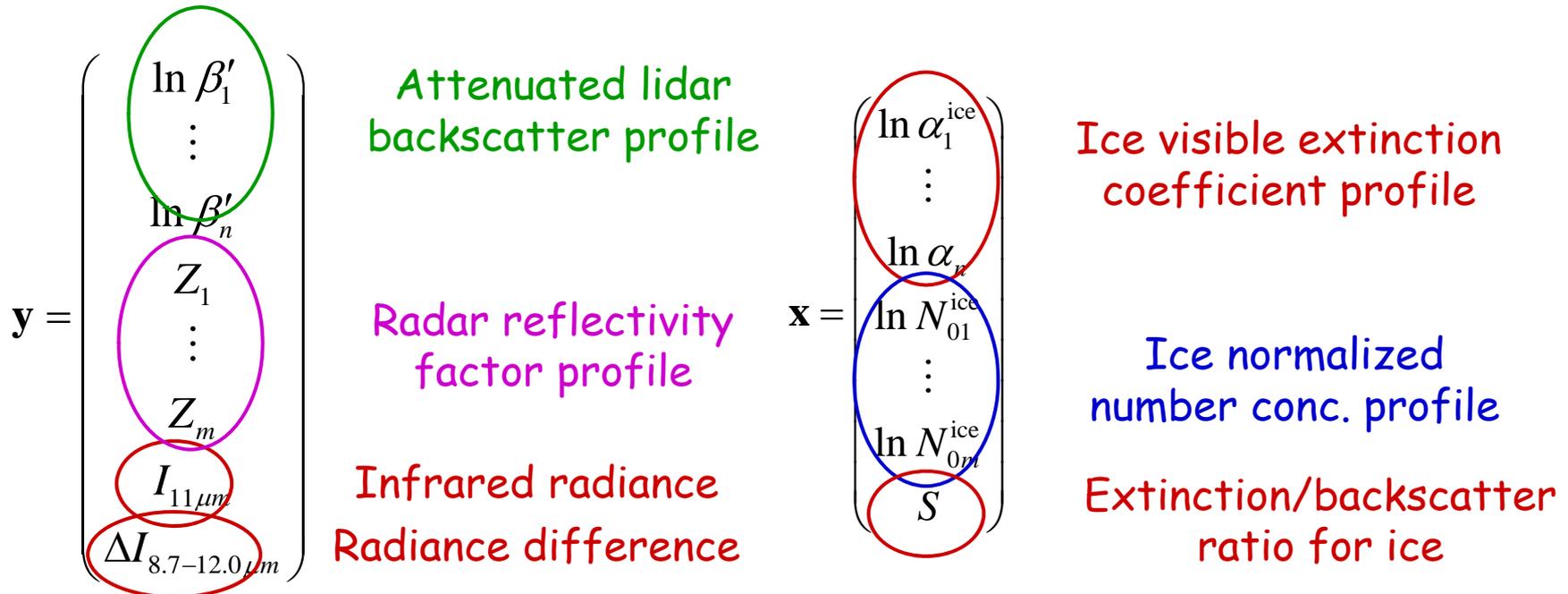
Radiances ensure that the retrieved profiles can be used for radiative transfer studies

- *Single channel*: information on extinction near cloud top
- *Pair of channels*: ice particle size information near cloud top

We use “unified” variational scheme to retrieve ice cloud properties, thin and thick ice clouds
Delanoë and Hogan 2008, JGR (doi:10.1029/2007JD009000)

We know the **observations** (instrument measurements) and we would like to know **cloud properties** : visible extinction, Ice water content, effective radius...

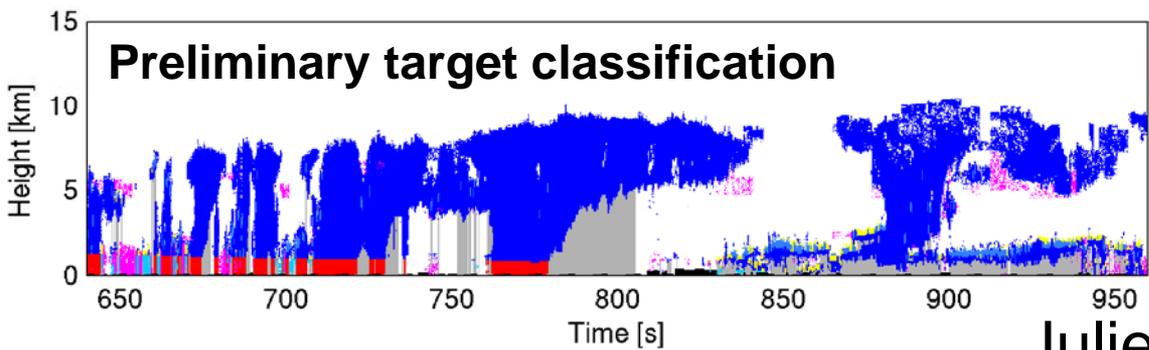
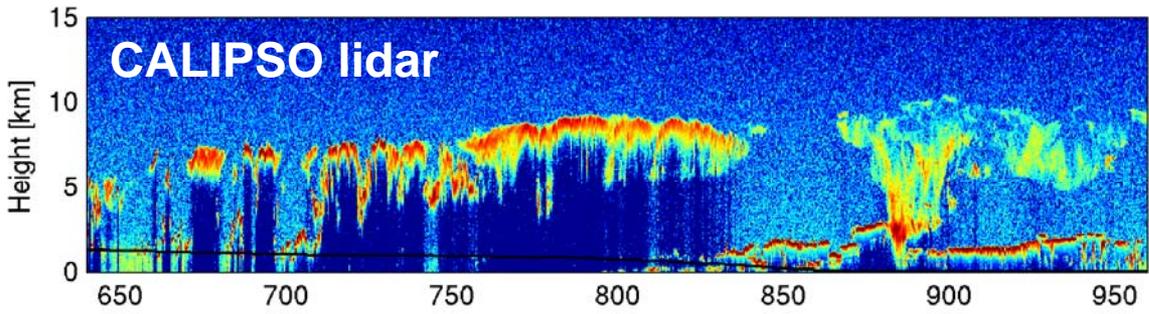
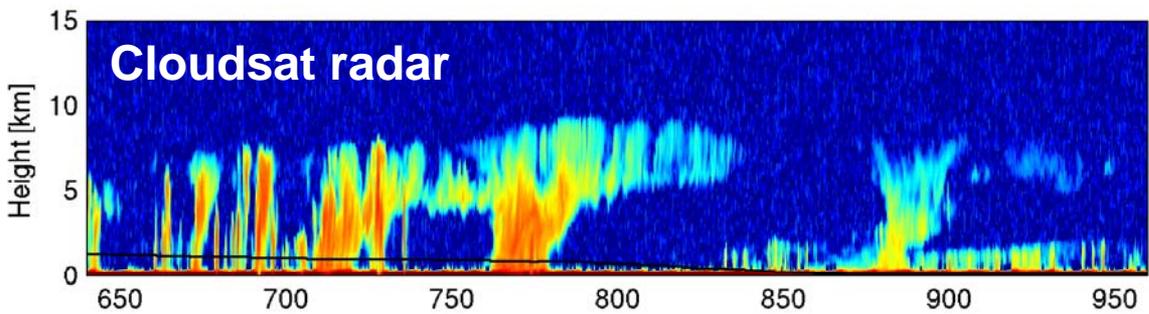
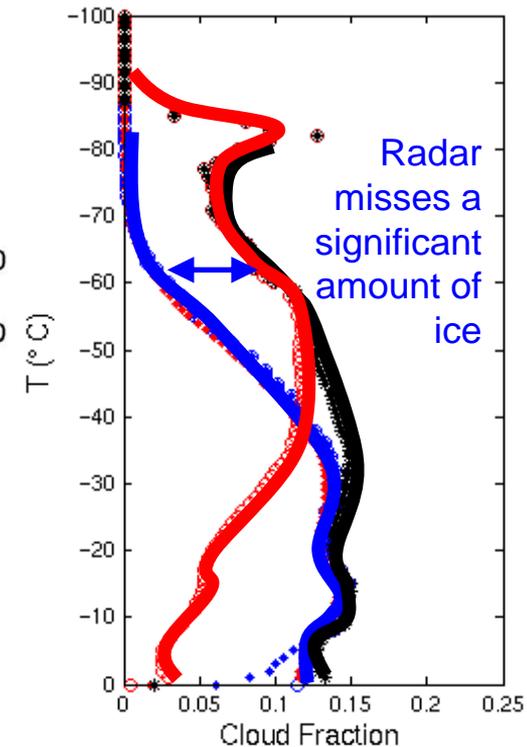
- **Observation vector**
 - Elements may be missing
- **State vector** (which we want to retrieve)



Iterative process: compare predicted observations and measurements, with an **a-priori** and **measurement errors** as a constraint

Combining radar and lidar...

Global-mean cloud fraction



- Insects
- Aerosol
- Rain
- Supercooled liquid cloud
- Warm liquid cloud
- Ice and supercooled liquid
- Ice
- Clear
- No ice/rain but possibly liquid
- Ground

Radar and lidar
Radar only
Lidar only

Frequency of occurrence of IWC vs temperature

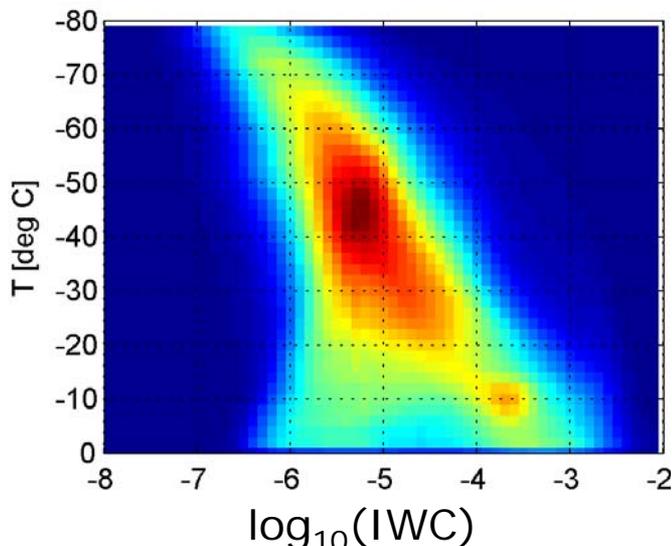
- IWC increases with temperature:
- but spread over 2 to 3 orders of magnitude at low temperatures
- reach 5 orders of magnitude close to 0° C

Advantage of the algorithm:

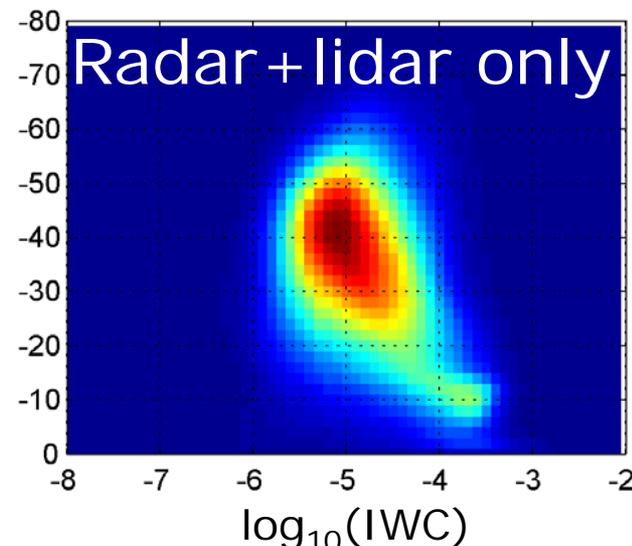
Deep ice clouds: radar
Thin ice clouds: lidar

When radar and lidar work well together very good confidence in the retrievals

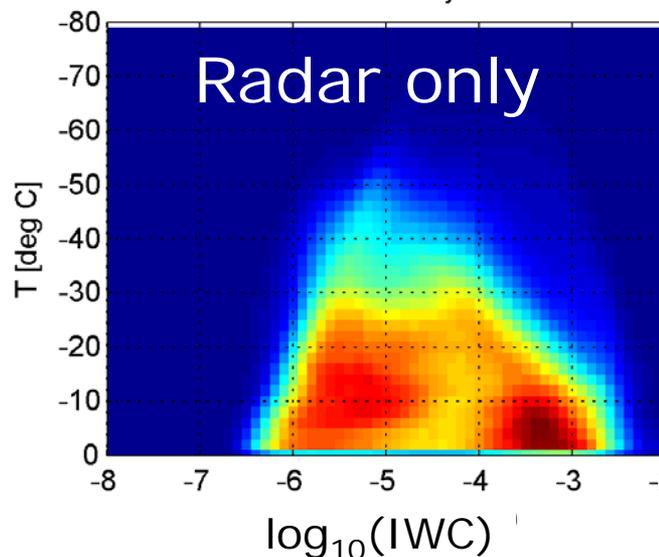
⇒ Obvious complementarity radar-lidar



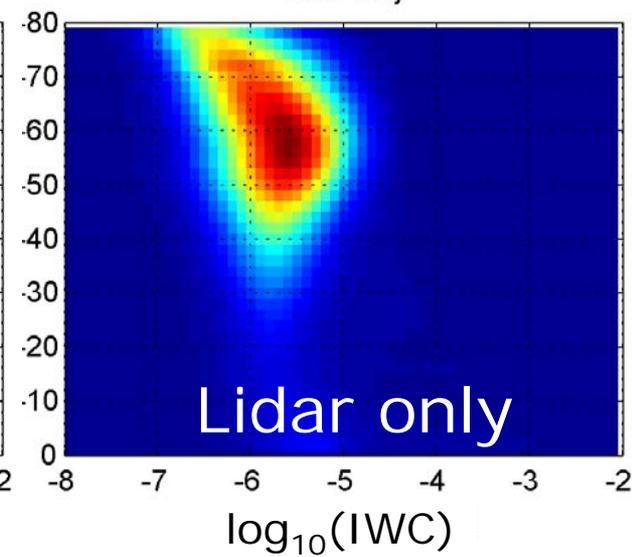
Radar only



Lidar only



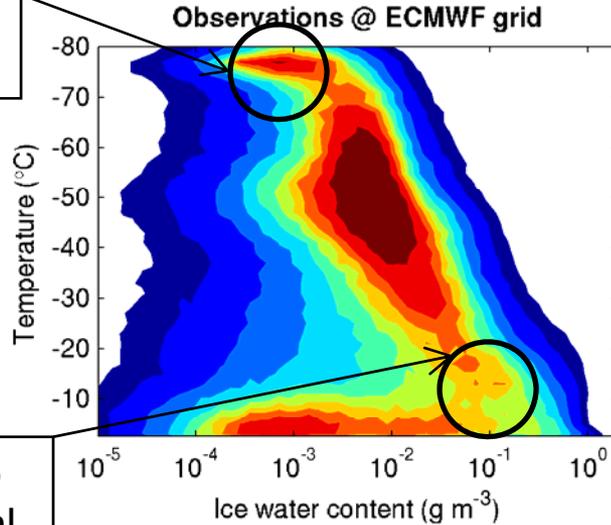
log₁₀(IWC)



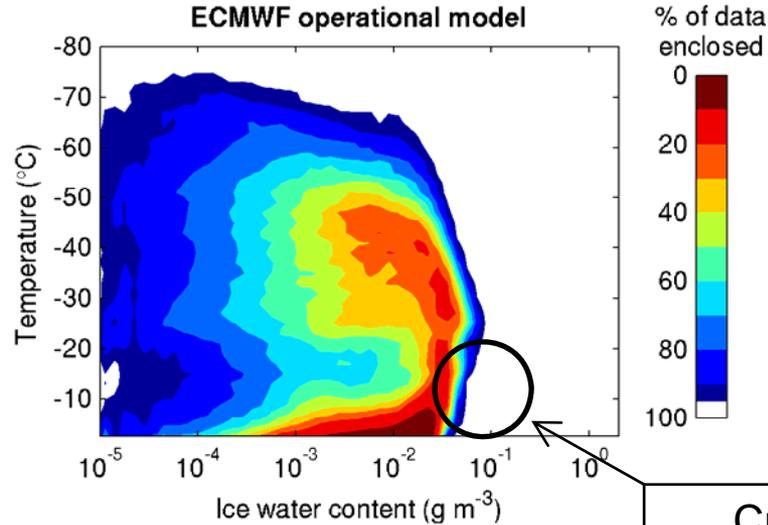
log₁₀(IWC)

CloudSat/CALIPSO Model Verification

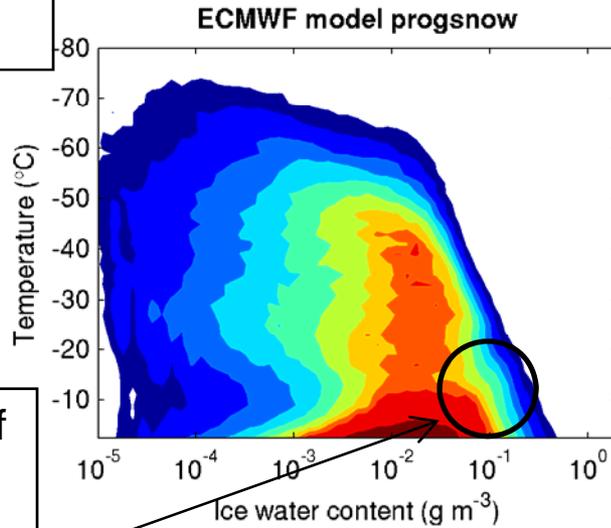
GLOBAL Ice Water Content vs. T distributions



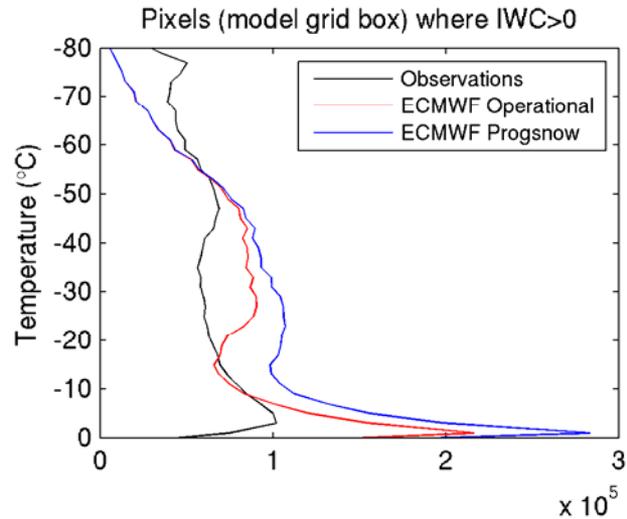
Specular reflection ?



Changes to IWC retrieval result



Distribution of IWC in new scheme is improved



Current scheme misses larger IWC (snow)

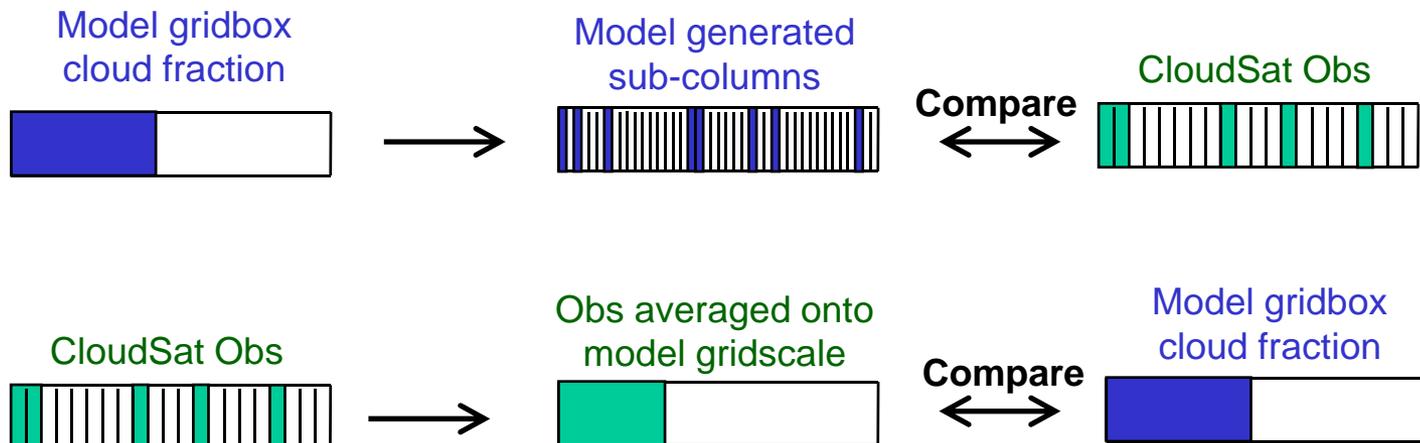
(In collaboration with Delanoë and Hogan, Reading Univ.)

When comparing a model with observations, we need to compare like-with-like



Spatial resolution mis-match

- Need to address mismatch in spatial scales in model (50 km) and obs (1 km)
- Sub-grid variability is predicted by the IFS model in terms of a cloud fraction and assumes a vertical overlap.
- Either:
 - (1) Average obs to model representative spatial scale
 - (2) Statistically represent model sub-gridscale variability using a Monte-Carlo multi-independent column approach.

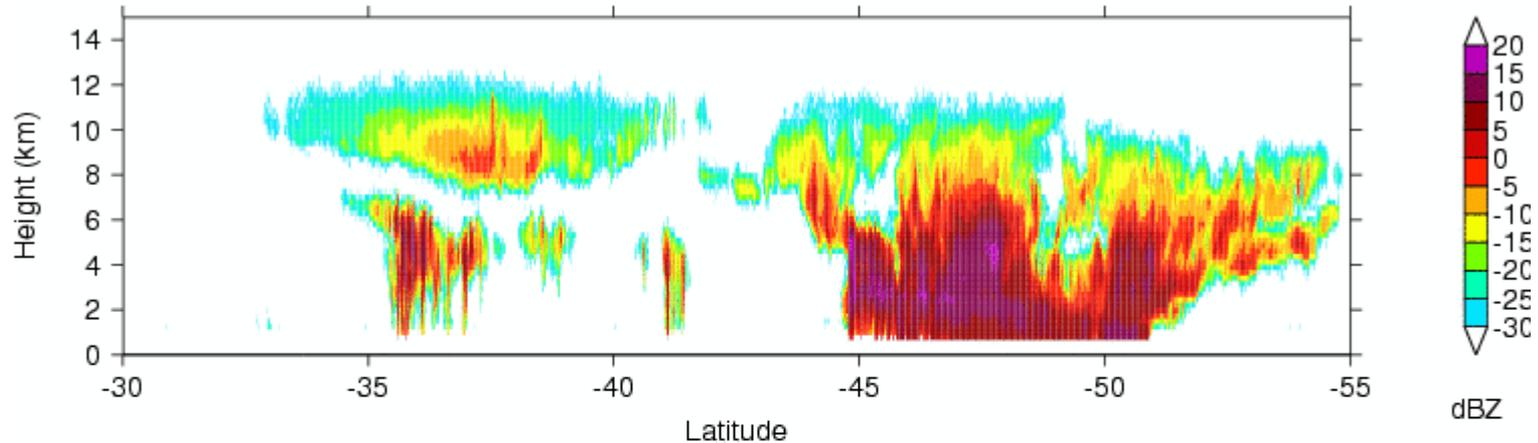


- Model Cloudy
- Obs Cloudy
- Cloud-free

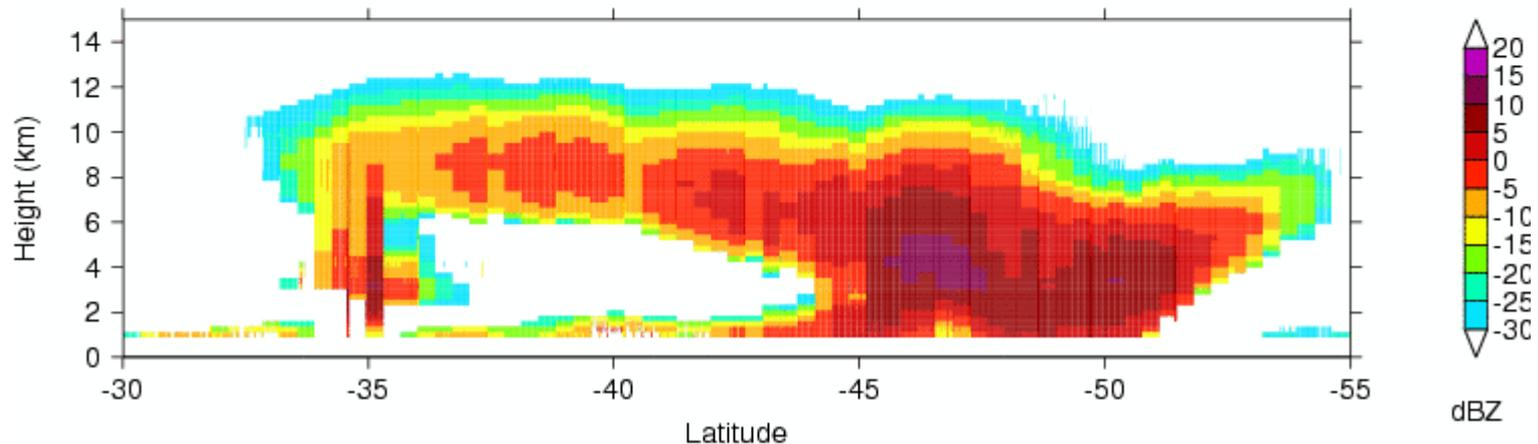
MODEL to OBSERVATION

Radar Reflectivity: Cross-section through a mid-latitude front

CloudSat Effective Radar Reflectivity



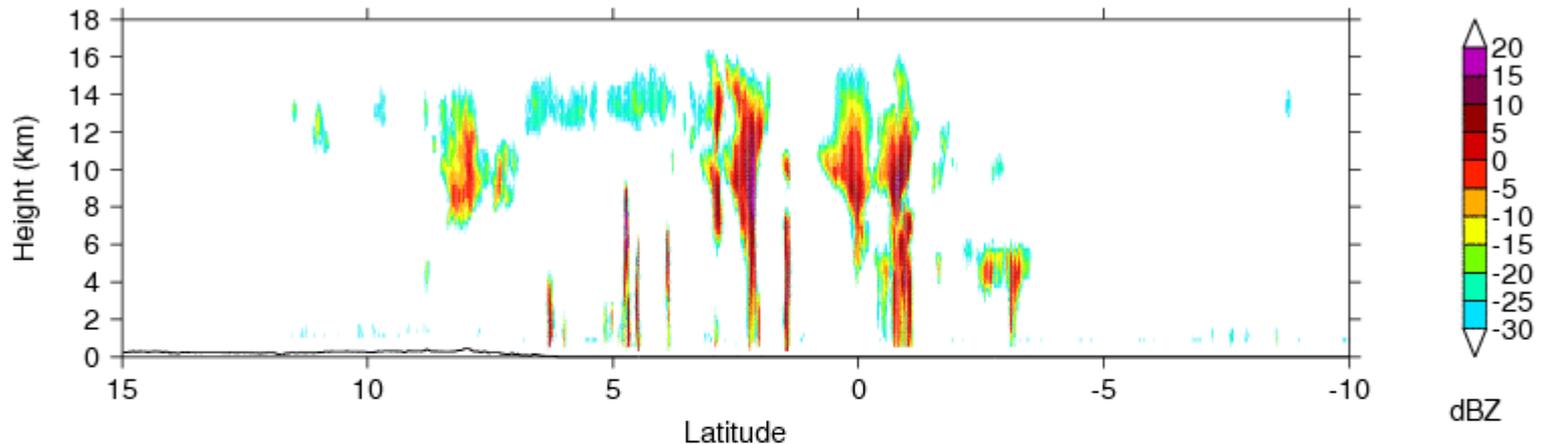
IFS Along-track Effective Radar Reflectivity



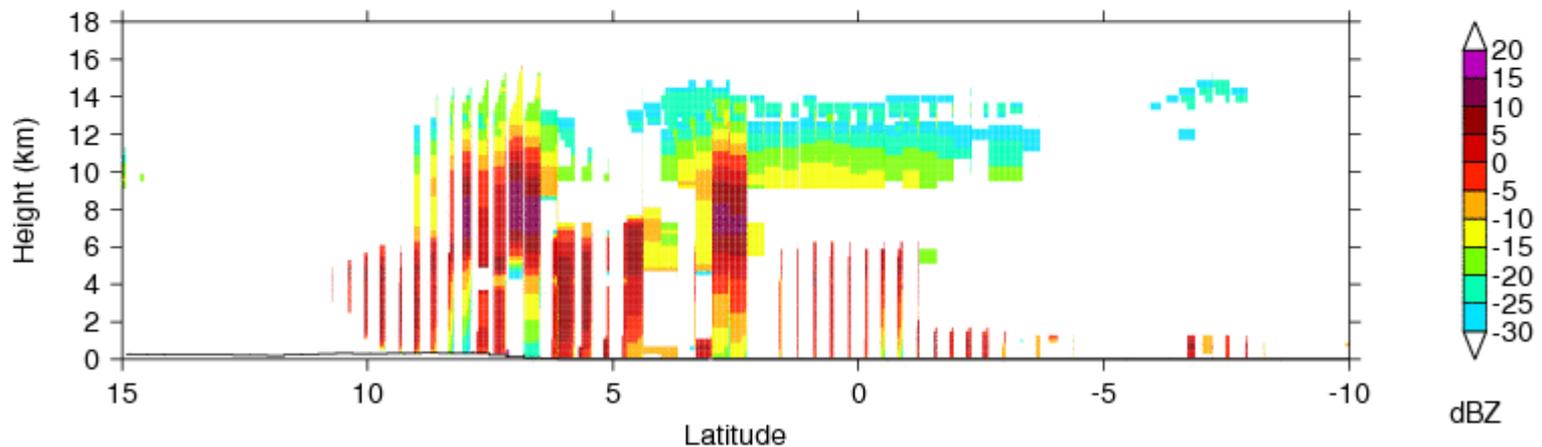
Radar Reflectivity

Cross-section through tropical convection

CloudSat Effective Radar Reflectivity: Granule 04182



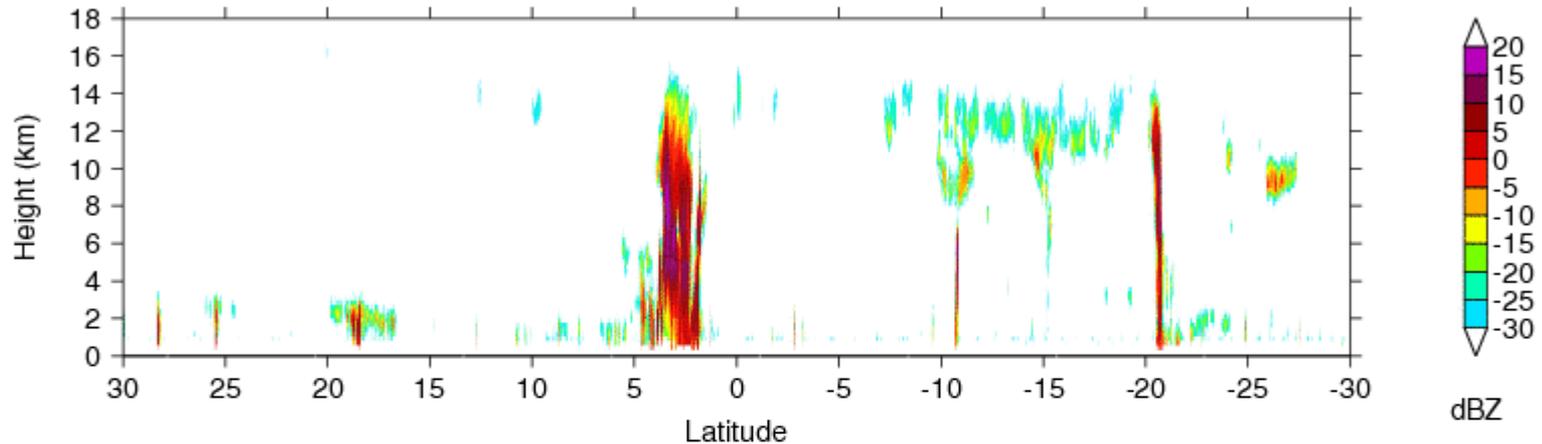
IFS Along-track Effective Radar Reflectivity



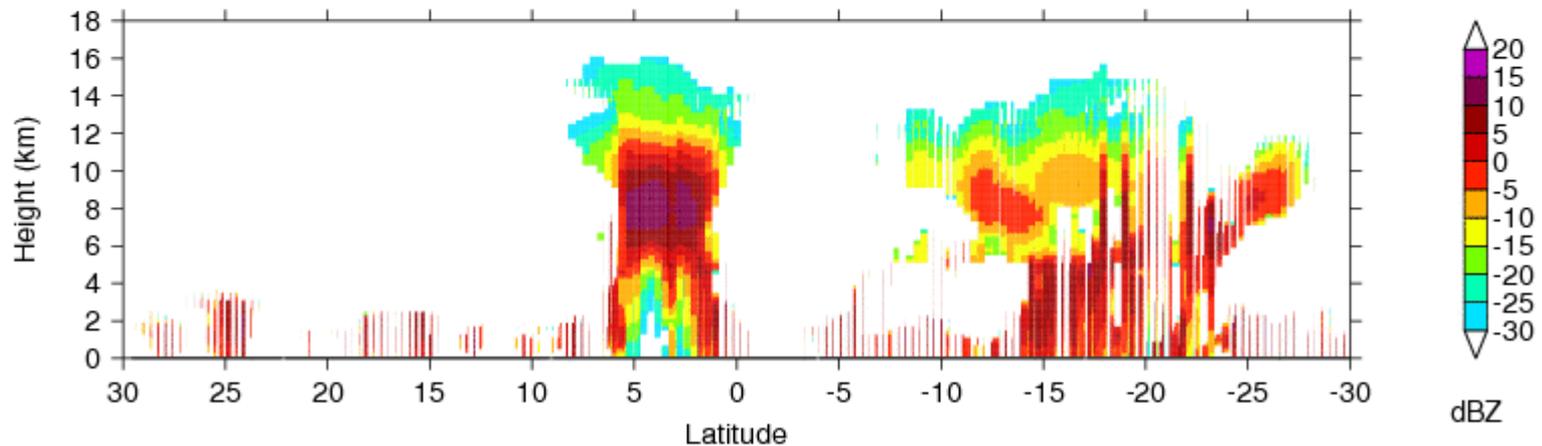
Radar Reflectivity

Cross-section through tropical convection

CloudSat Effective Radar Reflectivity: Granule 04175



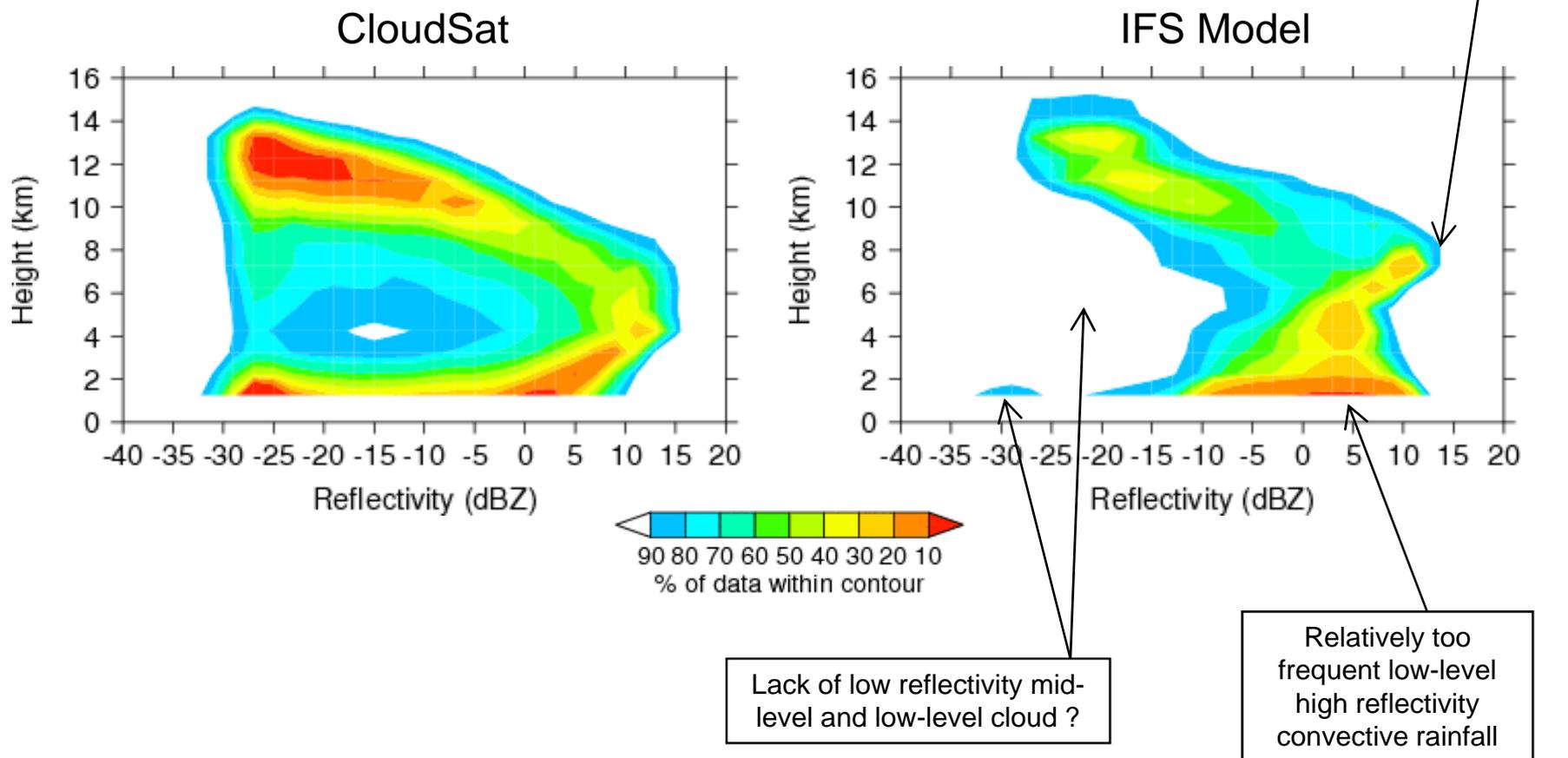
IFS Along-track Effective Radar Reflectivity



Radar Reflectivity Statistics

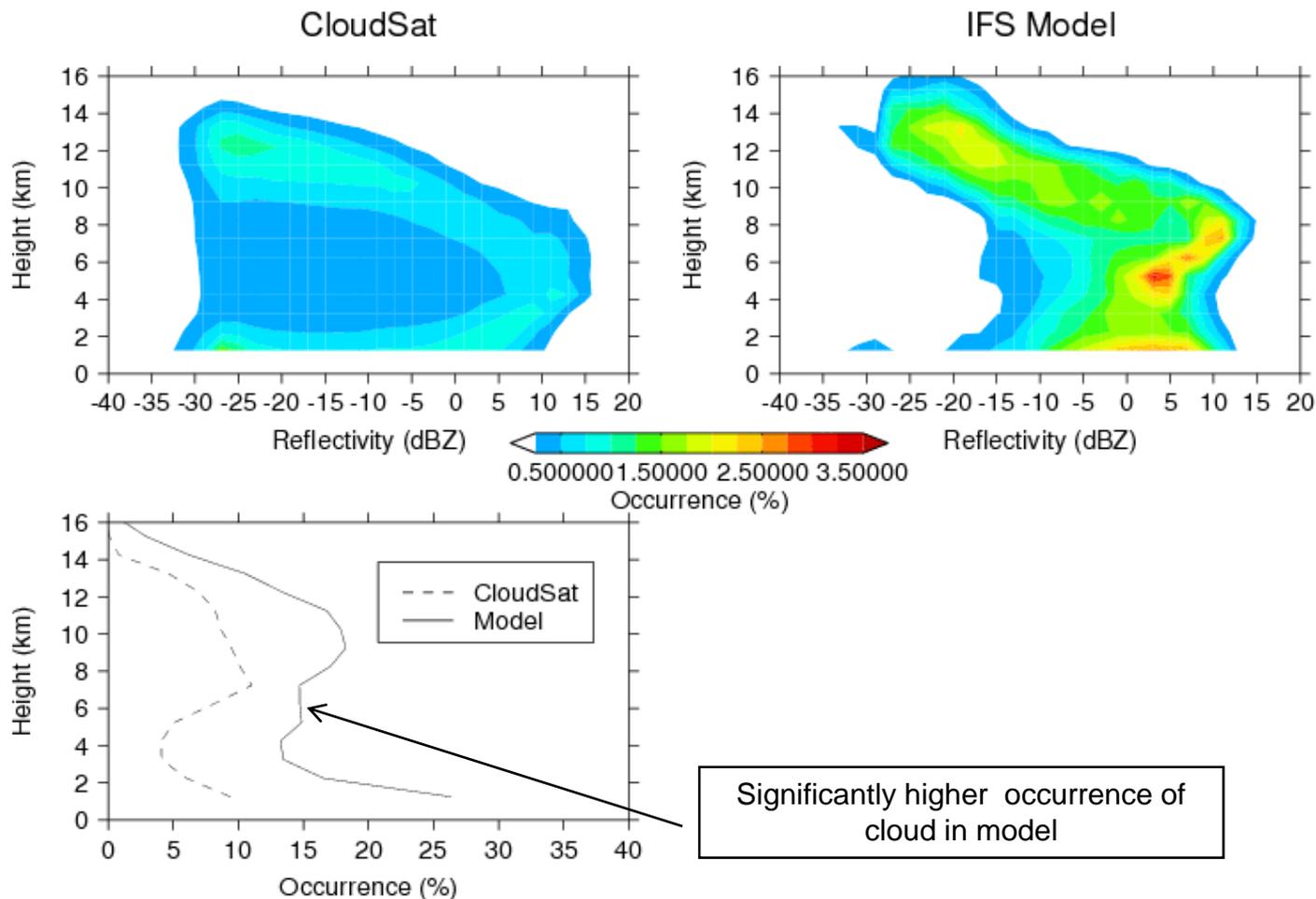
Radar Reflectivity vs. Height Relative Frequency of Occurrence

Tropics over ocean 30S to 30N for February 2007



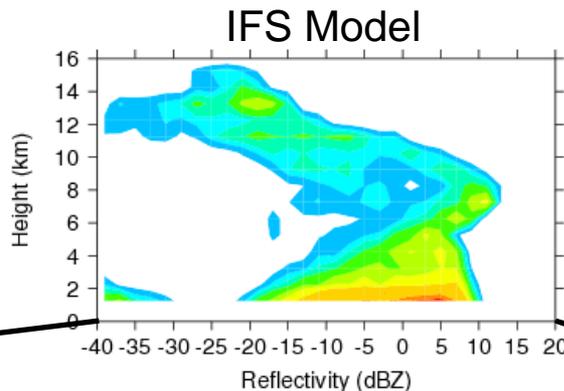
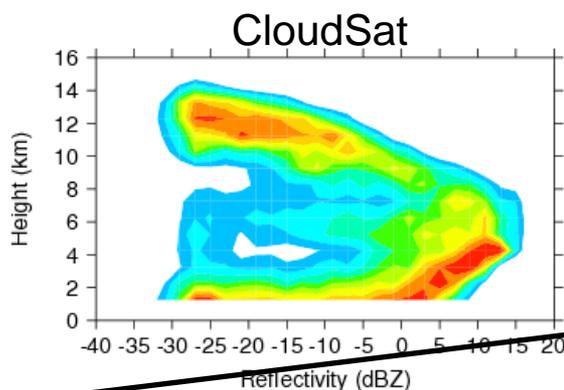
Radar Reflectivity Statistics

STATISTICS: Frequency of occurrence (Radar Reflectivity vs. Height)
Tropics over ocean 30S to 30N for February 2007



Radar Reflectivity PDF

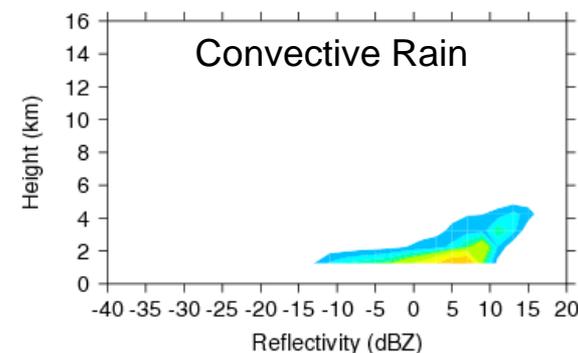
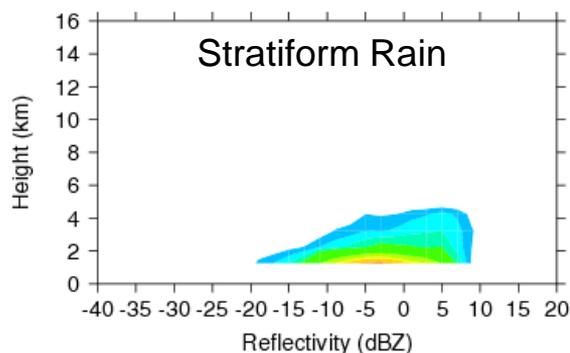
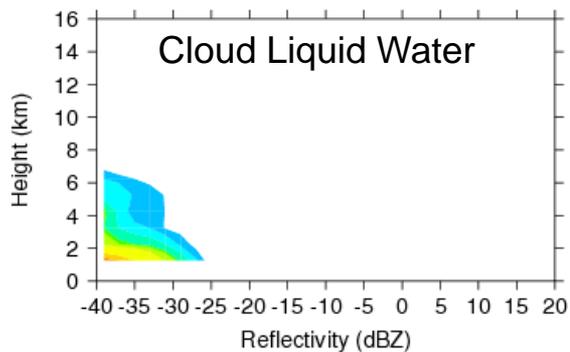
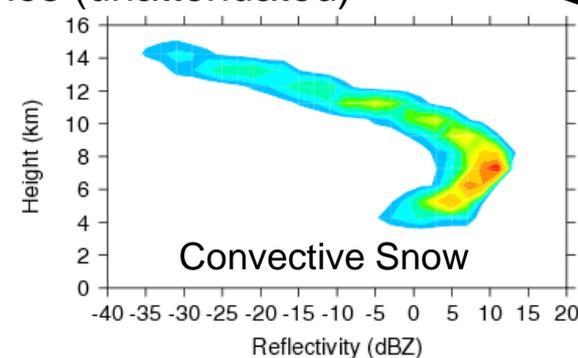
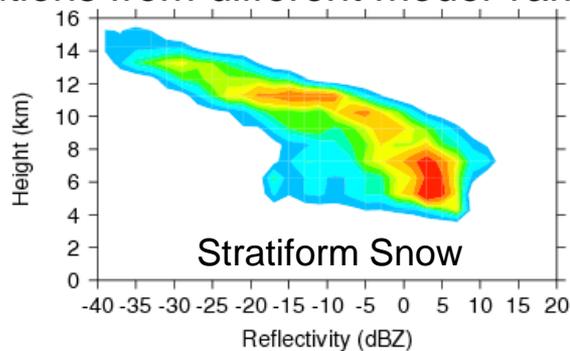
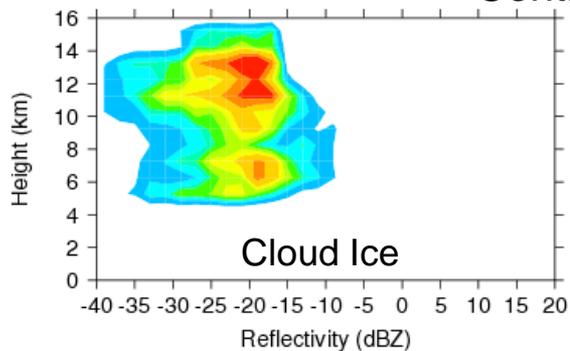
Contributions from cloud/precip (tropics)



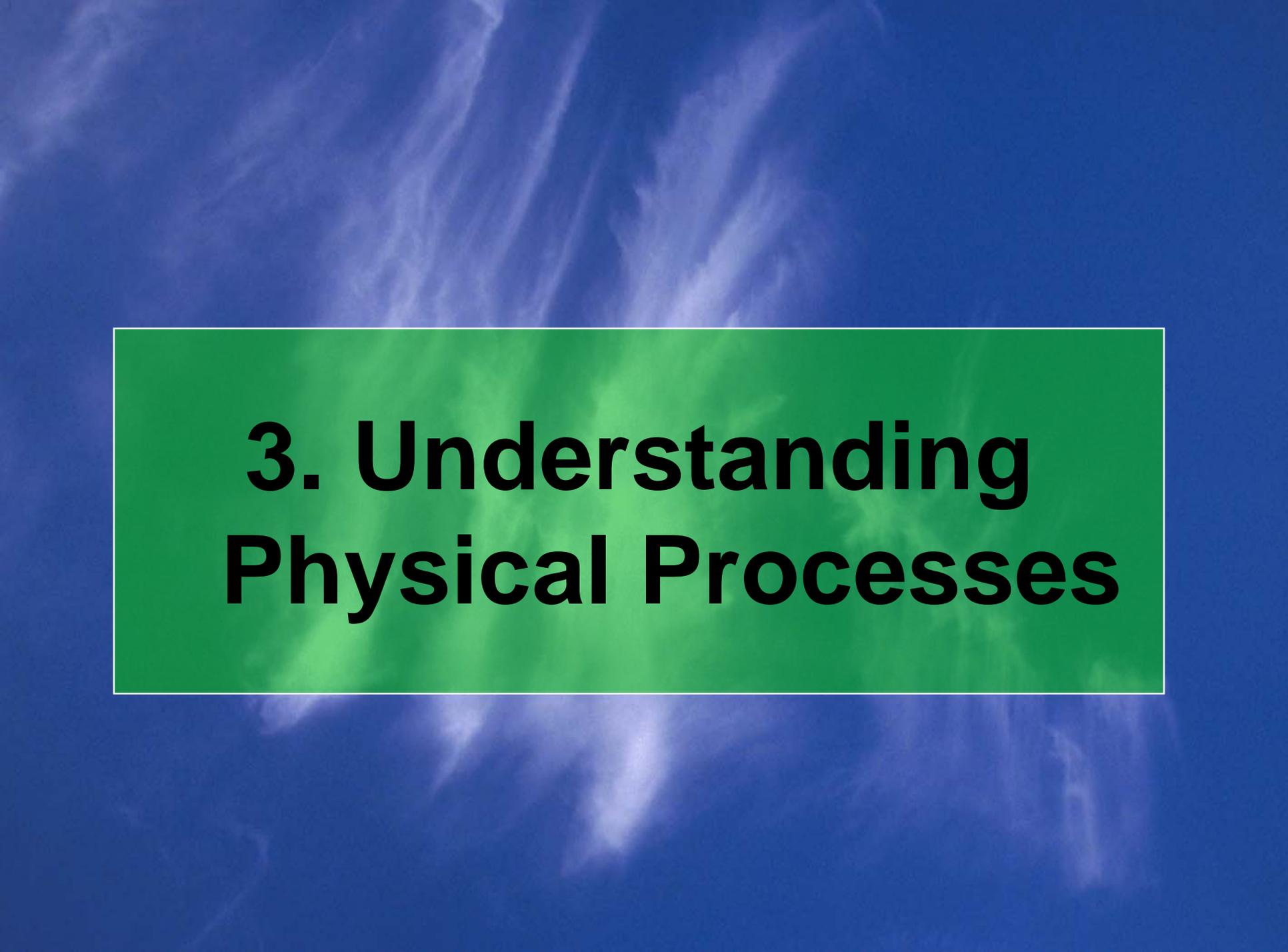
Data from
09/02/2007



Contributions from different model variables (unattenuated)

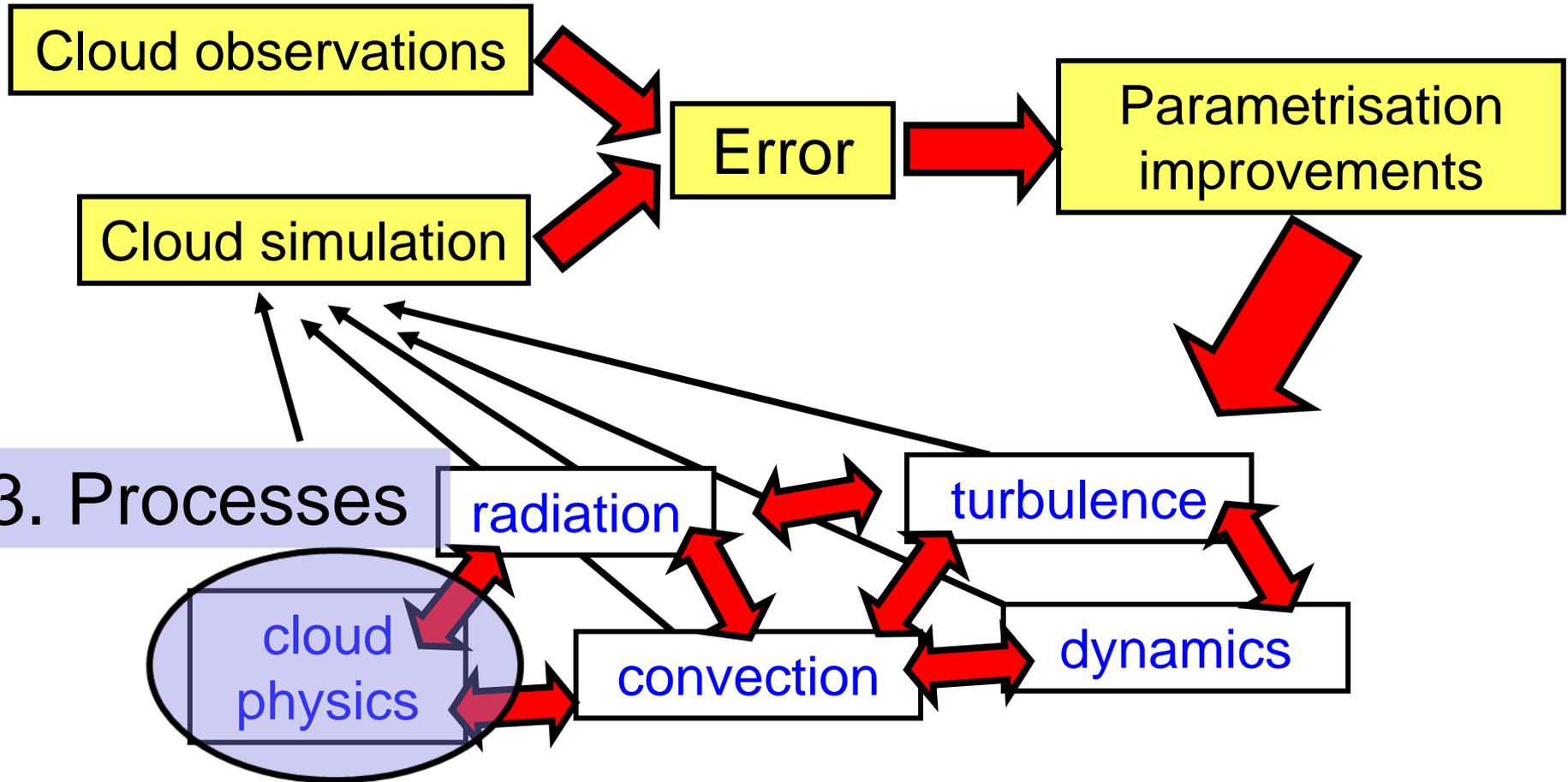


- Limitations and uncertainty:
 - Observations have limitations, provide a partial picture.
 - We need to know the error characteristics (including systematic errors). But we don't always know this!
- Synergy:
 - Different observation sources have different strengths and weaknesses Make the most of this complementary information (e.g. CloudSat, CALIPSO, MODIS)
- Need to compare like-with-like
 - Compare in “model-space”, or “obs space”
 - Assumptions required for both
 - Spatial and temporal resolution differences
- Diagnose model problems from different angles
 - Retrieval of model variables from observations (“obs-to-model”), e.g. IWC
 - Forward modelling of observed variables (“model-to-obs”), e.g. Z
 - Different approaches help to diagnose model problems

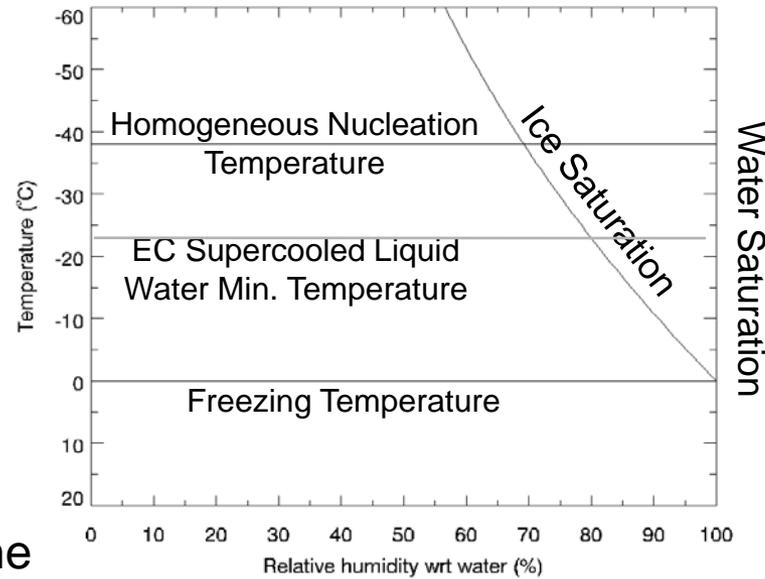


3. Understanding Physical Processes

Cloud Validation: The problems

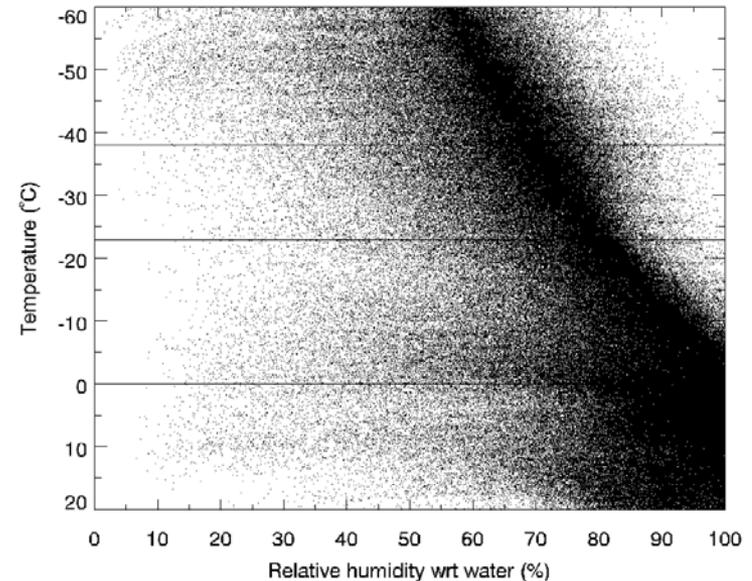
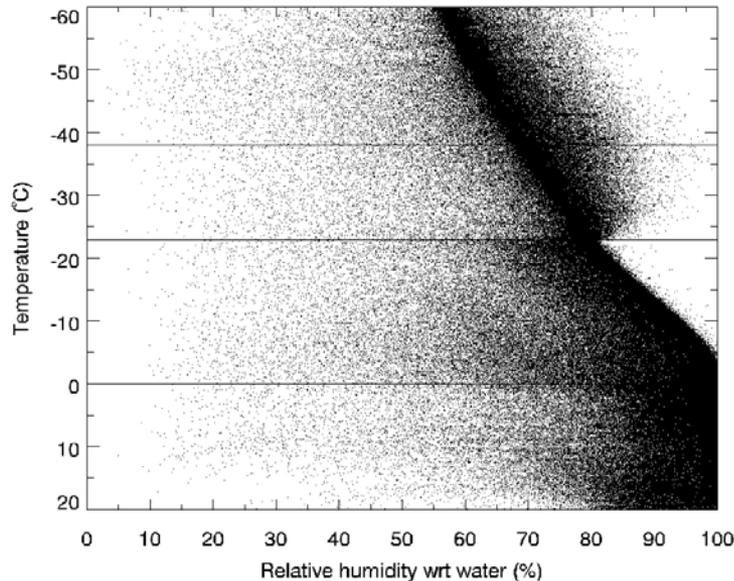


Temperature vs. Relative Humidity



Current EC cloud scheme

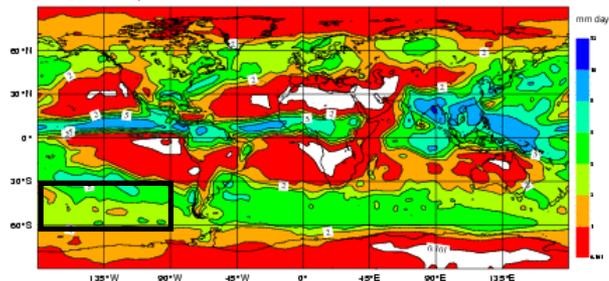
New EC cloud scheme



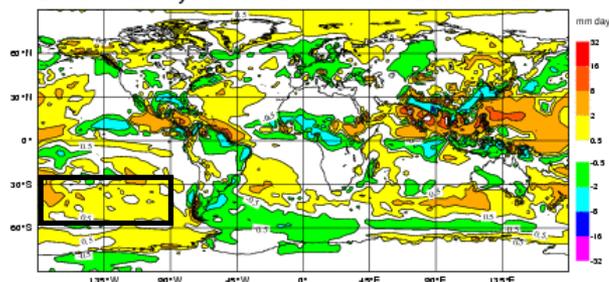
Precipitation validation with CloudSat

(in collaboration with Graeme Stephens)

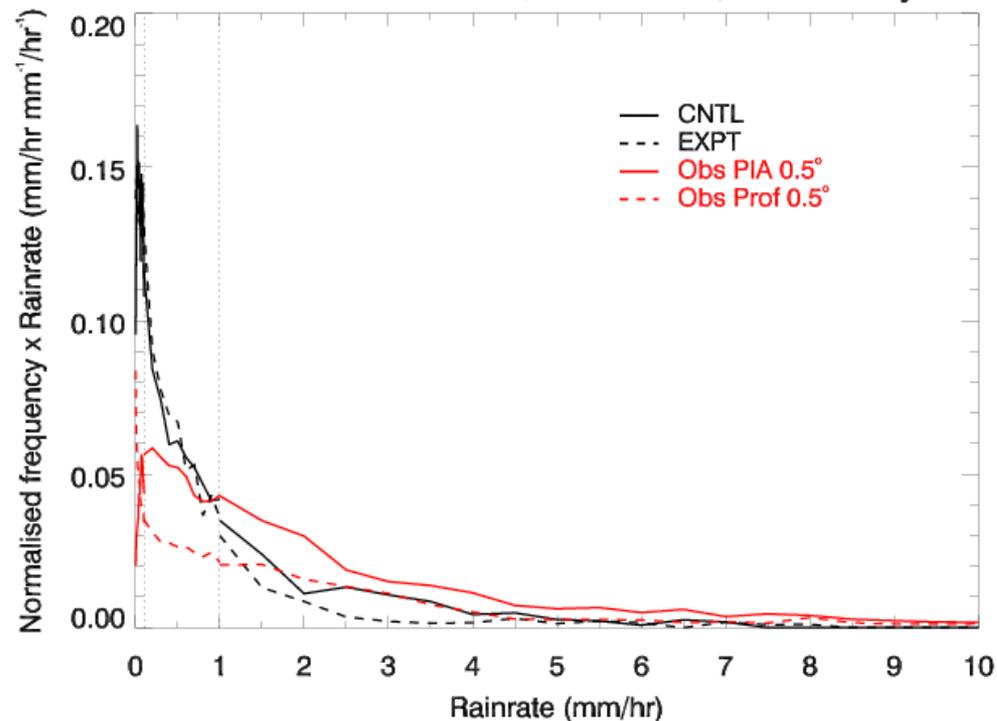
Total Precipitation GPCP JJA 2001 Global Mean: 2.63



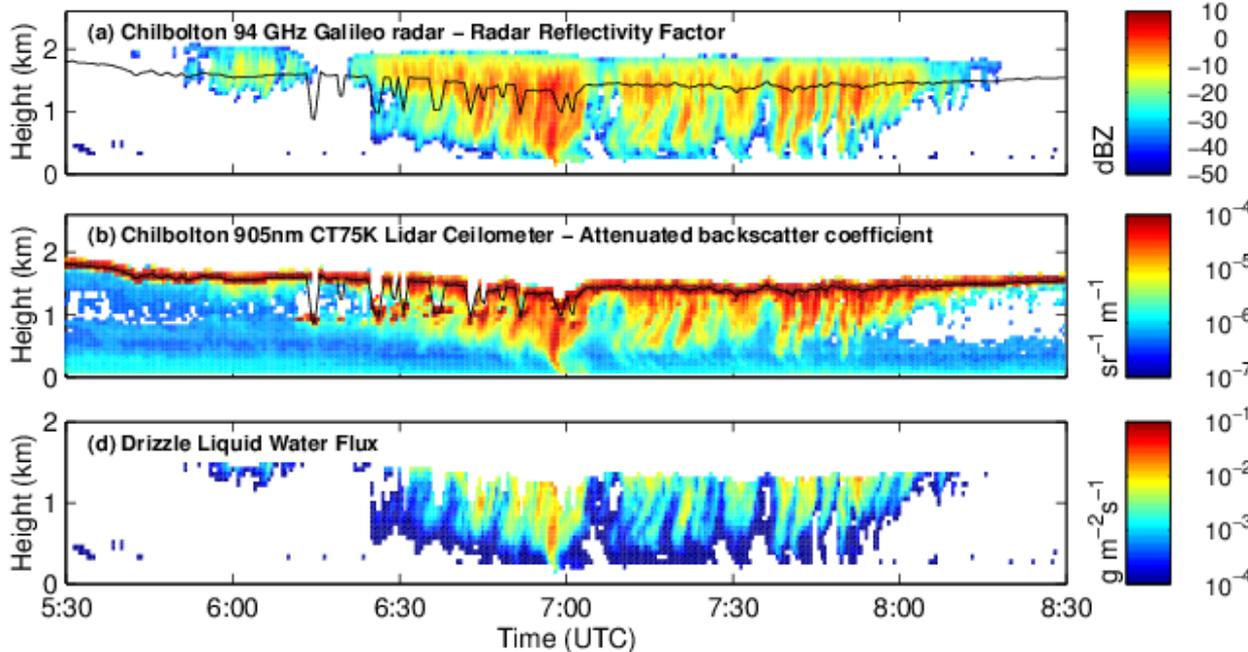
Difference ey0u - GPCP error 0.526 RMS 2.13



Domain -180 to -90E, -30 to -60N, Ocean only



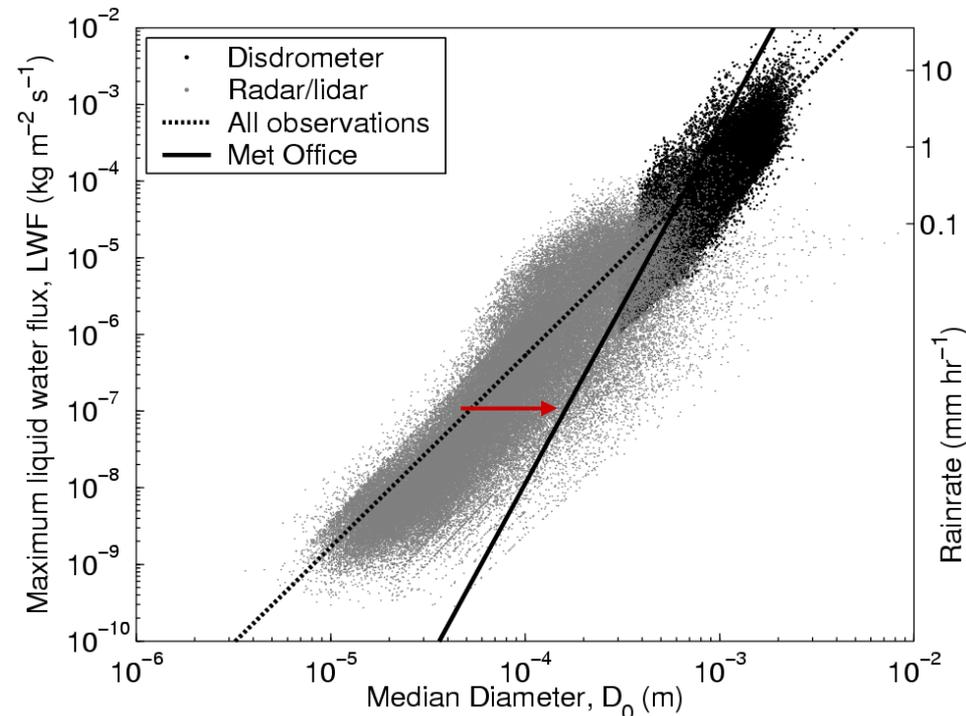
- Model overestimates frequency of low precipitation rates (< 1 mm/hr)
- Model underestimates frequency of high precipitation rates (> 5 mm/hr?) (but representativity?)
- Still an issue of uncertainty in the obs – work in progress.



- Radar and lidar used to derive drizzle rate below stratocumulus
- Important for cloud lifetime in climate models

O'Connor et al. (2005)

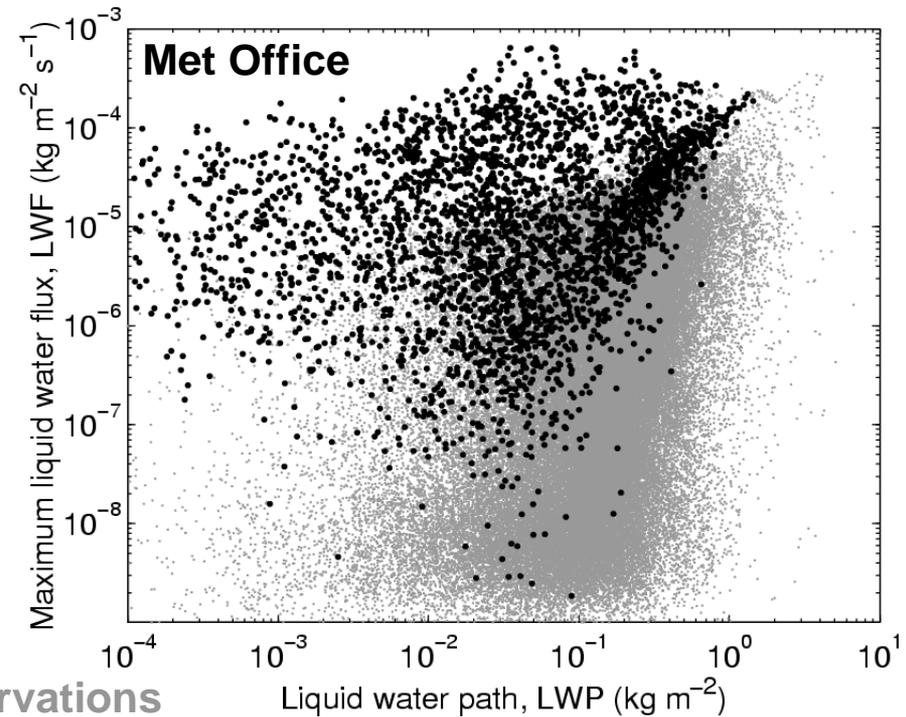
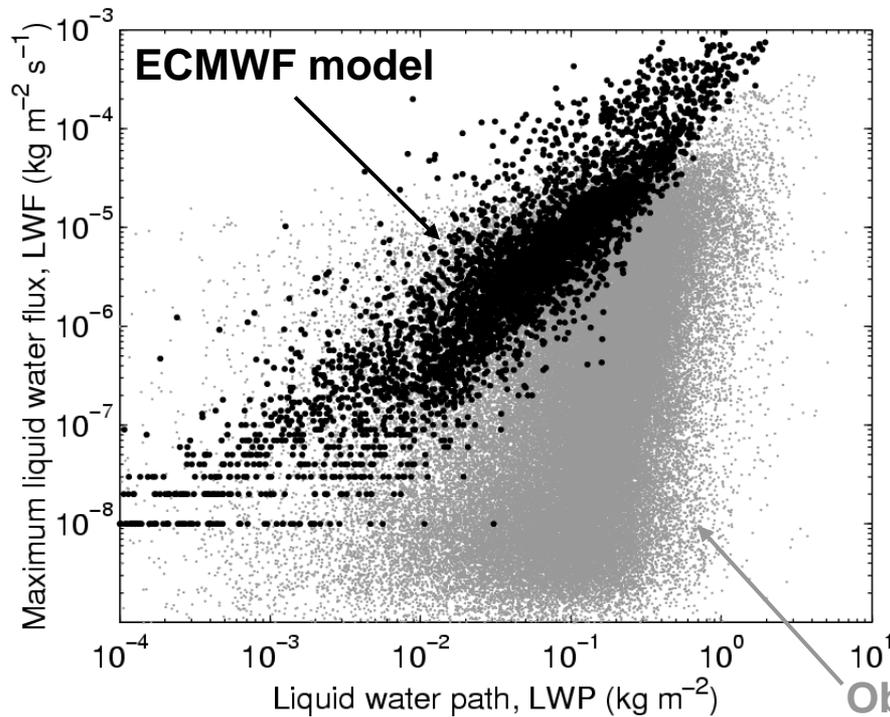
- Met Office uses Marshall-Palmer distribution for all rain
 - Observations show that this tends to overestimate drop size in the lower rain rates
- Most models (e.g. ECMWF) have no explicit raindrop size distribution



From Robin Hogan

1-year comparison with models

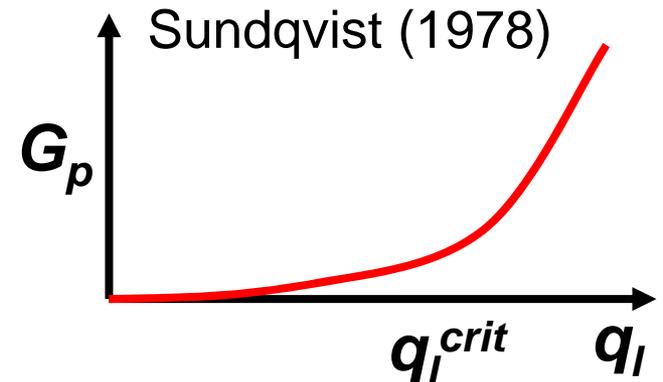
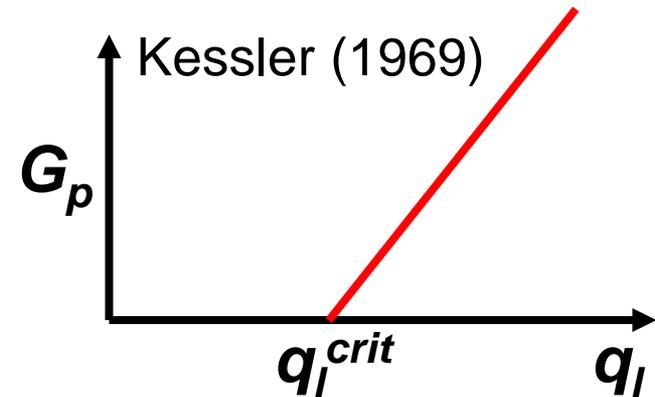
- ECMWF, Met Office and Meteo-France overestimate drizzle rate
 - Problem with auto-conversion and/or accretion rates?
- Larger drops in model fall faster so too many reach surface rather than evaporating: drying effect on boundary layer?



From Ewan O'Connor, Robin Hogan (Reading Univ.)

Warm-rain processes

- Autoconversion – conversion of cloud droplets to raindrops
- Accretion – sweep out of cloud droplets by rain
- Evaporation – below cloud base



Process-validation with CloudSat: Autoconversion/accretion

The observables

Z_e : layer-mean radar reflectivity

$$R_e = \frac{3}{2} \frac{1}{\rho_w} \frac{LWP(\text{AMS-R-E})}{\tau_c(\text{MODIS})}$$

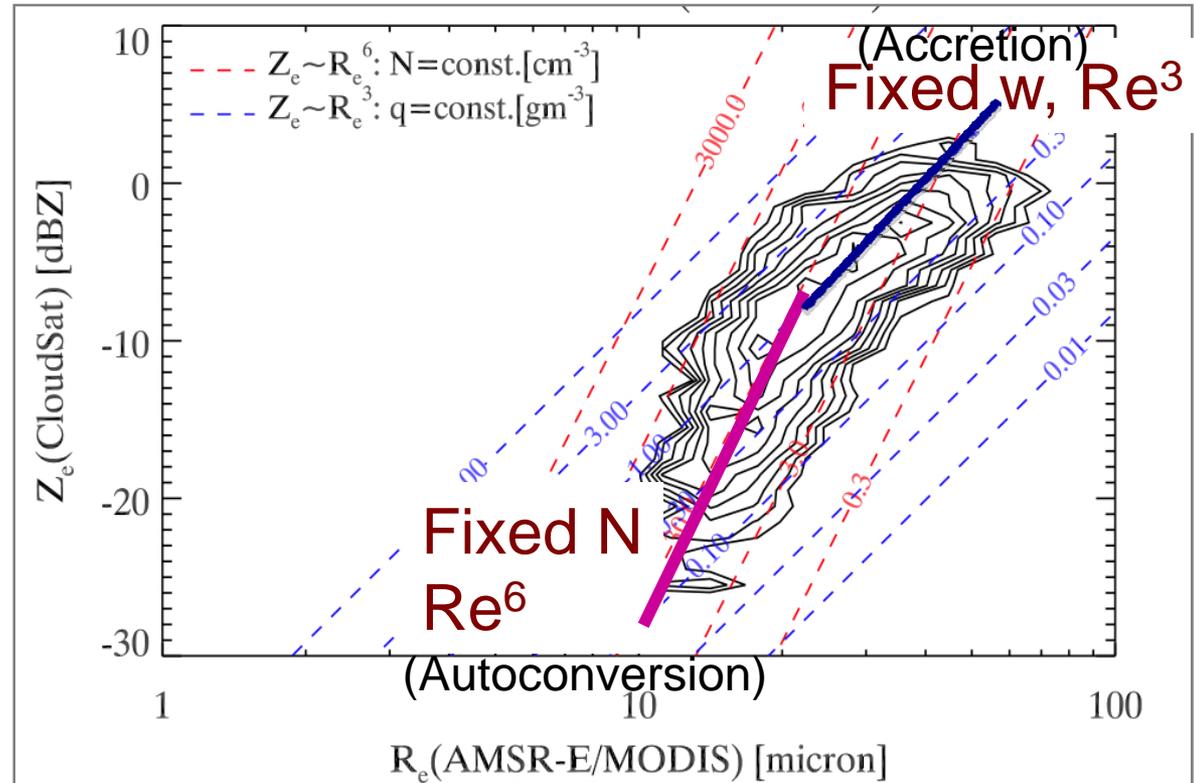
Masunaga et al., 2002a,b
Matsui et al., 2004

The relationships

$$Z_e \approx 64NR_e^6$$

$$Z_e \approx \frac{48}{\pi\rho_w} (w)R_e^3$$

Suzuki and Stephens, 2008



From Graeme Stephens

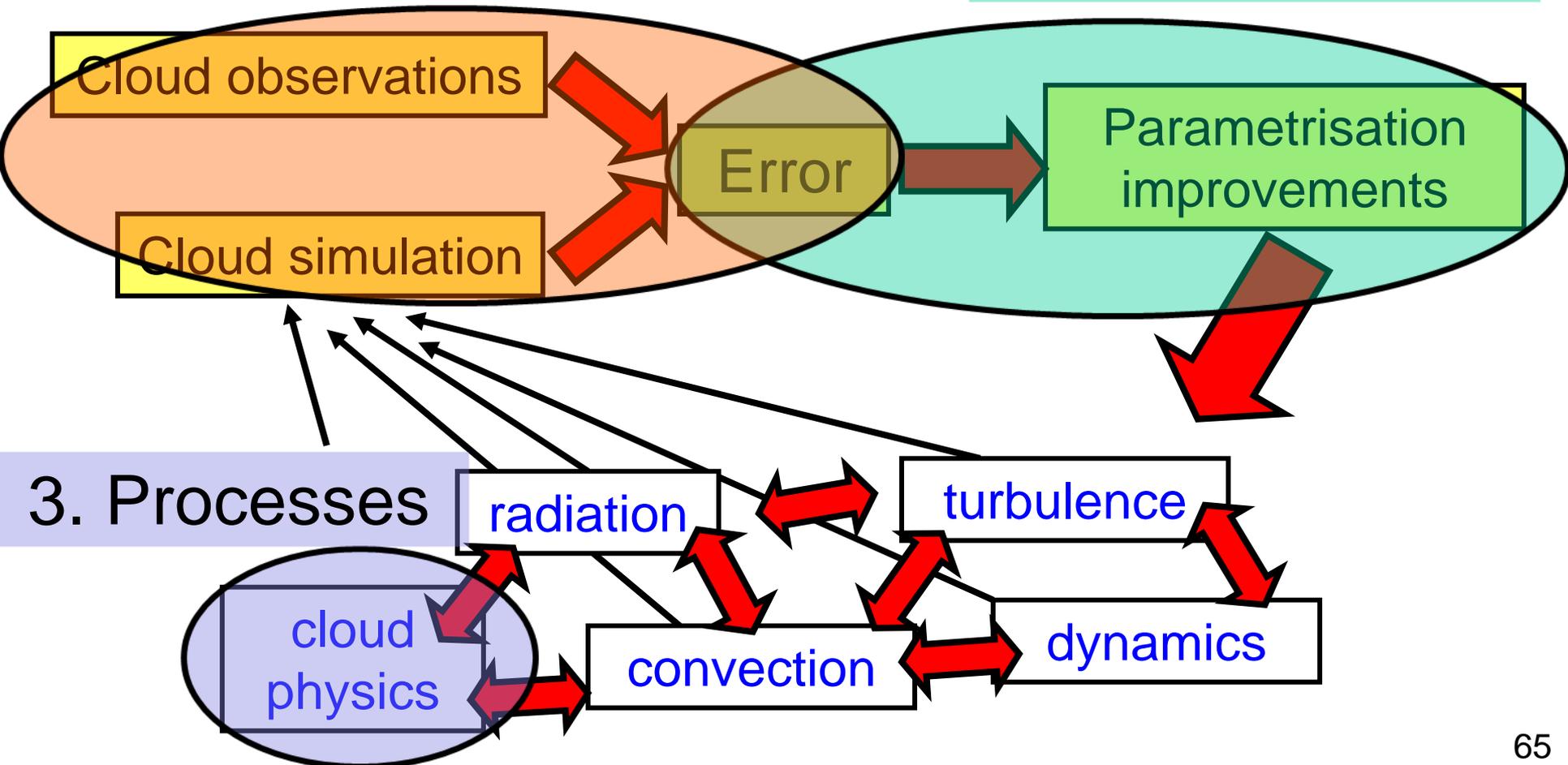


Summary

Cloud Validation: The problems

2. Uncertainty

1. Methodology



1. Methodology

Different approaches to verification (climate statistics, case studies, composites), resolution

2. Comparing model and obs: Uncertainty and limitations

Need to **understand the limitations** of observational data.

Different techniques (model-to-obs, obs-to-model) and a **range of observations** are required to validate and improve cloud parametrizations.

3. Processes

Can observations be used to test model's **physical relationships** between variables and to understand physical processes.