

# SAL - a novel error measure for the verification of high-resolution precipitation forecasts

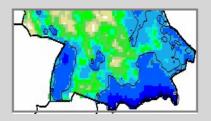
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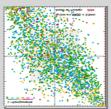
Christoph Frei – Bundesamt für Meteorologie und Klimatologie, MeteoSwiss Zürich

Martin Hagen - Institut für Physik der Atmosphäre, DLR Oberpfaffenhofen









1. February 2007

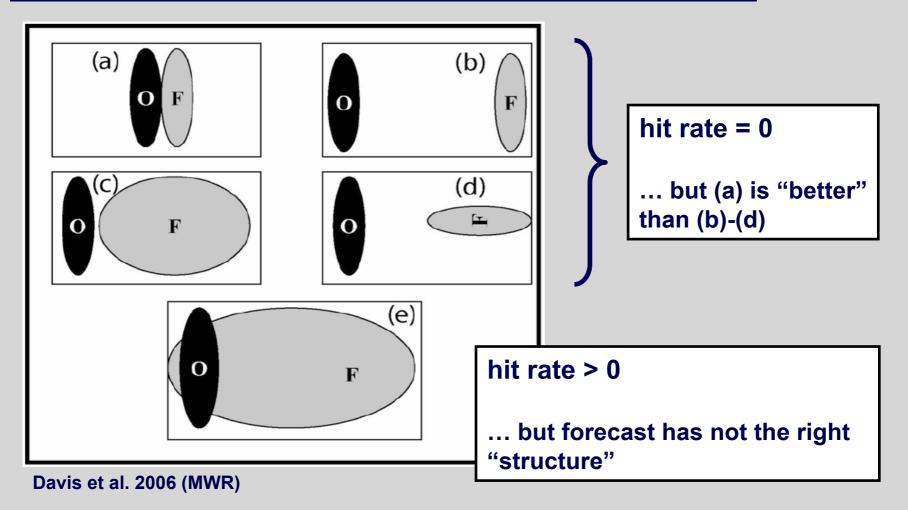
**SAL-examples** 

**SAL-statistics** 

**Conclusions** 



#### Problematic aspects of grid point based error scores



**Marcus Paulat** 

**Christoph Frei** 

**Martin Hagen** 

SAL-examples

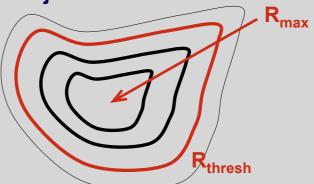
**SAL-statistics** 

**Conclusions** 



#### **S A L – a novel error measure for precipitation forecasts**

- consider precipitation in pre-specified area (e.g. river catchment)
- SAL consists of three independent components
- components address quality of structure (S), amplitude (A) and location (L) of QPF in that area
- according to SAL a forecast is perfect if S = A = L = 0
- S requires the definition of precipitation objects



• but: no attribution between precipitation objects in forecast and observations!

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**Conclusions** 



#### **SAL** - Definition of the components

$$A = (D(R_{mod}) - D(R_{obs})) / 0.5*(D(R_{mod}) + D(R_{obs}))$$

D(...) denotes the area-mean value (e.g. catchment) normalized amplitude error in considered area

$$A \in [-2, ..., 0, ..., +2]$$

$$L = |r(R_{mod}) - r(R_{obs})| / dist_{max}$$

r(...) denotes the centre of gravity of the precipitation field in the area normalized location error in considered area

$$L \in [0, ..., 1]$$

$$S = (V(R_{mod}^*) - V(R_{obs}^*)) / 0.5*(V(R_{mod}^*) + V(R_{obs}^*))$$

V(...) denotes the weighted volume average of all scaled precipitation objects in considered area normalized structure error in considered area

**SAL-examples** 

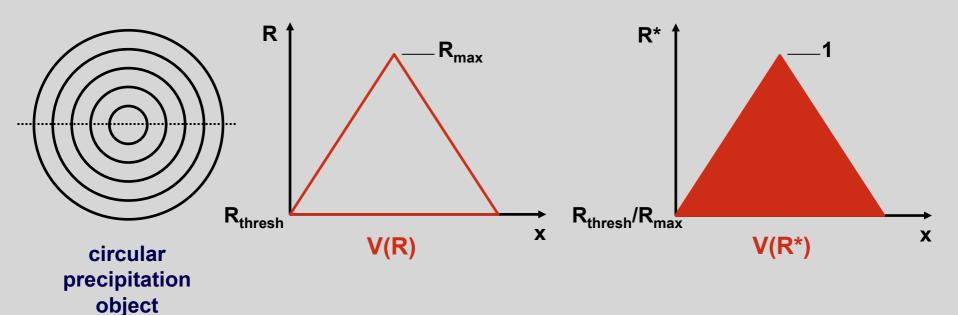
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#### **SAL** - the S-component

scaling for every object:  $R^* = R / R_{max}$ ;  $R^* \in [R_{thresh}/R_{max}, ..., 1]$ 



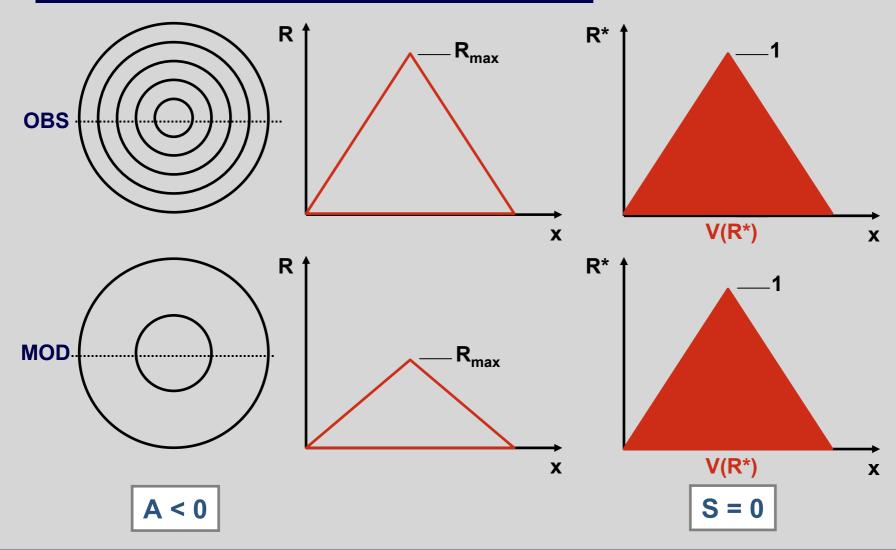
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Conclusions



#### intense vs. weak objects with same size



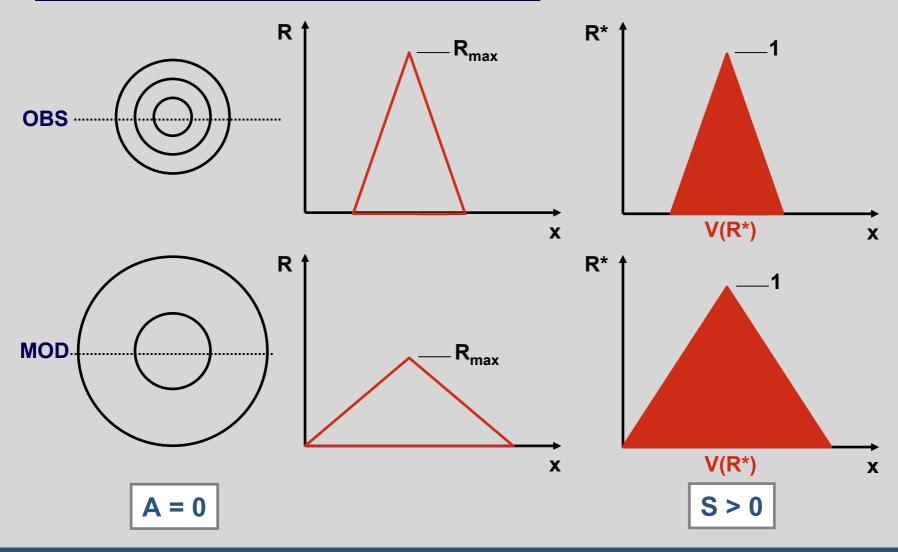
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#### small intense vs. large weak objects



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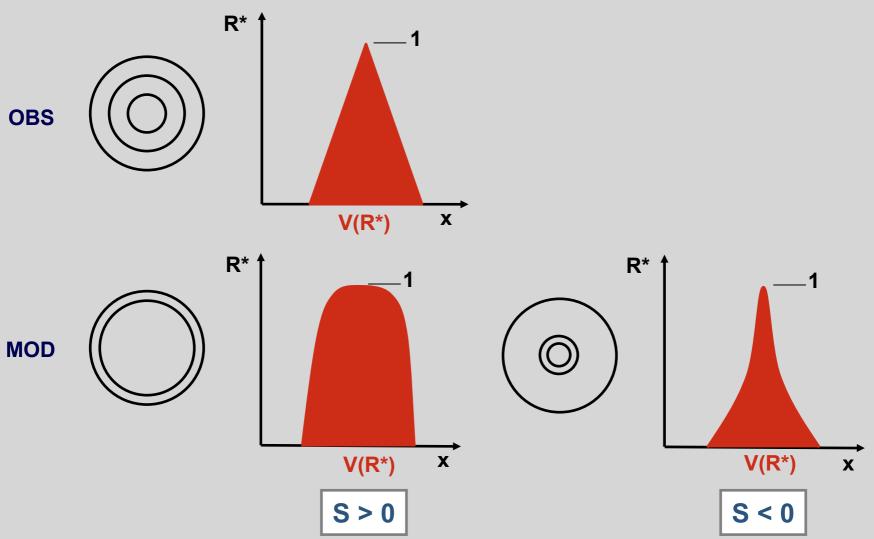
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### peaked vs. flat objects



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GUTENBERG

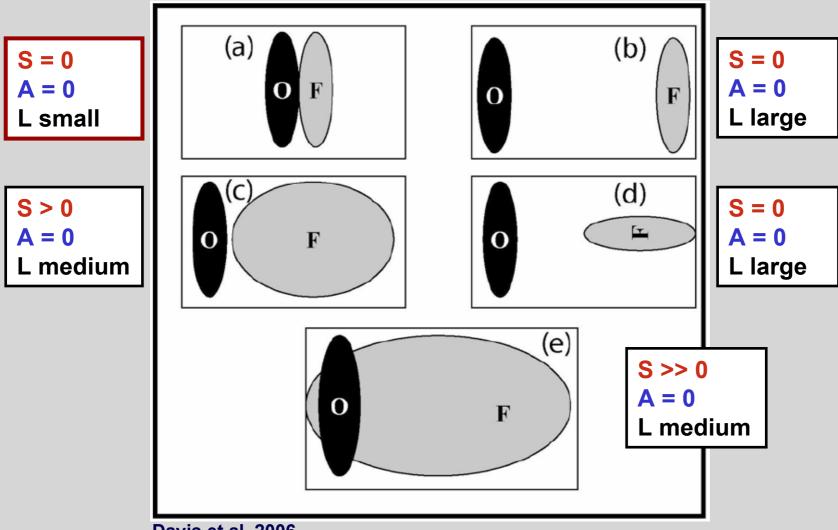
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Davis et al. 2006

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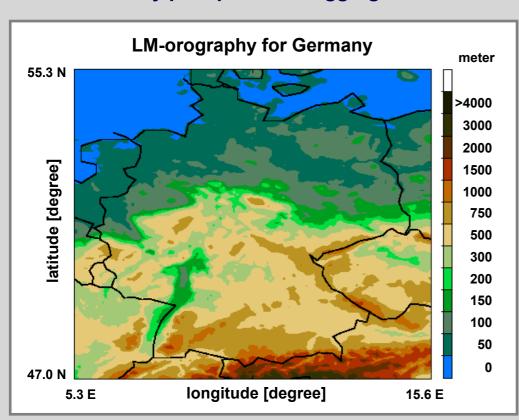
**Conclusions** 



#### precipitation in Germany: MOD and OBS

MOD: aLMo: operational NWP-model from MeteoSwiss: January 2001 – December 2004

OBS: hourly precip from disaggregation of 24h-rain gauges (4000 stations) with radar



#### MOD

- aLMo is non-hydrostatic grid point model
- horizontal resolution: 7 km
- 45 vertical layers
- domain covers W and central Europe
- nested in ECMWF global model
- operational at MeteoSwiss since 1999
- 72h-forecasts started at 00 and 12 UTC
- model output every hour

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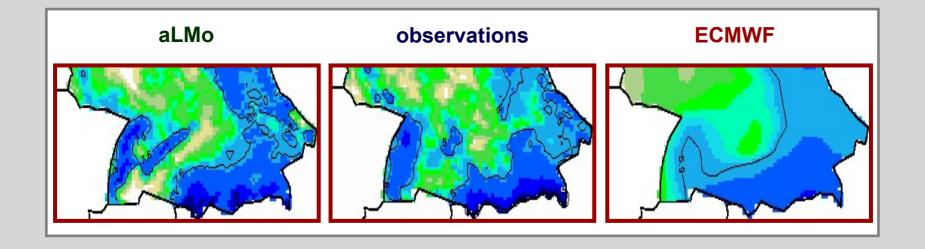
**Conclusions** 



#### a real case example

$$R_{thresh} = R_{max}(area)/15$$

S, 
$$A \in [-2,...,0,...,+2]$$
;  $L \in [0,...,1]$ 



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**SAL-statistics** 

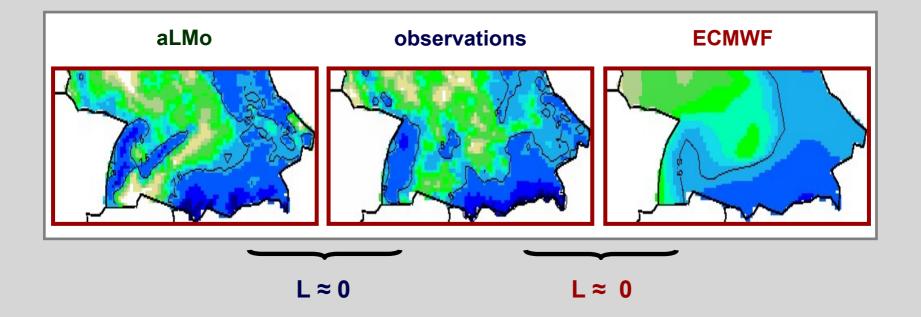
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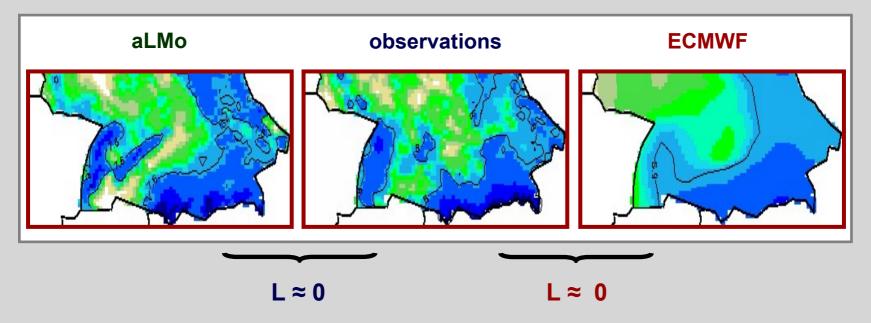
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$$R_{thresh} = R_{max}(area)/15$$

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A ≈ 0

A = -0.14

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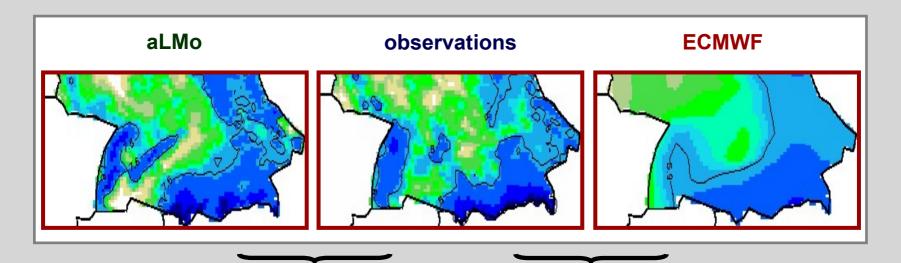
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#### a real case example

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S, 
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L ≈ 0

**L≈ 0** 

A ≈ 0

A = -0.14

S = 0.17

S = 0.63

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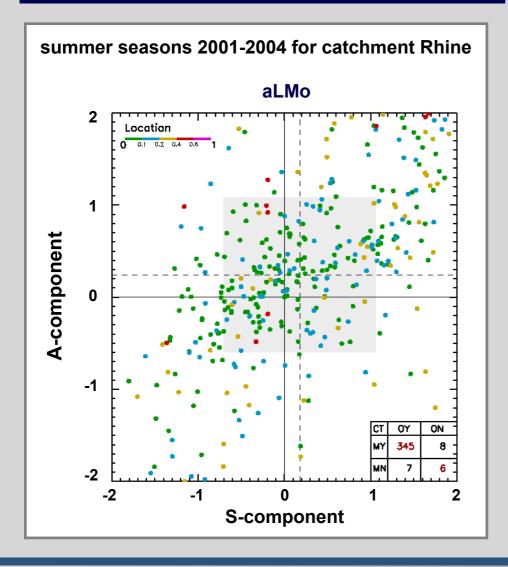
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**Conclusions** 



#### S A L - statistics: 24h accumulated



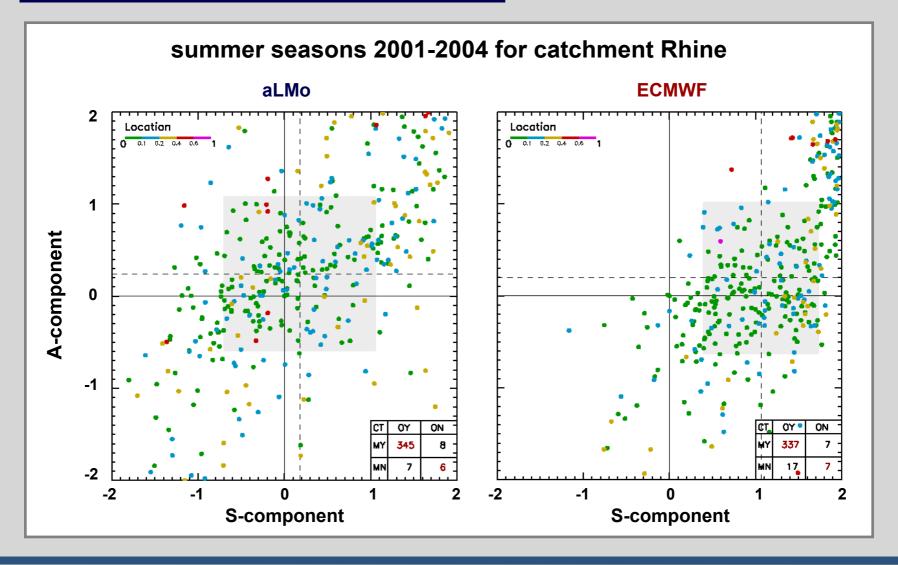
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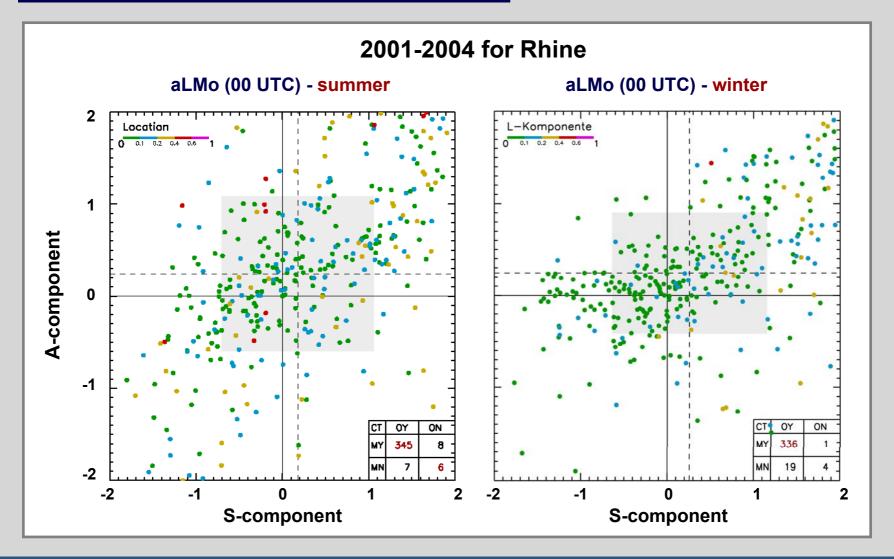
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#### **S A L – statistics: 24h accumulated**



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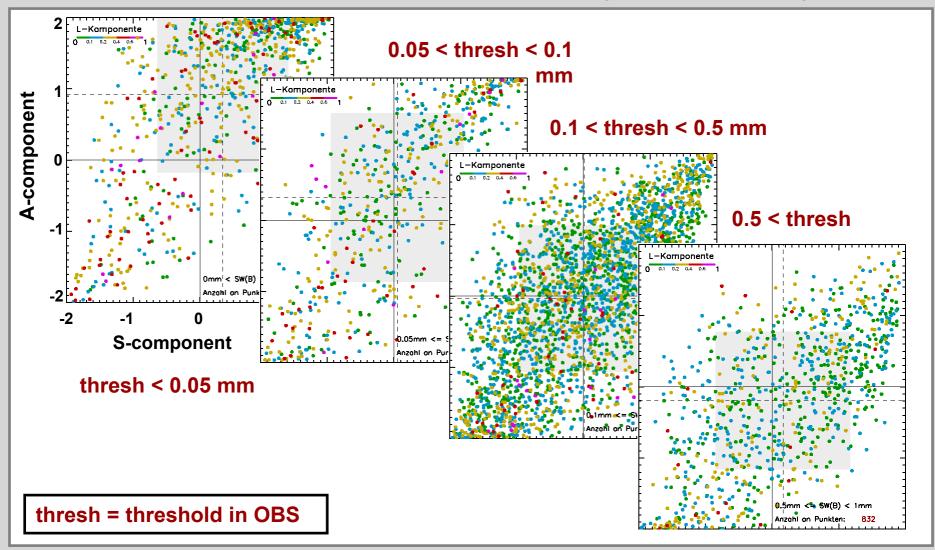
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#### S A L – statistics for aLMo: 1h accumulated (summer, Rhine)



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#### **Conclusions**

• SAL: has 3 independent components to quantify quality of structure, amplitude

and location of QPF

• claim: with SAL verification of key characteristics of precipitation

field in pre-specified area, close to "subjective human judgement"

• advantage: no attribution between objects (difficult for small objects)

• first results: 24h QPF: S is smaller for mesocale model compared to global model

1h QPF from mesoscale model: differences between seasons, intensity

categories

• caveats: non-perfect QPFs can yield S = A = L = 0

no consideration of orientation of objects

currently very simple definition of objects



#### **THANKS**

## DFG - German Research Foundation for funding within the German Priority Progamme on QPF



LM data

Rain gauge precipitation data

**Precipitation climate data** 

Radar data



aLMo data