# Diagnostic evaluation of precipitation forecasts at multiple spatial scales

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### Traditional "Measures"-Based Approach

Consider forecasts and observations of some dichotomous field on a grid:



Critical Success Index CSI=YY/(YY+NY+YN)

Equitable Threat Score

ETS=(YY- $\varepsilon$ )/(YY+NY+YN- $\varepsilon$ ), where  $\varepsilon$ =success due to chance



Non-diagnostic and utra-sensitive to small errors in simulation of localized phenomena!

## **MODE\*: Object-based approach**



\*Method for Object-based Diagnostic Evaluation

## **Object identification**



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#### **Observations and model**

- Forecasts: Weather Research and Forecasting (WRF) model
  - Advanced Research WRF (ARW), 4km grid spacing
  - Forecasts initialized at 0000 UTC from Eta initial conditions
  - 24-h lead
  - 1-h precipitation accumulation
  - 18 April 4 June, 2005; 9 cases selected for extensive study
  - Study Domain: United States, Rocky Mountains (west) to Appalachian Mountains (east)
- Observations: Multi-sensor hourly accumulated precipitation
  - Stage II on 4-km grid



Stage II precipitation estimate; 1 June 2005, 0000 UTC

#### **Object-based example: 1 June 2005**



Radius = 5 grid squares, Threshold = 0.05''

### Issues: Matching and merging

- Evaluation of matching and merging procedures
  - Two-step process merges observed objects separately from forecast objects
  - But 2-step process leads to non-optimal matches between forecast and observed objects
  - Double-threshold, single step procedure appears to be most robust, provide most reasonable results





#### **Issues: Object identification and scale**

- How should object identification parameters (radius, threshold) be selected?
- Alternative question: What scale(s) are appropriate and meaningful?
- **Goal:** Examine impacts of scale on object and matching properties



#### Scale features



Both are characterized by sharp features, complexity. High threshold results in many small objects, fine-scaled features

#### Scale features



Large radius creates large blobby objects. Medium parameters focus on more intense rain areas. Verification "Quilts"

Forecast
performance
attributes as
a function of
spatial scale

 Similar to charts developed by Casati, Marzban, Ebert

Single objects: Vedian Forecast + Observed Object Area Convolution threshold (in/100) 5 10 15 20 25 30 25 8000 20 6000 4000 2000 0 5 15 10 20 30 25 Convolution radius (grid sq)

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## Percent of single objects matched



- Region with large radius and large threshold has low rate of matches, except for most extreme values
- Region with moderate values of radius and low threshold (around 5) is the scale with best potential for object matching

## Measure of matching strength



- Region with moderate values of radius and low threshold (around 5) is the scale with best potential for object matching
- A measure of skill?

## **Critical success index**



- Highly dependent on radius
  - Largest values for smooth objects
  - Less dependence on threshold

#### Conclusions

- Matching capabilities are not surprisingly – highly dependent on scale of objects
- Verification "quilts" help define scales with potential skill
- The appropriate question should be Which scales are reasonable to
  - Examine in the context of users' applications?
  - Provide a meaningful evaluation of forecast skill (and other attributes)?

Thus – it is more appropriate to examine objects associated with several representative sets of parameters, rather than focusing on a single set.